

SICK **RFU6xx Function Block**

Block Version V2.X

SICK RFU6XX PN CP Function Block for
Siemens Step7 Controllers



Version history

| Version | Date | Description |
|---------|------------|--|
| V2.0 | 11/29/2012 | Initial version |
| V2.0 | 11/12/2013 | Documentation revised (antenna selection, number of retries, error code W#16#001B) |
| V2.1 | 19/07/2016 | Support multi-instance offsets > 4095 |

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About this document

Please read this chapter carefully before you begin working with these operating instructions and the SICK RFU6xx function block.

1.1 Purpose of this document

These operating instructions describe how to use the SICK RFU6XX PN CP function block. They are intended to guide technical personnel working for the machine manufacturer/operator through the processes of configuring and commissioning the function block.

1.2 Target group

These operating instructions are aimed at specialist personnel such as technicians and engineers.

2 General information

The "SICK RFU6XX PN CP" function block is used to facilitate communication between a SIMATIC controller and a SICK RFU6xx RFID sensor.

The following figure shows how the function block is represented in the function block diagram (FBD) view.

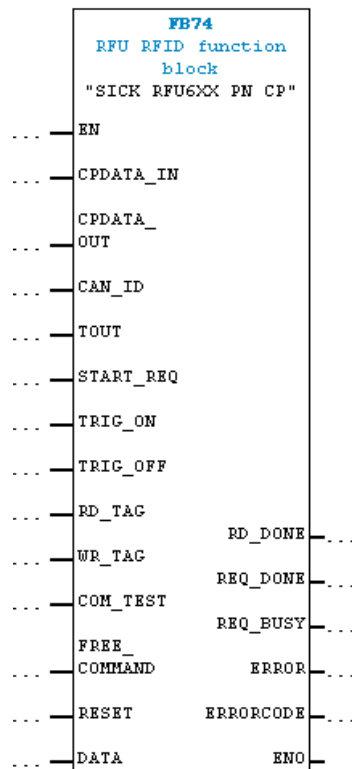


Figure 1: SICK RFU6XX PN CP function block

Block functions:

- Send a trigger command (CoLaⁱ command) via the PLC
- Receive reading results (defined in SOPAS-ETⁱⁱ output format)
- Read and write transponder content
- Execute a communication test
- Communicate via freely selectable CoLa commands (CoLa-A protocol)
- Address devices that communicate with each other via CAN bus

ⁱ The command language (CoLa) is a protocol internal to SICK for communicating with SOPAS devices.

ⁱⁱ SOPAS-ET is an engineering tool for configuring SICK sensors.

3 Hardware configuration

3.1 Supported PLC controllers

The function block may only be operated with Simatic S7-300 controllers. Only controllers that feature the relevant fieldbus interface are supported. Communication via a communication processor is not supported by this block.

3.2 Supported fieldbus gateways/sensors

The SICK sensor communicates with the controller via a fieldbus (PROFIBUS/PROFINET). If the sensor does not support the PROFIBUS/PROFINET fieldbuses, gateway modules can be used.

The following gateways are supported by the function block:

- CDM 425 (PROFINET), firmware version V3.31 or higher
- CDF 600 (PROFIBUS), firmware version V1.15 or higher
- CDM 420 including CMF400 PROFIBUS module, firmware version V1.100 or higher

Required RFU firmware version:

- RFU6xx, firmware version V1.30 or higher

3.3 Configuration in Step7

The RFU must be configured properly in the Step7 hardware configuration before the function block can be used. In order for this to happen, the corresponding generic station description (GSD file) must be imported into the Step7 hardware library.

The function block is specially designed for handshake mode. Only use HS modules with lengths of between 8 and 128 bytes. The addresses used can be configured inside or outside of the I/O area. Addresses must not be assigned to I/O areas that have a partial process image and OB6x connection (synchronous interrupts) assigned to them.

3.3.1 Hardware configuration

Figure 2 shows a sample configuration for the RFU.

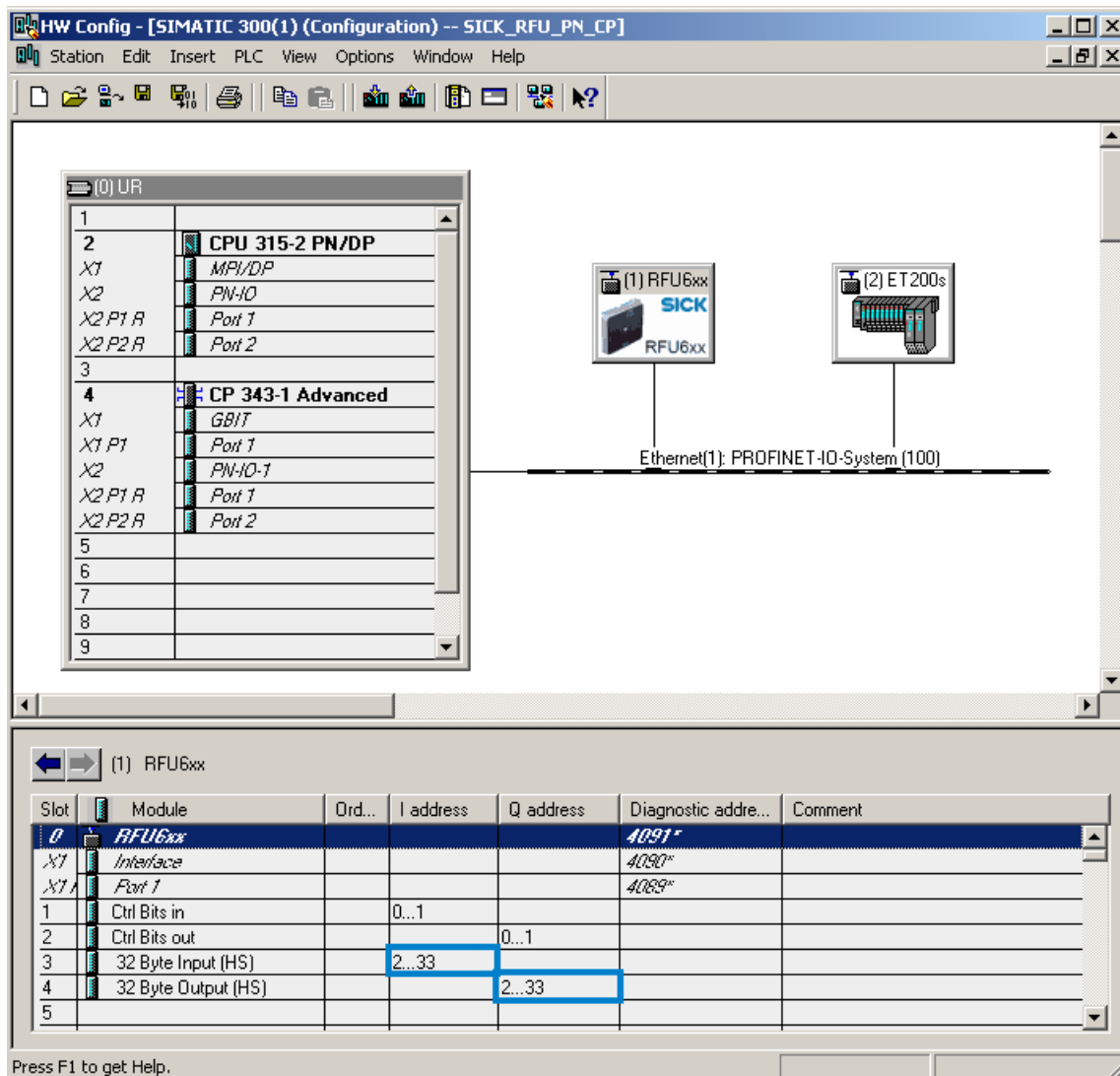


Figure 2: Step7 hardware configuration

Please note that the I/O addresses of the CP module are not identical to the I/O addresses of the CPU because the CP module has its own address range. Therefore, direct communication with the PROFINET station is not possible from the S7 program.

The entire I/O area of the CP module (in this case, the SICK CDM425 and Siemens ET200S stations) is accessed via the FC11 (PNIO_SEND) and FC12 (PNIO_RECV) functions. These functions result in a consistent I/O image of all the devices connected to the CP module.

In order to utilize the Siemens FCs, the I/O areas of the connected I/O devices must be configured in a continuous sequence, starting with address 0.

3.3.2 Access to the I/O area

The I/O area of the connected stations should be read or written to during every PLC cycle. In this example, the FC11/FC12 functions are called cyclically in OB1.

Function FC12 (PNIO_RECV) must be configured as follows:

CPLADDR: Hardware address of the configured CP module (see Figure 4)
 MODE: 0 = IO controller mode
 LEN: Byte length of all input data starting from address 0
 RFU ctrl bits in (0..1) = 2 bytes
 RFU input data (2..33) = 32 bytes
 ET200s (34..37) = 4 bytes
 Total = 38 bytes
 RECV: Pointer referencing the data area (DB) where the incoming data is to be stored
 IOPS: Pointer referencing the data area (DB) where the IOPS (IO Producer Status) is to be stored. The data area for the IOPS data must have a length of LEN/8 (38/8 = 5 bytes when rounded up).

Network 1: RECEIVE DATA

Receive the whole CP-PN data via FC12. In this case only a SICK Reader was configured in the HW-Config.

CPLADDR: CP-Module address from the hardware configuration

MODE: 0= IO-Controller mode

LEN: Length of the whole CP-Data area to be transferred in bytes (Beginning at adresse 0 !!!)

RECV: Data area where the received CP-Data should be stored

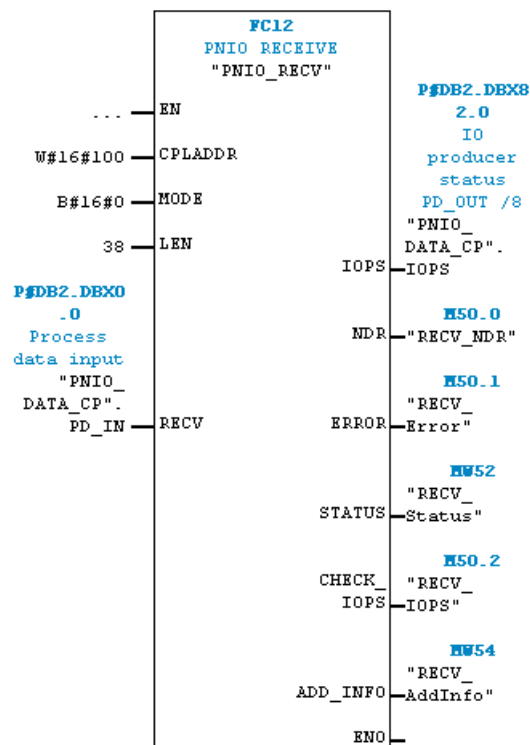


Figure 3: FC12 (PNIO_RECV) call in OB1

Figure 4 shows you where to find the hardware address of the configured CP module in the Simatic hardware configuration.

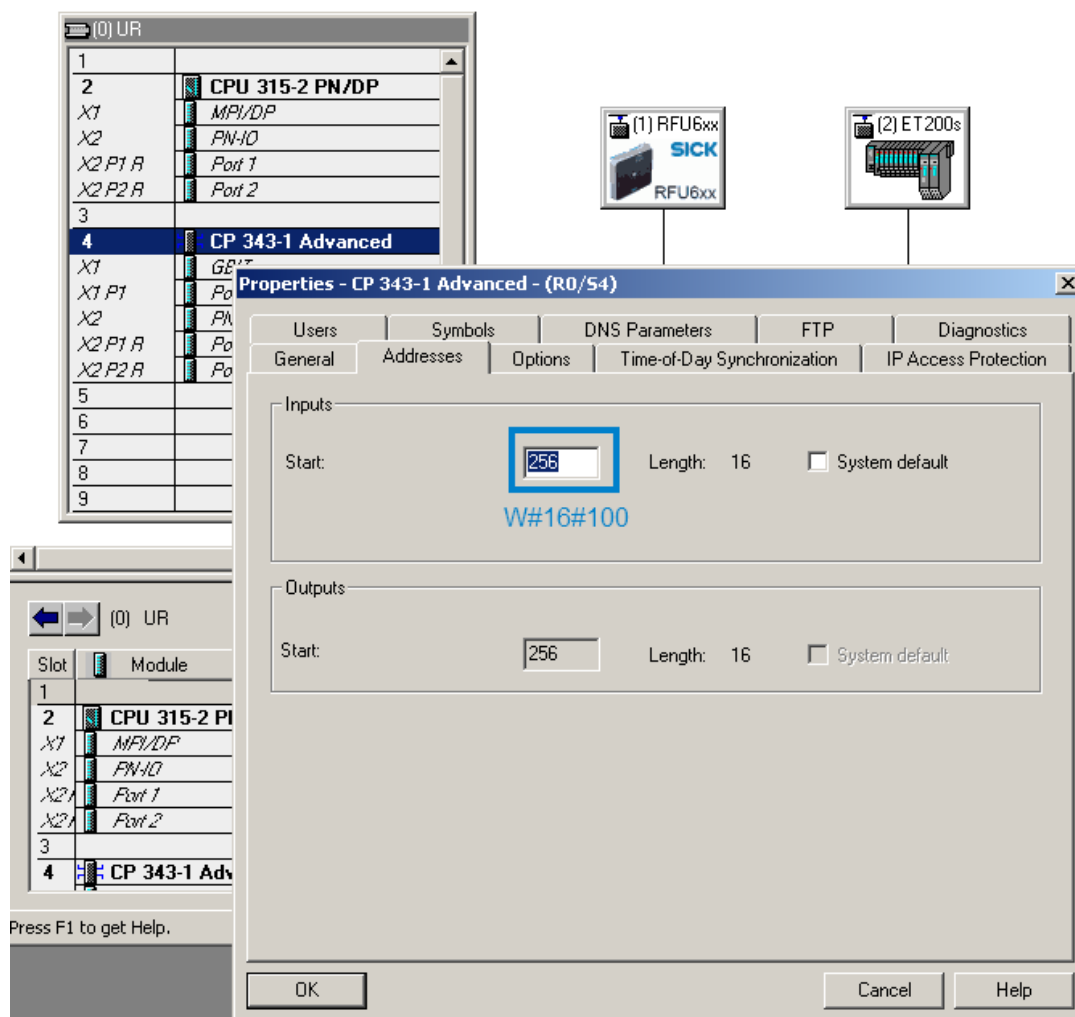


Figure 4: Hardware address of the configured CP module

Function FC11 (PNIO_SEND) must be configured as follows:

CPLADDR: Hardware address of the configured CP module (see Figure 4)
 MODE: 0 = IO controller mode
 LEN: Byte length of all input data starting from address 0
 RFU ctrl bits out (0..1) = 2 bytes
 RFU output data (2..33) = 32 bytes
 ET200s (34..37) = 4 bytes
 Total = 38 bytes
 SEND: Pointer referencing the data area (DB) used to store the output data that is to be written
 IOCS: Pointer referencing the data area (DB) where the IOCS (IO Consumer Status) is to be stored. The data area for the IOCS data must have a length of LEN/8 (38/8 = 5 bytes when rounded up).

Network 2 : SEND DATA

Send the whole data CP-PN data via FC11. In this case only a SICK Reader was configured in the HW-Config.

CPLADDR: CP-Module address from the hardware configuration
 MODE: 0= IO-Controller mode
 LEN: Length of the whole CP-Data area to be send in bytes (Beginning at adresse 0 !!!)
 SEND: Data which a send to the CP-Module

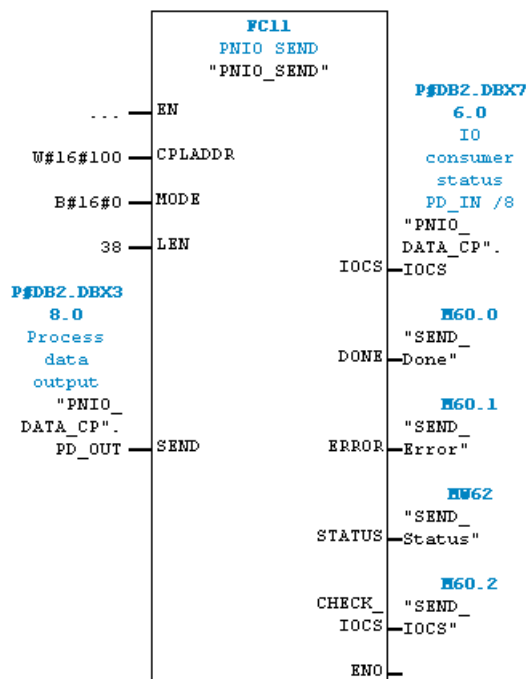


Figure 5: FC11 (PNIO_SEND) call in OB1

4 Block description

The function block is an asynchronous FB, i.e., processing encompasses several function block calls. This means that the block must be called in the user program on a cyclical basis.

The RFU block encapsulates the "SICK CCOM PN CP" (FB14) function block, which facilitates communication between the PLC and the sensor. FC10 (SICK COLA ACCESS) is used internally to interpret CoLa telegrams.

4.1 Block specifications

| | |
|-----------------------------------|---|
| Block number: | FB74 |
| Block name: | SICK RFU6XX PN CP |
| Version: | 2.1 |
| Blocks called: | SFC20 (BLKMOV) SFB4 (TON) FB14 (SICK CCOM PN CP) FC10 (SICK COLA ACCESS) DB74 (SICK RFU DATA) |
| Data blocks used: | |
| Block call: | Cyclical |
| Flags used: | None |
| Counters used: | None |
| Registers used: | AR1, AR2 (for multi-instance calls) |
| Capable of multi-instancing: | Yes |
| Language used for block creation: | Step7 STL |
| Step7 version: | Simatic Step7 V5.5 |

The system functions (SFCs) used in the function block must exist on the controller that is being used.

If block numbers are changed, then the corresponding calls in the SICK RFU6XX PN CP block must be updated accordingly.

4.2 Operating principle

The following communication parameters must be specified before the RFU block can be used:

CPDATA_IN: Pointer referencing the input data of the sensor/gateway. The input data first has to be fetched using function FC12 (PNIO_RECV).

CPDATA_OUT: Pointer referencing the output data of the sensor/gateway. The output data has to be transmitted to the device using function FC11 (PNIO_SEND).

DATA: The data block (DB74) that accompanies the function block contains input and output parameters for the supported block functions. The data block must be transferred to the "DATA" input parameter of the function block.

Executable block functions:

- Trigger on → Uses a CoLa command to open the device reading gate
- Trigger off → Uses a CoLa command to close the device reading gate
- Read tag → Reads out the transponder data
- Write tag → Writes transponder data
- Communication test → Checks whether the device can be contacted by sending command "sRIO"
- Free command → Executes a freely selectable CoLa command

To execute a block function (TRIG_ON, RD_TAG, etc.), the desired function must first be selected. Only one function can be executed at a time. The START_REQ parameter must be triggered with a rising edge (signal change from logical zero to one) in order for the function to be executed. Until a valid device response is received, the REQ_BUSY parameter signals that a response is still pending.

If the block's REQ_DONE output parameter = TRUE, it means that the function has been successfully completed. If data was requested from the device during this function (e.g., RD_TAG), this data is copied to the relevant data area of the accompanying user data block (DATA).

Data sent via a trigger command (TRIG_ON, TRIG_OFF) or directly by the device (e.g., direct trigger via a photoelectric sensor) is stored in the data block (ReadingResult.arrResult). For one PLC cycle, the RD_DONE output parameter indicates that new data has been received. The data sent by the device can be changed or adapted in SOPAS output format (see chapter 4.5.3).

4.3 Response to errors

If the function block has an incorrect input value or if the input has been connected incorrectly, an error bit (ERROR) is set and an error code (ERRORCODE) is output. In this case, no further processing is carried out. The diagnostic parameters (ERROR, ERRORCODE) of the function block retain their values until a new command is started.

The RESET bit can be used to reset communication between the sensor and PLC. The reset command is executed as soon as the RESET bit is selected and the START_REQ bit is triggered with a rising edge (signal change from zero to one). The REQ_BUSY bit signals that the command is being processed. Once the reset routine is completed, the REQ_DONE bit is set.

The following functions are executed during a reset routine:

- Reset of Confirmed Messaging Protocol counter (device communication)
- All error messages reset

4.4 Timing

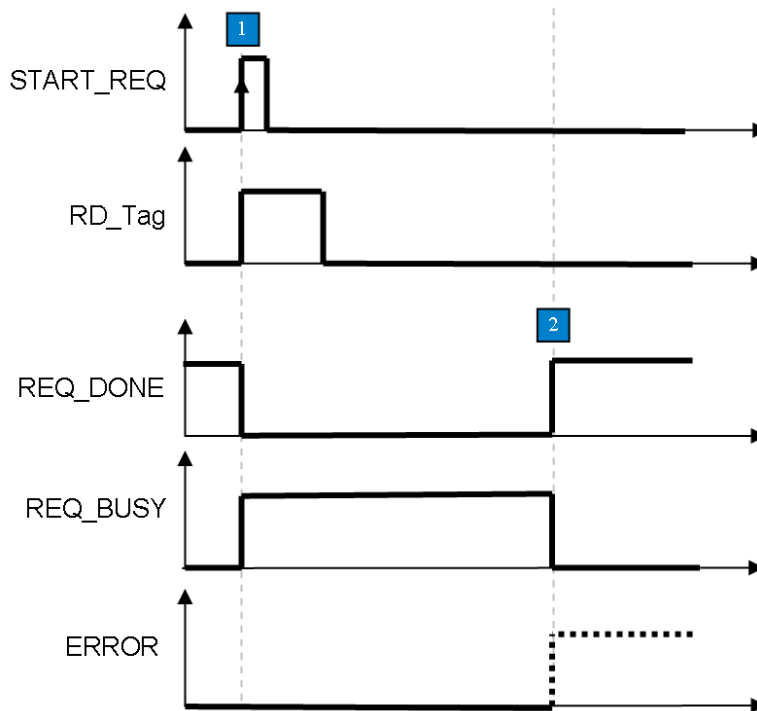


Figure 6: Timing diagram

1: Request triggered by rising edge at START_REQ

The desired function (RD_TAG in this case) must be selected at the same time/in advance. Only one function may be selected at once; otherwise, the function will be aborted with "ERROR".

2: Once all commands have been sent and all responses received, the function is terminated with "REQ_DONE". If an error occurred during the function, the function is terminated with "ERROR". "ERRORCODE" contains information on the error that occurred if the function is aborted with "ERROR".

4.5 Value transfer

The supplied data block "SICK RFU DATA" (DB74) contains input and output parameters for all supported block functions. The data block can be renamed according to the user program. The data structure has a fixed definition and may not be modified except for the last entry (ReadingResult.arrResult) (see chapter 4.6: Receiving reading results > 200 bytes).

| Address | Name | Type | Initial value | Comment |
|---------|----------------|---------------|---------------|--|
| 0.0 | | STRUCT | | |
| +0.0 | Mode | STRUCT | | -- MODE -- |
| +0.0 | bMode | BOOL | FALSE | 1: Use a fixed UII 0: Use the UII of the transponder in the field (IN) |
| +2.0 | iUIILength | INT | 0 | Byte length of UII (IN/OUT) |
| +4.0 | arrPC | ARRAY[1..4] | | PC word (OUT) |
| +1.0 | | CHAR | | |
| +8.0 | arrUII | ARRAY[1..60] | | Transponder UII (IN/OUT) |
| +1.0 | | CHAR | | |
| +68.0 | arrRSSI | ARRAY[1..4] | 0 | RSSI values of the 4 antennas (Internal/External) |
| +2.0 | | INT | | |
| +76.0 | | END_STRUCT | | |
| +76.0 | ReadTag | STRUCT | | --- READ TAG --- |
| +0.0 | nBank | BYTE | B#16#0 | Bank selection (0=RESERVED 1=UII/EPC 2=TID 3=USER) (IN) |
| +2.0 | nStartWord | WORD | W#16#0 | First word to read, starting from 0 (IN) |
| +4.0 | nWordCount | BYTE | B#16#0 | Number of words to read (IN) |
| +5.0 | nRetry | BYTE | B#16#0 | Number of retries, until failure is reported (IN) |
| +6.0 | nAntenna | BYTE | B#16#0 | Antenna mask for reading (1= Internal,2,4,8) (IN) |
| +8.0 | iDataLength | INT | 0 | Byte length of the reading data (OUT) |
| +10.0 | arrData | ARRAY[1..64] | | Read data (OUT) |
| +1.0 | | BYTE | | |
| +74.0 | | END_STRUCT | | |
| +150.0 | WriteTag | STRUCT | | --- WRITE TAG --- |
| +0.0 | nBank | BYTE | B#16#0 | Bank selection (0=RESERVED 1=UII / EPC 2=TID 3=USER) (IN) |
| +2.0 | nStartWord | WORD | W#16#0 | First word to write, starting from 0 (IN) |
| +4.0 | nWordCount | BYTE | B#16#0 | Number of words to write (IN) |
| +5.0 | nRetry | BYTE | B#16#0 | Number of retries, until failure is reported (IN) |
| +6.0 | nAntenna | BYTE | B#16#0 | Antenna mask for writing (1= Internal,2,4,8) (IN) |
| +8.0 | arrData | ARRAY[1..64] | | Data to be written (IN) |
| +1.0 | | BYTE | | |
| +72.0 | | END_STRUCT | | |
| +222.0 | FreeCommand | STRUCT | | -- FREE COMMAND -- |
| +0.0 | iCommandLength | INT | 0 | Length of the free command (IN) |
| +2.0 | arrCommand | ARRAY[1..100] | | Command (SICK CoLA-A protocol without [STX]/[ETX] framing) (IN) |
| +1.0 | | CHAR | | |
| +102.0 | iResultLength | INT | 0 | Byte length of the free command result (OUT) |
| +104.0 | arrResult | ARRAY[1..100] | | Result (SICK CoLA-A protocol) (OUT) |
| +1.0 | | CHAR | | |
| +204.0 | | END_STRUCT | | |
| +426.0 | ReadingResult | STRUCT | | -- READING RESULT -- |
| +0.0 | nCounter | BYTE | B#16#0 | This counter is incremented if a new reading result has arrived (OUT) |
| +2.0 | iLength | INT | 0 | Byte length of the reading result (OUT) |
| +4.0 | arrResult | ARRAY[1..200] | | Reading result data (OUT) |
| +1.0 | | CHAR | | |
| +204.0 | | END_STRUCT | | |
| +630.0 | | END_STRUCT | | |

Figure 7: Structure of the SICK RFU DATA user data DB

4.5.1 Mode

The RFU can only communicate with a single transponder at any one time. For this reason, read and write commands are always addressed. The function block uses the UII (Unique Item Identifier) to identify the transponder.

The function block supports two different modes in order to determine which transponder UII is to be communicated with:

Mode 1: The system always communicates with the transponder which is currently in the read field. This mode can only be used when precisely one tag is located within the field. The RFU must be specially configured in SOPAS-ET (see chapters 4.5.2 and 4.5.3) for this mode.

Mode 2: A user-defined transponder UII is used for the purpose of communication.

| Parameter | Declaration | Data type | Description |
|-----------------|--------------|-----------------------------|--|
| Mode.bMode | Input | BOOL | Addressing mode FALSE: Mode 1 active TRUE: Mode 2 active |
| Mode.iUIILength | Input/Output | INT | Length of UII used 0 = Unaddressed read/write 1..60 = Length of UII defined in array "Mode.arrUII" <i>The UII is determined automatically in Mode 1.</i> |
| Mode.arrPC | Output | ARRAY [1..4] OF CHAR | PC word of the transponder used <i>(Mode 1 only)</i> |
| Mode.arrUII | Input/Output | ARRAY [1..60] OF CHAR | Transponder identifier (UII) <i>The UII is determined automatically in Mode 1.</i> |
| Mode.arrRSSI | Output | ARRAY [1..4] OF INT | RSSI value (reception strength) of the transponder used <i>(Mode 1 only)</i> [1] = RSSI value from antenna 1 (internal) [2] = RSSI value from antenna 2 (external) [3] = RSSI value from antenna 3 (external) [4] = RSSI value from antenna 4 (external) |

Table 1: Mode parameters

4.5.2 Mode 1: SOPAS-ET object trigger control

The object trigger control settings define when the reading gate is opened or closed. The sensor sends a reading result to the PLC after each reading gate. The function block uses this mechanism in order to read out the UII, the PC word, and the RSSI values from the transponder that is being addressed.

The SOPAS-ET settings under menu item *Parameter* → *Reading Configuration* → *Object Trigger Control* must be defined so that the trigger window is opened via a SOPAS command and closed again when a "Good Read" result is received or after a defined period of time (1000 ms in this case).

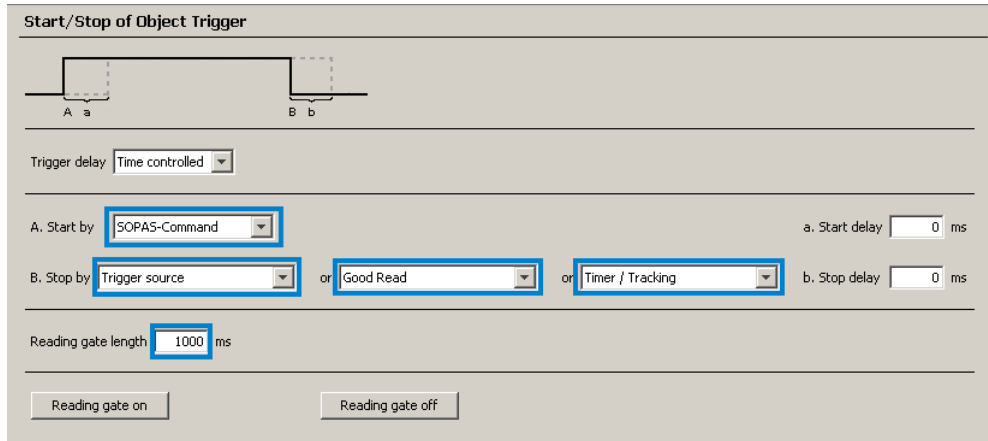


Figure 8: Trigger setting (SOPAS)

4.5.3 Mode 1: SOPAS-ET output format

The output format defines the content of the telegram that is sent by the device as soon as the trigger window is closed. This telegram is evaluated by the PLC and the information that is required for the address-specific reading/writing of tag data is read. In order for the function block to be used in Mode 1, the SOPAS output format must be structured as shown in Figure 9.

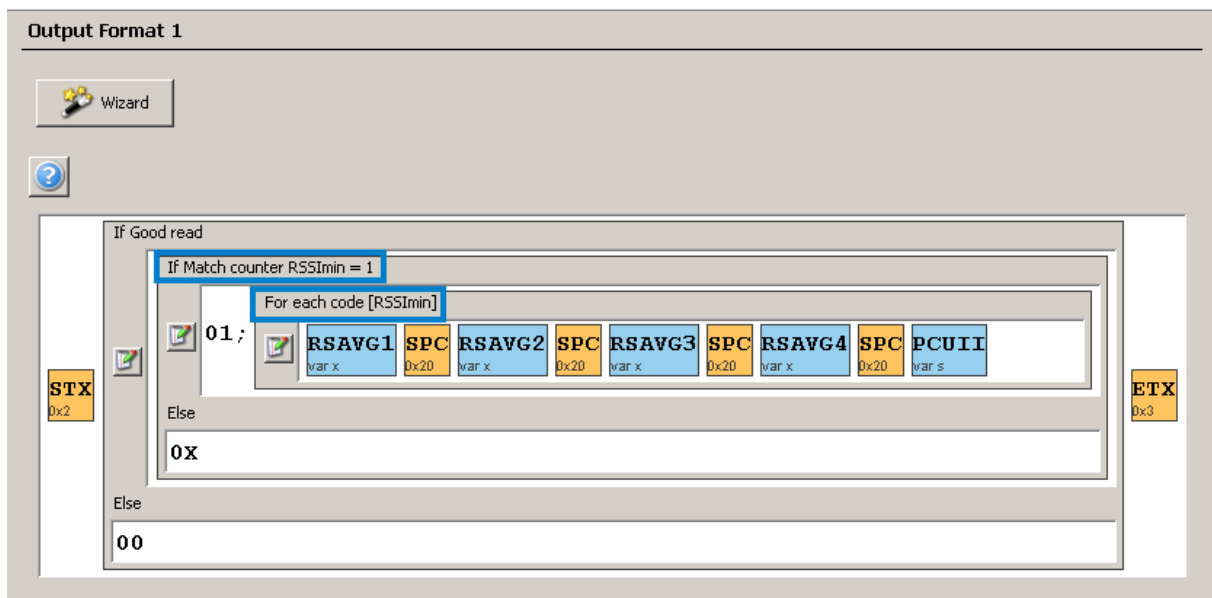


Figure 9: SOPAS output format

Please ensure that the format of blocks "RSAVG1...4" is set to hexadecimal (double-click the respective block). The "PCUII" block may not be changed.

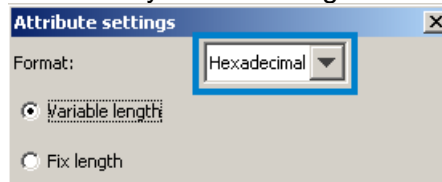


Figure 10: Settings for RSSI blocks (RSAVG1...4)

Depending on the number of tags located in the receiving range of the RFU and the configured RSSI threshold, the following telegrams are sent (in ASCII format):

Case 1: One tag in field:

[STX]01;[RSSI Antenna 1] [RSSI Antenna 2] [RSSI Antenna 3] [RSSI Antenna 4]
[PC+UII][ETX]

Case 2: More than one tag in field:

[STX]0X[ETX]

Case 3: No tags in field:

[STX]00[ETX]

4.5.4 Read tag

The read tag function is used to read a defined data area of a tag. This function can only ever be applied to one tag. The selected mode determines which transponder the system communicates with (see chapter 4.5.1).

The following parameters must be set in the "ReadTag" structure before an RFID tag is read.

| Parameter | Declaration | Data type | Description |
|--------------------|-------------|-----------|--|
| ReadTag.nBank | Input | BYTE | Selection of the memory bank from which data is to be read 0 = reserved 1 = UII/EPC 2 = TID 3 = user memory |
| ReadTag.nStartWord | Input | WORD | First word (16 bits) to be read |
| ReadTag.nWordCount | Input | BYTE | Number of words (16 bits) to be read Valid range: [1..32] |
| ReadTag.nRetry | Input | BYTE | Number of read attempts to be carried out Valid range: LoNibble (retries on one channel) B#16#[0..7] HiNibble (retries on different channels) B#16#[0..5] Example: ReadTag.iRetry = B#16#32 executes 2 retries per channel (3 <i>tries per channel</i>) with 3 channel changes (4 <i>channels</i>), i.e., a total of 3x4 = 12 attempts . |

| Parameter | Declaration | Data type | Description | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------------|-------------|-----------------------|--|-------|----|----|----|----|---|--|--|--|---|---|--|--|---|--|---|--|---|--|--|---|---|--|--|--|
| ReadTag.nAntenna | Input | BYTE | <p>Antenna selection for current read command. Only one antenna can be selected per command.</p> <p>A1 = antenna 1 (internal/external, depending on device type) A2 = antenna 2 (external) A3 = antenna 3 (external) A4 = antenna 4 (external)</p> <table><tr><th>Value</th><th>A4</th><th>A3</th><th>A2</th><th>A1</th></tr><tr><td>1</td><td></td><td></td><td></td><td>X</td></tr><tr><td>2</td><td></td><td></td><td>X</td><td></td></tr><tr><td>4</td><td></td><td>X</td><td></td><td></td></tr><tr><td>8</td><td>X</td><td></td><td></td><td></td></tr></table> <p>Valid range: [1, 2, 4, 8]</p> | Value | A4 | A3 | A2 | A1 | 1 | | | | X | 2 | | | X | | 4 | | X | | | 8 | X | | | |
| Value | A4 | A3 | A2 | A1 | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | | | | X | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | | | X | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | | X | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | X | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| ReadTag.iDataLength | Output | INT | Valid length of read content in bytes. Required in order to define which content of ReadTag.arrData is valid. | | | | | | | | | | | | | | | | | | | | | | | | | |
| ReadTag.arrData | Output | ARRAY [1..64] OF BYTE | Content of read data | | | | | | | | | | | | | | | | | | | | | | | | | |

Table 2: Read tag parameters

4.5.5 Write tag

The write tag function is used to write to a defined data area of a tag. This function can only ever be applied to one tag. The selected mode determines which transponder the system communicates with (see chapter 4.5.1).

The following parameters must be set in the "WriteTag" structure before writing to an RFID tag.

| Parameter | Declaration | Data type | Description |
|---------------------|-------------|-----------|--|
| WriteTag.nBank | Input | BYTE | <p>Selection of the memory bank from which data is to be read</p> <p>0 = reserved 1 = UII/EPC 2 = TID 3 = user memory</p> |
| WriteTag.nStartWord | Input | WORD | First word (16 bits) to be written |
| WriteTag.nWordCount | Input | BYTE | <p>Number of words (16 bits) to be written</p> <p>Valid range: [1..32]</p> |

| Parameter | Declaration | Data type | Description | | | | | | | | | | | | | | | | | | | | | | | | | |
|-------------------|-------------|-----------------------|---|-------|----|----|----|----|---|--|--|--|---|---|--|--|---|--|---|--|---|--|--|---|---|--|--|--|
| WriteTag.nRetry | Input | BYTE | <p>Number of write attempts to be carried out</p> <p>Valid range: LoNibble (retries on one channel) B#16#[0..7] HiNibble (retries on different channels) B#16#[0..5]</p> <p>Example: WriteTag.iRetry = B#16#32 executes 2 retries per channel (3 <i>tries per channel</i>) with 3 channel changes (4 <i>channels</i>), i.e., a total of 3x4 = 12 attempts.</p> | | | | | | | | | | | | | | | | | | | | | | | | | |
| WriteTag.nAntenna | Input | BYTE | <p>Antenna selection for current write command. Only one antenna can be selected per command.</p> <p>A1 = antenna 1 (internal/external, depending on device type) A2 = antenna 2 (external) A3 = antenna 3 (external) A4 = antenna 4 (external)</p> <table><tr><td>Value</td><td>A4</td><td>A3</td><td>A2</td><td>A1</td></tr><tr><td>1</td><td></td><td></td><td></td><td>X</td></tr><tr><td>2</td><td></td><td></td><td>X</td><td></td></tr><tr><td>4</td><td></td><td>X</td><td></td><td></td></tr><tr><td>8</td><td>X</td><td></td><td></td><td></td></tr></table> <p>Valid range: [1, 2, 4, 8]</p> | Value | A4 | A3 | A2 | A1 | 1 | | | | X | 2 | | | X | | 4 | | X | | | 8 | X | | | |
| Value | A4 | A3 | A2 | A1 | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | | | | X | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | | | X | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | | X | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | X | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| WriteTag.arrData | Output | ARRAY [1..64] OF BYTE | Data to be written to the selected tag area | | | | | | | | | | | | | | | | | | | | | | | | | |

Table 3: Write tag parameters

4.5.6 Free command

The free command allows you to communicate with the RFU via a valid CoLa command. For this to happen, the command must be stored in the "arrCommand" parameter of the "FreeCommand" structure. The character length of the command to be transmitted is written to the "iCommandLength" parameter. The commands can be obtained from the device description or SOPAS-ET.

| Parameter | Declaration | Data type | Description |
|--------------------------------|-------------|------------------------------|---|
| FreeCommand. iCommandLength | Input | INT | Character length of the CoLa command to be transmitted Valid range [1..100] |
| FreeCommand. arrCommand | Input | ARRAY [1..100] OF CHAR | Freely selectable CoLa command (for commands, see device documentation) |
| FreeCommand. iResultLength | Output | INT | Byte length of received CoLa telegram |
| FreeCommand. arrResult | Output | ARRAY [1..100] OF CHAR | Response to the transmitted CoLa telegram |

Table 4: Free command parameters

4.5.7 Reading result

The "ReadingResult.arrResult" array stores data that is sent via a trigger command (TRIG_ON, TRIG_OFF) or directly from the device (e.g., direct trigger via photoelectric sensor). The RD_DONE output parameter signals whether data has been received.

| Parameter | Declaration | Data type | Description |
|-----------------------------|-------------|------------------------------|---|
| ReadingResult. nCounter | Output | BYTE | The receive counter is incremented by one as soon as a new reading result is received. Value range: [0x00..0xFF] |
| ReadingResult. iLength | Output | INT | Byte length of received reading result |
| ReadingResult. arrResult | Output | ARRAY [1..200] of BYTE | Response to a trigger signal (can be defined via the SOPAS output format) The maximum length of the received data is 200 bytes. Chapter 4.6 describes the procedure for receiving longer data telegrams. |

Table 5: Reading result parameters

4.6 Receiving reading results > 200 bytes

The function block is designed to receive reading results up to a length of 200 bytes. If longer data is to be received, the function block must be changed at the points indicated below.

Changes in SICK RFU DATA data block:

The length of the "ReadingResult.arrResult" array in the user data block supplied (DB74) must be set so that the reading result to be received fits into the data area of the variable.

| | | | | |
|--------|---------------|---------------|--------|---|
| +426.0 | ReadingResult | STRUCT | | -- READING RESULT -- |
| +0.0 | nCounter | BYTE | B#16#0 | This counter is incremented if a new reading result has arrived (OUT) |
| +2.0 | iLength | INT | 0 | Byte length of the reading result (OUT) |
| +4.0 | arrResult | ARRAY[1..200] | | Reading result data (OUT) |
| +1.0 | | CHAR | | |
| =204.0 | | END_STRUCT | | |

Figure 11: Receiving reading results > 200 bytes (change to data block)

Changes in SICK RFU6XX PN CP function block:

In the static area of the variable overview, the length of the "arrRecord" variable must be adapted so that the reading result fits into the data area of the variable. The array is not allowed to be less than 300 bytes in length, but must be greater than or equal to the length of "ReadingResult.arrResult".

| Contents Of: 'Environment\Interface\STAT' | | | |
|---|------------------------|---------|--|
| Name | Data Type | Address | |
| iCommandLength | Int | 38.0 | |
| iReqLength | Int | 40.0 | |
| arrCommand | Array [1..300] Of Byte | 42.0 | |
| arrRecord | Array [1..300] Of Byte | 342.0 | |
| fbCCOM | SICK CCOM PN CP | 642.0 | |

Figure 12: Receiving reading results > 200 bytes (change to function block declaration)

The newly defined array lengths must be entered into network 3 of the SICK RFU6XX PN CP function block.

```

Network 3: CONFIGURATION

- Configure the length of the "Record" array
- Configure the length of the "Command" array
- Configure the length of the "Reading Result" array
- Configure [STX]/[ETX] framing flag

PLEASE NOTE:
"Record" array >= "Command" array
"Record" array >= "Reading Result" array (external DB)

/-- LENGTH OF THE RECORD ARRAY
L 300
T #iArrayRecLen

/-- LENGTH OF THE COMMAND ARRAY
L 300
T #iArrayComLen

/-- LENGTH OF THE READING RESULT ARRAY
L 200
T #iArrayReadLen

/-- FRAMING
SET                                     // Add framing
= #bAddFraming

```

Figure 13: Receiving reading results > 200 bytes (change to block code)

After modification, the instance of the function block must be updated. Subsequently, the modified user data block and the function block must be transferred to the PLC again, together with the updated instance.

5 Parameters

| Parameter | Declaration | Data type | Memory area | Description |
|------------|-------------|-----------|-----------------|--|
| EN | INPUT | BOOL | I,M,D,L, const. | Enable input (LD and FBD) |
| CPDATA_IN | INPUT | ANY | D | <p>Pointer referencing the input area of the sensor/gateway. Only the BYTE data type is permitted.</p> <p><u>Note:</u> Please be aware that the DB parameter data always has to be specified in its entirety for the parameter (e.g.: P#DB13.DBX0.0 BYTE 100). Na explicit DB number cannot be omitted; otherwise a block error will occur.</p> |
| CPDATA_OUT | INPUT | ANY | D | <p>Pointer referencing the output area of the sensor/gateway. Only the BYTE data type is permitted.</p> <p><u>Note:</u> Please be aware that the DB parameter data always has to be specified in its entirety for the parameter (e.g.: P#DB13.DBX0.0 BYTE 100). Na explicit DB number cannot be omitted; otherwise a block error will occur.</p> |
| CAN_ID | INPUT | INT | I,M,D,L, const. | <p>CAN ID of the sensor to be addressed</p> <p>If no CAN network is used, the CAN ID is B#16#00.</p> <p>The master or multiplexer is always addressed with CAN ID B#16#00, even if it has been assigned another CAN ID.</p> |
| TOUT | INPUT | TIME | I,M,D,L, const. | Period of time, after which a timeout error is triggered |
| START_REQ | INPUT | BOOL | I,M,D,L | Rising edge: Selected block function is executed |
| TRIG_ON | INPUT | BOOL | I,M,D,L, const. | Block function: Execute a device trigger (open trigger window). |
| TRIG_OFF | INPUT | BOOL | I,M,D,L, const. | <p>Block function: Execute a device trigger (close trigger window).</p> <p>The result sent from the device (SOPAS output format) is stored in the "ReadingResult.arrResult" variable of the user data DB (DB74).</p> |

| Parameter | Declaration | Data type | Memory area | Description |
|--------------|-------------|-----------|-----------------|---|
| RD_TAG | INPUT | BOOL | I,M,D,L, const. | <p>Block function: Read tag content.</p> <p>This function only works if the parameters of the "ReadTag" structure for the transferred data block have been assigned valid values (see chapter 4.5.4).</p> <p>The selected addressing mode determines which transponder is to be read (see chapter 4.5.1).</p> |
| WR_TAG | INPUT | BOOL | I,M,D,L, const. | <p>Block function: Write tag content.</p> <p>This function only works if the parameters of the "WriteTag" structure for the transferred data block have been assigned valid values (see chapter 4.5.5).</p> <p>The selected addressing mode determines which transponder is to be written to (see chapter 4.5.1).</p> |
| COM_TEST | INPUT | BOOL | I,M,D,L, const. | <p>Block function: Execute a communication test.</p> <p>REQ_DONE = TRUE: Communication OK</p> <p>REQ_DONE = FALSE: Communication not OK</p> |
| FREE_COMMAND | INPUT | BOOL | I,M,D,L, const. | <p>Block function: Execute a free command.</p> <p>This function only works if valid data has been assigned to the iCommandLength and arrCommand parameters in the structure (FreeCommand) within the user data block (DB74) (see chapter 4.5.6).</p> <p>Following successful transfer, the command response (REQ_DONE = TRUE) is made available in the RESULT area of the data block.</p> |
| RESET | INPUT | BOOL | I,M,D,L, const. | Block function: Reset communication with device. |
| DATA | INPUT | BLOCK_DB | Const. | Transfers the accompanying user data block that is required to configure the block functions and store the reading results (DB74) |
| RD_DONE | OUTPUT | BOOL | Q,M,D,L | <p>Rising edge:</p> <p>New reading result received</p> |

| Parameter | Declaration | Data type | Memory area | Description |
|------------|-------------|-----------|-------------|---|
| REQ_DONE | OUTPUT | BOOL | Q,M,D,L | Indicates whether the selected block function has been successfully completed TRUE: Successfully completed FALSE: Not completed |
| REQ_BUSY | OUTPUT | BOOL | Q,M,D,L | Command in progress |
| ERROR | OUTPUT | BOOL | Q,M,D,L | Error bit: 0: No error 1: Aborted with error |
| ERROR CODE | OUTPUT | WORD | Q,M,D,L | Error status (see "Error codes") |
| ENO | OUTPUT | BOOL | Q,M,D,L | Enable output (LD and FBD) |

Table 6: Block parameters

6 Error codes

The ERRORCODE parameter contains the following error information:

| Error code | Brief description | Description |
|------------|--|---|
| W#16#0000 | No error | No error |
| W#16#0001 | Timeout error | <p>Command could not be executed within the selected timeout period</p> <p>Possible causes:</p> <ul style="list-style-type: none"> - Device is not connected to the PLC - Incorrect communication parameters - CAN bus station not present |
| W#16#0002 | Internal block error | Internal block error |
| W#16#0003 | No block function selected, or more than one block function selected | Only one block function can be executed at a time. |
| W#16#0004 | Received reading result > reading result array | The reading result received is longer than 200 bytes. See chapter 4.6 for information on how to receive longer reading results. |
| W#16#0005 | 100 < FreeCommand. iCommandLength <=0 | <p>Length of free command is invalid</p> <p>Valid range: [1...100]</p> |
| W#16#0006 | Free command response > 100 bytes | The response to the free command sent is longer than 100 bytes. |
| W#16#0007 | 63 < CAN_ID < 0 | <p>Invalid CAN ID</p> <p>Valid range: [0..63]</p> |
| W#16#0008 | Reserved | Reserved |
| W#16#0009 | Communication error | <p>Communication could not be established with the device.</p> <p>Possible causes:</p> <ul style="list-style-type: none"> - Length of I/O data is invalid - A telegram > arrRecord was received. |
| W#16#XX0A | Device error | <p>A device error occurred ("sFA XX").</p> <p>XX = device error (see device documentation)</p> |

| Error code | Brief description | Description |
|-----------------------|--------------------------------|--|
| W#16#000B | Invalid command response | <p>The selected function was not executed.</p> <p>The following causes are possible, depending on the function:</p> <ul style="list-style-type: none"> - Incorrect trigger setting in the SOPAS device configuration - Device is not in "Run mode" - Send/receive power insufficient - Tag not long enough in field - Attempt to access a non-existent tag area (check nStartWord and nWordCount parameters) - Selected antenna cannot access the selected tag (check nAntenna parameter) - Invalid UII (check Mode.arrUII and Mode.iUIILength) |
| W#16#000C – W#16#000F | Reserved | Reserved |
| W#16#0010 | 60 < Mode.iUIILength < 0 | <p>UII length is invalid</p> <p>Valid range: [0..60]</p> |
| W#16#0011 | 3 < ReadTag.nBank < 0 | <p>Invalid bank (read tag)</p> <p>Valid range: [0..3]</p> |
| W#16#0012 | 32 < ReadTag.nWordCount <= 0 | <p>The function block can read a maximum of 32 words (64 bytes) from the tag.</p> <p>Valid range [1..32]</p> |
| W#16#0013 | Invalid retry (ReadTag.nRetry) | <p>Invalid retry parameter (read tag)</p> <p>Valid range: Low nibble = [0..7] High nibble = [0..5]</p> |
| W#16#0014 | 15 < ReadTag.nAntenna < 1 | <p>Invalid antenna selection (read tag)</p> <p>Valid range: [1..15]</p> |
| W#16#0015 | 3 < WriteTag.nBank < 0 | <p>Invalid bank (write tag)</p> <p>Valid range: [0..3]</p> |
| W#16#0016 | 32 < WriteTag.nWordCount <= 0 | <p>The function block can write a max. of 32 words (64 bytes) to the tag.</p> <p>Valid range [1..32]</p> |

| Error code | Brief description | Description |
|------------|---|---|
| W#16#0017 | Invalid retry (WriteTagTag.nRetry) | Invalid retry parameter (write tag) Valid range: Low nibble = [0..7] High nibble = [0..5] |
| W#16#0018 | 15 < WriteTag. nAntenna < 1 | Invalid antenna selection (write tag) Valid range: [1..15] |
| W#16#0019 | Invalid output format | Invalid SOPAS-ET output format. Check the output format (see chapter 4.5.3). This error can only occur in Mode 1. |
| W#16#001A | No tag in field | There are no tags in the receiving range of the RFU. This error can only occur in Mode 1. |
| W#16#001B | There is more than one tag in the field or the RSSImin evaluation condition has not been met. | This error can signify several different things: <ul style="list-style-type: none"> - There is more than one tag in the receiving range of the RFU. - The RSSImin evaluation condition has not been met (see SOPAS-ET). This error can only occur in Mode 1. |

Table 7: Error codes

7 Examples

Figure 14 shows an example of a connected SICK RFU6XX function block. A SICK device with a process data width of 32 bytes input/output has been set up in the hardware configuration. The I/O area of the device is written to/read using functions FC11/FC12 (see chapter 3.3). As the sensor's CAN communication is not being used, a zero is entered for the CAN ID.

Program call:

```

Network 3: AUFRUF RFU FB | CALL RFU FB

Aufruf des RFU Funktionsbausteins (Profinet-Anbindung über CP-Modul)
---
Call of the RFU function block (Profinet-Connection via CP-Module)

CALL "SICK RFU6XX PN CP" , "INSTANCE_FB74"      FB74 / DB174
CPDATA_IN    :=P#DB2.DBX2.0 BYTE 32
CPDATA_OUT   :=P#DB2.DBX40.0 BYTE 32
CAN_ID       := "iCanID"                        MW16
TOUT         :=T#5S
START_REQ    := "bRequest"                      M10.0
TRIG_ON      := "bTriggerOn"                    M12.1
TRIG_OFF     := "bTriggerOff"                   M12.2
RD_TAG       := "bRdTag"                        M12.3
WR_TAG       := "bWrTag"                        M12.5
COM_TEST     := "bComTest"                      M12.4
FREE_COMMAND := "bFreeCommand"                 M12.6
RESET        := "bReset"                        M12.0
DATA         := "SICK RFU DATA"                DB74
RD_DONE      := "bRdDone"                       M10.1
REQ_DONE     := "bReqDone"                      M10.2
REQ_BUSY     := "bReqBusy"                      M10.3
ERROR        := "bError"                       M10.4
ERRORCODE    := "nErrorcode"                   MW14
  
```

Figure 14: Example of a connected SICK RFU6XX PN CP function block

| Slot | Module | Ord... | I address | Q address | Diagnostic addre... |
|------|---------------------|--------|-----------|-----------|---------------------|
| 0 | RFU6xx | | | | 4091* |
| X7 | Interface | | | | 4090* |
| X7A | Port 1 | | | | 4089* |
| 1 | Ctrl Bits in | | 0...1 | | |
| 2 | Ctrl Bits out | | | 0...1 | |
| 3 | 32 Byte Input (HS) | | 2...33 | | |
| 4 | 32 Byte Output (HS) | | | 2...33 | |

Figure 15: Step7 hardware configuration

7.1 Reading tag content

First, it is necessary to determine which transponder the system is to communicate with. If bit Mode.bMode = FALSE, then the system will communicate with the transponder that is currently located in the RFID sensor's reading range. The RFU must be specially configured in SOPAS-ET (see chapters 4.5.2 and 4.5.3) for this mode.

```
// ===== Mode =====
```

| | | | | |
|----------|-----|----------------------------|------|-------|
| DB74.DBX | 0.0 | "SICK RFU DATA".Mode.bMode | BOOL | false |
|----------|-----|----------------------------|------|-------|

Figure 16: Selection of communication mode

Then, it is necessary to define what content is to be read out of the transponder.

Bank: 3 (user memory)
 Tag range: 0 ... 6 words (12 bytes)
 Number of retries: 0x57 (5 changes of channel with 7 retries per channel)
 Antenna selection: 1 (antenna 1)

```
// ===== Read Tag =====
```

| | | | | |
|----------|----|------------------------------------|-----|---------|
| DB74.DBB | 76 | "SICK RFU DATA".ReadTag.nBank | DEC | 3 |
| DB74.DBW | 78 | "SICK RFU DATA".ReadTag.nStartWord | DEC | 0 |
| DB74.DBB | 80 | "SICK RFU DATA".ReadTag.nWordCount | DEC | 6 |
| DB74.DBB | 81 | "SICK RFU DATA".ReadTag.nRetry | HEX | B#16#57 |
| DB74.DBB | 82 | "SICK RFU DATA".ReadTag.nAntenna | DEC | 1 |

Figure 17: Definition of reading parameters

The reading function (bRdTag) is executed as soon as the "bRequest" bit is triggered with a rising edge.

```
// SICK RFU6XX PNCP Function Block Example
```

| | | | | |
|-----|------|--------------|------|------------|
| MVW | 16 | "iCanID" | DEC | 0 |
| M | 10.0 | "bRequest" | BOOL | true |
| M | 10.2 | "bReqDone" | BOOL | true |
| M | 10.3 | "bReqBusy" | BOOL | false |
| M | 10.4 | "bError" | BOOL | false |
| MVW | 14 | "nErrorcode" | HEX | VW#16#0000 |


```
// Selection of the FB action to be executed
```

| | | | | |
|---|------|----------------|------|-------|
| M | 12.1 | "bTriggerOn" | BOOL | false |
| M | 12.2 | "bTriggerOff" | BOOL | false |
| M | 12.3 | "bRdTag" | BOOL | true |
| M | 12.5 | "bWrTag" | BOOL | false |
| M | 12.4 | "bComTest" | BOOL | false |
| M | 12.6 | "bFreeCommand" | BOOL | false |
| M | 12.0 | "bReset" | BOOL | false |

Figure 18: Starting the block function

The reading function is completed as soon as bit bReqDone = TRUE. The read tag content is available in the "ReadTag.arrData" array of the user data block. The "ReadTag.iDataLength" variable specifies how many bytes have been received and are valid.

```
// ===== Read Tag =====
```

| | | | | |
|----------|-----|-------------------------------------|-----------|---------|
| DB74.DBB | 76 | "SICK RFU DATA".ReadTag.nBank | DEC | 3 |
| DB74.DBW | 78 | "SICK RFU DATA".ReadTag.nStartWord | DEC | 0 |
| DB74.DBB | 80 | "SICK RFU DATA".ReadTag.nWordCount | DEC | 6 |
| DB74.DBB | 81 | "SICK RFU DATA".ReadTag.nRetry | HEX | B#16#57 |
| DB74.DBB | 82 | "SICK RFU DATA".ReadTag.nAntenna | DEC | 1 |
| DB74.DBW | 84 | "SICK RFU DATA".ReadTag.iDataLength | DEC | 12 |
| DB74.DBB | 86 | "SICK RFU DATA".ReadTag.arrData[1] | CHARACTER | 'H' |
| DB74.DBB | 87 | "SICK RFU DATA".ReadTag.arrData[2] | CHARACTER | 'e' |
| DB74.DBB | 88 | "SICK RFU DATA".ReadTag.arrData[3] | CHARACTER | 'l' |
| DB74.DBB | 89 | "SICK RFU DATA".ReadTag.arrData[4] | CHARACTER | 'l' |
| DB74.DBB | 90 | "SICK RFU DATA".ReadTag.arrData[5] | CHARACTER | 'o' |
| DB74.DBB | 91 | "SICK RFU DATA".ReadTag.arrData[6] | CHARACTER | ' ' |
| DB74.DBB | 92 | "SICK RFU DATA".ReadTag.arrData[7] | CHARACTER | 'W' |
| DB74.DBB | 93 | "SICK RFU DATA".ReadTag.arrData[8] | CHARACTER | 'o' |
| DB74.DBB | 94 | "SICK RFU DATA".ReadTag.arrData[9] | CHARACTER | 'r' |
| DB74.DBB | 95 | "SICK RFU DATA".ReadTag.arrData[10] | CHARACTER | 'l' |
| DB74.DBB | 96 | "SICK RFU DATA".ReadTag.arrData[11] | CHARACTER | 'd' |
| DB74.DBB | 97 | "SICK RFU DATA".ReadTag.arrData[12] | CHARACTER | ' ' |
| DB74.DBB | 98 | "SICK RFU DATA".ReadTag.arrData[13] | CHARACTER | B#16#00 |
| DB74.DBB | 99 | "SICK RFU DATA".ReadTag.arrData[14] | CHARACTER | B#16#00 |
| DB74.DBB | 100 | "SICK RFU DATA".ReadTag.arrData[15] | CHARACTER | B#16#00 |

Figure 19: Read tag content

7.2 Writing tag content

First, it is necessary to determine which transponder the system is to communicate with. If bit Mode.bMode = TRUE, then the system will communicate with the specified transponder, the Ull of which is known in advance (in this case: 12345678).

```
// ===== Mode =====
```

| | | | | |
|----------|-----|---------------------------------|-----------|---------|
| DB74.DBX | 0.0 | "SICK RFU DATA".Mode.bMode | BOOL | true |
| DB74.DBW | 2 | "SICK RFU DATA".Mode.iUllLength | DEC | 8 |
| DB74.DBB | 8 | "SICK RFU DATA".Mode.arrUll[1] | CHARACTER | '1' |
| DB74.DBB | 9 | "SICK RFU DATA".Mode.arrUll[2] | CHARACTER | '2' |
| DB74.DBB | 10 | "SICK RFU DATA".Mode.arrUll[3] | CHARACTER | '3' |
| DB74.DBB | 11 | "SICK RFU DATA".Mode.arrUll[4] | CHARACTER | '4' |
| DB74.DBB | 12 | "SICK RFU DATA".Mode.arrUll[5] | CHARACTER | '5' |
| DB74.DBB | 13 | "SICK RFU DATA".Mode.arrUll[6] | CHARACTER | '6' |
| DB74.DBB | 14 | "SICK RFU DATA".Mode.arrUll[7] | CHARACTER | '7' |
| DB74.DBB | 15 | "SICK RFU DATA".Mode.arrUll[8] | CHARACTER | '8' |
| DB74.DBB | 16 | "SICK RFU DATA".Mode.arrUll[9] | CHARACTER | B#16#00 |
| DB74.DBB | 17 | "SICK RFU DATA".Mode.arrUll[10] | CHARACTER | B#16#00 |

Figure 20: Specification of transponder Ull

Subsequently, it is necessary to define what content is to be written to the tag and where it should be stored.

Bank: 3 (user memory)
 Tag range: 0 ... 3 words (6 bytes/character)
 Number of retries: 0x57 (5 changes of channel with 7 retries per channel)
 Antenna selection: 1 (antenna 1)
 Content to be written: "Tag 01" (6 ASCII characters)

```
// ===== Write Tag =====
```

| | | | |
|--------------|-------------------------------------|-----------|---------|
| DB74.DBB 150 | "SICK RFU DATA".WriteTag.nBank | DEC | 3 |
| DB74.DBW 152 | "SICK RFU DATA".WriteTag.nStartWord | DEC | 0 |
| DB74.DBB 154 | "SICK RFU DATA".WriteTag.nWordCount | DEC | 3 |
| DB74.DBB 155 | "SICK RFU DATA".WriteTag.nRetry | HEX | B#16#57 |
| DB74.DBB 156 | "SICK RFU DATA".WriteTag.nAntenna | HEX | B#16#01 |
| DB74.DBB 158 | "SICK RFU DATA".WriteTag.arrData[1] | CHARACTER | 'I' |
| DB74.DBB 159 | "SICK RFU DATA".WriteTag.arrData[2] | CHARACTER | 'a' |
| DB74.DBB 160 | "SICK RFU DATA".WriteTag.arrData[3] | CHARACTER | 'g' |
| DB74.DBB 161 | "SICK RFU DATA".WriteTag.arrData[4] | CHARACTER | ' ' |
| DB74.DBB 162 | "SICK RFU DATA".WriteTag.arrData[5] | CHARACTER | '0' |
| DB74.DBB 163 | "SICK RFU DATA".WriteTag.arrData[6] | CHARACTER | '1' |

Figure 21: Definition of reading parameters

The write function (bWrTag) is executed as soon as the "bRequest" bit is triggered with a rising edge.

```
// SICK RFU6XX PNCP Function Block Example
```

| | | | |
|--------|--------------|------|-----------|
| MW 16 | "iCanID" | DEC | 0 |
| M 10.0 | "bRequest" | BOOL | true |
| M 10.2 | "bReqDone" | BOOL | true |
| M 10.3 | "bReqBusy" | BOOL | false |
| M 10.4 | "bError" | BOOL | false |
| MW 14 | "nErrorcode" | HEX | W#16#0000 |

```
// Selection of the FB action to be executed
```

| | | | |
|--------|----------------|------|-------|
| M 12.1 | "bTriggerOn" | BOOL | false |
| M 12.2 | "bTriggerOff" | BOOL | false |
| M 12.3 | "bRdTag" | BOOL | false |
| M 12.5 | "bWrTag" | BOOL | true |
| M 12.4 | "bComTest" | BOOL | false |
| M 12.6 | "bFreeCommand" | BOOL | false |
| M 12.0 | "bReset" | BOOL | false |

Figure 22: Starting the block function

The write function is completed as soon as bit bReqDone = TRUE.