

# ATM60-A4A00S07

ATM60

**ABSOLUTE ENCODERS**

**SICK**  
Sensor Intelligence.



Illustration may differ

### Ordering information

Type	part no.
ATM60-A4A00S07	1082941

Other models and accessories → [www.sick.com/ATM60](http://www.sick.com/ATM60)

### Detailed technical data

#### Features

<b>Special device</b>	✓
<b>Specialty</b>	Replaces item 1034234 CHI-81B001002048 with adapter kit. Technical data below refers to the encoder Without mechanical adapters Dimensional drawing shows the complete device with premounted mechanical adapter
<b>Standard reference device</b>	ATM60-A4A12X12, 1030001

#### Safety-related parameters

<b>MTTF<sub>D</sub> (mean time to dangerous failure)</b>	150 years (EN ISO 13849-1) <sup>1)</sup>
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<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Performance

<b>Number of steps per revolution (max. resolution)</b>	8,192 (13 bit)
<b>Number of revolutions</b>	8,192 (13 bit)
<b>Max. resolution (number of steps per revolution x number of revolutions)</b>	13 bit x 13 bit (8,192 x 8,192)
<b>Resolution</b>	Maximum permissible resolution: 25 bit (12 bit singleturn x 13 bit multiturn or 13 bit singleturn x 12 bit multiturn).
<b>Measuring step</b>	0.043 °
<b>Error limits G</b>	± 0.25 ° <sup>1)</sup>
<b>Repeatability standard deviation <math>\sigma_r</math></b>	0.1 ° <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

<sup>2)</sup> In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

#### Interfaces

<b>Communication interface</b>	SSI
<b>Initialization time</b>	1,050 ms <sup>1)</sup>
<b>Position forming time</b>	0.15 ms
<b>Parameterising data</b>	Number of steps per revolution Number of revolutions

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Minimum, LOW level (Clock +): 500 ns.

	Code type Electronic adjustment
<b>Code type</b>	Gray, binary
<b>Code sequence parameter adjustable</b>	CW/CCW (V/R)
<b>Clock frequency</b>	1 MHz <sup>2)</sup>
<b>Set (electronic adjustment)</b>	H-active (L = 0 - 4,7 V, H = 10 - Us V)
<b>CW/CCW (counting sequence when turning)</b>	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Minimum, LOW level (Clock +): 500 ns.

## Electronics

<b>Connection type</b>	Male connector, M23, 12-pin, radial
<b>Supply voltage</b>	10 ... 32 V
<b>Power consumption</b>	≤ 0.8 W (without load)
<b>Reverse polarity protection</b>	✓

## Mechanics

<b>Mechanical design</b>	Solid shaft, face mount flange
<b>Shaft diameter</b>	10 mm
<b>Shaft length</b>	19 mm
<b>Weight</b>	0.5 kg <sup>1)</sup>
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Start up torque</b>	2.5 Ncm (+20 °C), with shaft seal 0.5 Ncm (+20 °C), without shaft seal <sup>2)</sup>
<b>Operating torque</b>	1.8 Ncm (+20 °C), with shaft seal 0.3 Ncm (+20 °C), without shaft seal <sup>2)</sup>
<b>Permissible shaft loading</b>	300 N (radial) 50 N (axial)
<b>Operating speed</b>	≤ 6,000 min <sup>-1</sup> <sup>3)</sup>
<b>Moment of inertia of the rotor</b>	35 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>9</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Based on encoder with male connector.

<sup>2)</sup> If the shaft seal has been removed by the customer.

<sup>3)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3
<b>Enclosure rating</b>	IP67, with shaft seal (IEC 60529) <sup>1)</sup> IP43, without shaft seal, on encoder flange not sealed (IEC 60529) <sup>1)</sup> IP65, without shaft seal, on encoder flange sealed (IEC 60529) <sup>1)</sup>
<b>Permissible relative humidity</b>	98 %
<b>Operating temperature range</b>	-20 °C ... +85 °C

<sup>1)</sup> With mating connector fitted.

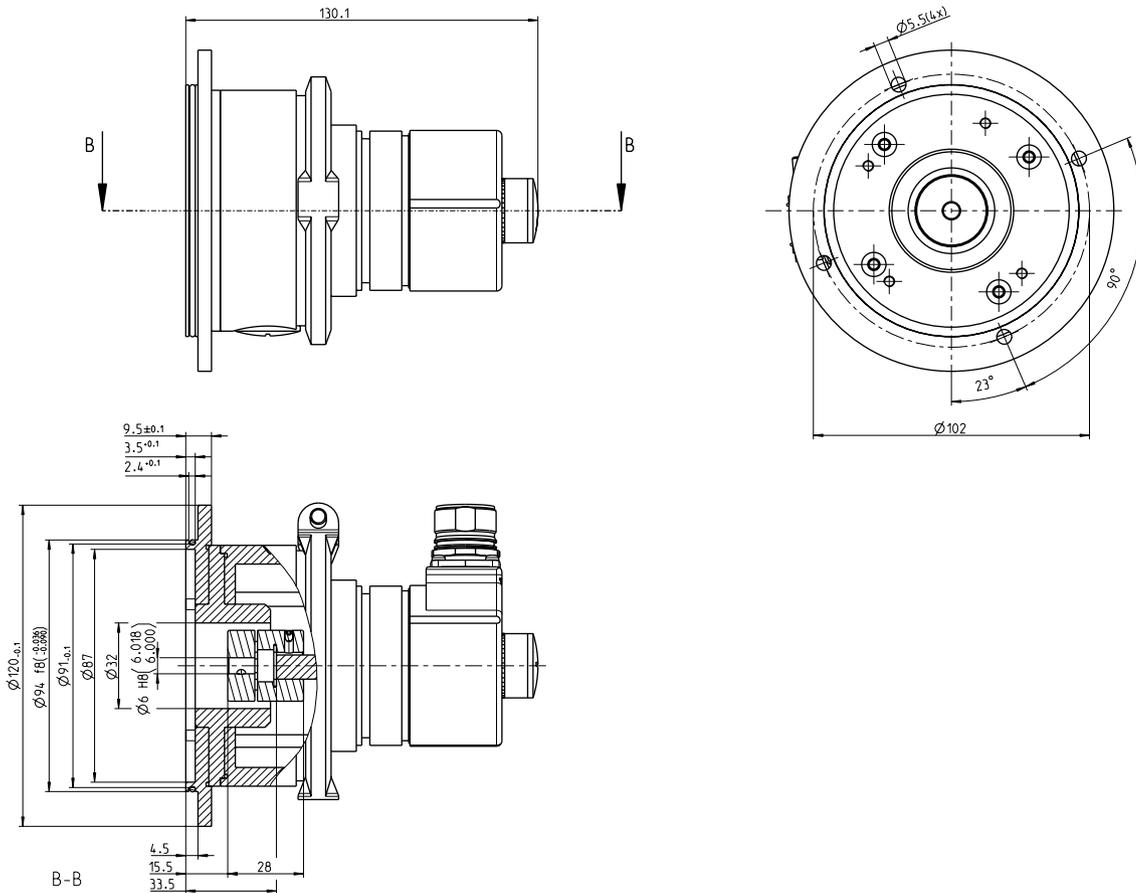
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	100 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

<sup>1)</sup> With mating connector fitted.

### Classifications

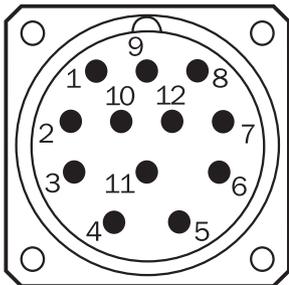
<b>ECLASS 5.0</b>	27270502
<b>ECLASS 5.1.4</b>	27270502
<b>ECLASS 6.0</b>	27270590
<b>ECLASS 6.2</b>	27270590
<b>ECLASS 7.0</b>	27270502
<b>ECLASS 8.0</b>	27270502
<b>ECLASS 8.1</b>	27270502
<b>ECLASS 9.0</b>	27270502
<b>ECLASS 10.0</b>	27270502
<b>ECLASS 11.0</b>	27270502
<b>ECLASS 12.0</b>	27270502
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

Dimensional drawing



Dimensions in mm (inch)

view of M23 male device connector on encoder



view of M23 male device connector on encoder

PIN	Signal	Wire colors (cable connection)	Explanation
1	GND	Blue	Ground connection
2	Data +	White	Interface signals
3	Clock +	Yellow	Interface signals
4	R x D +	Gray	RS-422 programming lines
5	R x D -	Green	RS-422 programming lines
6	T x D +	Pink	RS-422 programming lines

PIN	Signal	Wire colors (cable connection)	Explanation
7	T x D -	Black	RS-422 programming lines
8	$U_S$	Red	Operating voltage
9	SET <sup>1)</sup>	Orange	Electronic adjustment
10	Data -	Brown	Interface signals
11	Clock -	Purple	Interface signals
12	V/R <sup>2)</sup>	Orange-black	Sequence in direction of rotation
-	Screen	-	Housing potential

SET = This input activates the electronic zero set. If the SET cable is set to  $U_S$  for more than 100 ms, the mechanical position corresponds to the 0 value, i.e., the predetermined SET value.

V/R = Forwards/Reverse: This input programs the counting direction for the encoder. When it is not connected, this input is set to HIGH. If the encoder shaft is rotated clockwise (to the right) as viewed when facing the shaft, it counts in ascending order. If it should count in ascending order when the shaft is rotated counterclockwise (to the left), then this connection must be permanently set to LOW level (GND).

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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