Described product
microScan3

Manufacturer
SICK AG
Erwin-Sick-Str. 1
79183 Waldkirch
Germany

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Original document
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1 About this document

1.1 Function of this document

These operating instructions contain the information needed during the life cycle of the safety laser scanner.

Operating instructions of the safety laser scanner must be made available to all people who work with the device.

Read the operating instructions carefully and ensure that you have understood the contents completely before you work with the safety laser scanner.

1.2 Scope

The operating instructions, having the part number 8016344, only apply to the microScan3 safety laser scanner.

The operating instructions, SICK part number 8016344, are included (all available language versions of the operating instructions).

1.3 Target groups and structure of these operating instructions

These operating instructions are intended for the following target groups: project developers (planners, developers, designers), installers, electricians, safety experts (such as CE authorized representatives, compliance officers, people who test and approve the application), operators, and maintenance personnel.

The structure of these operating instructions is based on the life cycle phases of the safety laser scanner: project planning, mounting, electrical installation, configuration, commissioning, operation, and maintenance.

In many applications, the target groups consist of the manufacturer and the operator of the machine in which the safety laser scanner is integrated:

<table>
<thead>
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<th>Area of responsibility</th>
<th>Target group</th>
<th>Special chapters of these operating instructions</th>
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<td>Project developers (planners, developers, designers)</td>
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User

| Target group | Operation, page 109, Troubleshooting, page 121 |

Maintenance personnel

| Target group | Maintenance, page 114, Troubleshooting, page 121, Accessories, page 144 |

1 Chapters not listed here are intended for all target groups. All target groups must understand the safety information in all of the operating instructions!
In other applications, the operating organization is also the manufacturer of the equipment with the corresponding allocation of the target groups.

### 1.4 Further information

www.sick.com

The following information is available via the Internet:

- Further language versions of these operating instructions
- Data sheets and application examples
- CAD data for drawings and dimensional drawings
- Certificates (such as the EU declaration of conformity)
- Guide for Safe Machinery (six steps to a safe machine)
- Safety Designer (software for configuring the safety laser scanner and further safety solutions)

### 1.5 Symbols and document conventions

The following symbols and conventions are used in this document:

#### Safety notes and other notes

- **DANGER**
  Indicates a situation presenting imminent danger, which will lead to death or serious injuries if not prevented.

- **WARNING**
  Indicates a situation presenting possible danger, which may lead to death or serious injuries if not prevented.

- **CAUTION**
  Indicates a situation presenting possible danger, which may lead to moderate or minor injuries if not prevented.

- **NOTICE**
  Indicates a situation presenting possible danger, which may lead to property damage if not prevented.

- **NOTE**
  Indicates useful tips and recommendations.

#### Instructions to action

- The arrow denotes instructions to action.

1. The sequence of instructions for action is numbered.
2. Follow the order in which the numbered instructions are given.

#### LED symbols

These symbols indicate the status of an LED:

- ○ The LED is off.
-  The LED is flashing.
-  The LED is illuminated continuously.
2 Safety information

2.1 General safety notes

This chapter contains general safety information about the safety laser scanner. Further information about specific product use situations can be found in the relevant chapters.

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

- Read this document carefully and ensure that you have fully understood the contents before you work with the device.
- Pay particular attention to all safety notes in this document.

**WARNING**

Invisible laser radiation
Laser class 1M

![CAUTION] LASER 1M

IEC 60825-1:2007 & 2014
Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, June 2007

*Figure 1: Laser class 1M*

This device complies with the following standards:

- 21 CFR 1040.10 and 1040.11, except for changes due to Laser Notice No. 50 of 24/06/2007

The safety laser scanner’s accessible laser is not hazardous as long as the beam cross section is not reduced by optical instruments, such as magnifying glasses, lenses, telescopes.

The curved part of the optics cover is the outlet for the laser radiation.

The laser marking is located on the underside of the safety laser scanner.

- You must comply with the latest version of the applicable laser safety regulations.

**CAUTION**

If any operating or adjusting devices other than those specified in this document are used or other methods are employed, this can lead to dangerous exposure to radiation.

- Only use the operating or adjusting devices specified in this document.
- Only follow the methods specified in this document.
- Do not open the housing, except for the purposes of the installation and maintenance work specified in these operating instructions.
CAUTION

Observing the safety laser scanner through optical instruments (such as magnifying glasses, lenses, telescopes) may be hazardous for the eyes.

- Do not look directly at the laser beam source using optical instruments.

2.2 Correct use

The safety laser scanner is an electro-sensitive protective device (ESPE) and is suitable for the following applications:

- Hazardous area protection
- Hazardous point protection
- Access protection
- Mobile hazardous area protection (protection of automated guided vehicles)

The safety laser scanner must only be used within the limits of the prescribed and specified technical data and operating conditions at all times.

Incorrect use, improper modification of or tampering with the safety laser scanner will invalidate any warranty from SICK; in addition, any responsibility and liability of SICK for damage and secondary damage caused by this is excluded.

Foreseeable misuse

DANGER

Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

The safety laser scanner works as an indirect protective measure and cannot provide protection from pieces thrown from application nor from emitted radiation. Transparent objects are not detected.

- You must only use the safety laser scanner as an indirect protective measure.

The safety laser scanner is not suitable for the following applications, among others:

- Outdoors
- Underwater
- In explosive environments

2.3 Requirements for personnel qualifications

The safety laser scanner must only be configured, installed, connected, commissioned and serviced by qualified safety personnel.

Project planning

For project planning, a person is considered competent when he/she has expertise and experience in the selection and use of protective devices on machines and is familiar with the relevant technical rules and national work safety regulations.

Mechanical mounting

For mechanical mounting, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine that he/she can assess its operational safety status.
Electrical installation
For electrical installation, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine that he/she can assess its operational safety status.

Configuration
For configuration, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine that he/she can assess its work safety aspects.

Commissioning
For commissioning, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine that he/she can assess its operational safety status.

Operation and maintenance
For operation and maintenance, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine and has been instructed by the machine operator in its operation.

An operator may clean the safety laser scanner and carry out specific thorough checks following instruction. More information for the operator of the machine: see "Operation", page 109, see "Regular cleaning", page 114.
3 Product description

3.1 Setup and function

The safety laser scanner is an electro-sensitive protective device (ESPE), which two-dimensionally scans its environment with infrared laser beams.

The safety laser scanner forms a protective field using the invisible laser beams. This protective field protects the hazardous area and enables hazardous-point protection, access protection or hazardous-area protection. As soon as an object is situated in the protective field, the safety laser scanner signals the detection by means of a signal change at the safety output (OSSD for example). The machine or its control must safely analyze the signals (for example using a safe control or safety relays) and stop the dangerous state.

The safety laser scanner operates on the principle of time-of-flight measurement. It emits light pulses in regular, very short intervals. If the light strikes an object, it is reflected. The safety laser scanner receives the reflected light. The safety laser scanner calculates the distance to the object based on the time interval between the moment of transmission and moment of receipt ($\Delta t$).

![Figure 2: Principle of time-of-flight measurement](image)

A rotating mirror is situated in the safety laser scanner. The mirror deflects the light pulses so that they scan a fan-shaped area.
Figure 3: Light pulses scan an area

Angular resolution: the angular distance (in degrees) between two distance measurements.

Scan cycle time and resolution

The time that the mirror requires for one rotation is called the scan cycle time. The number of light pulses per unit time is constant. A change in the scan cycle time also changes the number of light pulses per mirror rotation. This results in different angular resolutions. The range for a given object resolution changes with the angular resolution. The object resolution indicates the minimum size that an object must be to allow it to be detected safely. Also, different response times result from a change to the scan cycle time.

Slightly different scan cycle times can be used to minimize mutual interference in neighboring safety laser scanners.

The resolution in protective fields can be set between 30 mm and 200 mm, according to the intended purpose.

Geometry of the scan plane

The laser beams emitted cover a sector of a circle, so an object can be detected in an area of up to 275°.

The sector of a circle covered ranges from –47.5° to 227.5°, where 90° denotes the axis of the safety laser scanner from the back to the front. When viewing the safety laser scanner from above, the direction of rotation of the mirror and the deflected light pulses is counterclockwise, see figure 3.
3.2 Product characteristics

3.2.1 Device overview

![microScan3 - overview](image)

Figure 4: microScan3 – overview

1. Optics cover
2. Display
3. Keypad
4. USB connection
5. Status LEDs
6. Additional LEDs
7. Safety laser scanner without system plug
8. System plug

Different variants of the safety laser scanner are available, see "Variants", page 15, see "Variant overview", page 132.

All variants have an optics cover and the rotating mirror is located below the optics cover. The light pulses are emitted and the reflected light pulses are received through the optics cover.

The display with four buttons is located below the optics cover. The safety laser scanner also has a number of LEDs, see "Status indicators", page 15, see "Buttons and display", page 110.

Information about connections: see "Connections", page 16.

The safety laser scanner can be mounted and operated in any alignment. In this document, position and direction information is used as follows with respect to the safety laser scanner, as long as different usage is not indicated separately:

- The top is the side of the safety laser scanner on which the optics cover is located.
- The bottom is the side of the safety laser scanner opposite the optics cover.
- The front is the side of the safety laser scanner on which the display is located. The 90° angle of the sector of a circle scanned by the safety laser scanner points in this direction.
- The back is the side of the safety laser scanner opposite the display. The sector of a circle not scanned by the safety laser scanner lies in this direction.
3.2.2 Variants

The safety laser scanner is delivered in different variants. You will find an overview of important distinguishing features of the variants in the following. Further information about the variants see “Variant overview”, page 132.

The following property differs in the variants:

- Maximum protective field range

Performance package

The core performance package features a number of configurable fields and a number of safety switching functions (OSSD pairs).

- microScan3 core I/O: 8 fields; safety output: 1 OSSD pair

Integration in the control

The microScan3 Core I/O communicates with the machine controller as follows:

- I/O: local inputs and outputs (incl. OSSDs)

Protective field range

There are two variants with different protective field ranges:

- 4.0 m
- 5.5 m

3.2.3 Status indicators

The safety laser scanner outputs important status information using a number of LEDs. The safety laser scanner has a graphical display and four pushbuttons for additional information.

Four status LEDs are located directly above the display.

![Figure 5: Status LEDs]

<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
<th>Color</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>①</td>
<td>OFF state</td>
<td>Red</td>
<td>Shines red when the OSSD pair is in the OFF state.</td>
</tr>
<tr>
<td>②</td>
<td>ON state</td>
<td>Green</td>
<td>Shines green when the OSSD pair is in the ON state.</td>
</tr>
<tr>
<td>③</td>
<td>Warning field</td>
<td>Yellow</td>
<td>Shines yellow if at least one warning field is interrupted.</td>
</tr>
<tr>
<td>④</td>
<td>Restart interlock</td>
<td>Yellow</td>
<td>Flashes if restart interlock is configured with reset and the restart interlock has been triggered. The operator must press the reset pushbutton.</td>
</tr>
</tbody>
</table>

Table 1: Status LEDs
The OFF state and ON state LEDs can be found in multiple locations on the safety laser scanner. Three sets are arranged in pairs on the base of the optics cover. These LEDs can also be seen in many cases when it is not possible to see the display, e.g., due to the mounting situation or because it is hidden from the operator's position.

More information about the meaning of the LEDs see "Diagnostic LEDs", page 121.

Depending on the configuration, the display shows current information about the safety laser scanner's status, see "Buttons and display", page 110.

3.2.4 Connections

The connections to the scanner are available as follows:

- **microScan3 Core I/O**: power supply and interfaces are tied via a short cable. The cable is securely connected to the safety laser scanner. A single M12 plug connector is located at the end of the cable.
- **USB 2.0 mini-B (female connector)**. The USB connection may only be used temporarily and only for configuration and diagnostics.

The safety laser scanner has the following interfaces:

- **OSSD**
- **Universal I/O** can be used as universal input, universal output or in pairs as static control input
- **USB** for configuration and diagnostics

**OSSD**

An OSSD is a safety switching output. The functionality of each OSSD is tested periodically. OSSDs are always connected in pairs and must undergo dual-channel analysis for safety reasons. An OSSD pair is formed from two OSSDs that are connected and analyzed together.

**Control input**

A control input receives signals, e.g., from the machine or from the control. Use of control inputs is how the protective device receives information about the conditions at the machine, e.g., if there is a change of operating mode. If the protective device is configured appropriately, it will activate a different monitoring case after receiving a new control input.

The control input information must be transmitted reliably. Generally, at least two separate channels are used to do this.

A static control input is a dual-channel control input, which evaluates a signal level as the value 0 or 1 on each channel. The signal states of a static control input give a unique signal pattern. This signal pattern activates a monitoring case.

**Universal I/O**

Universal I/O can be configured as universal input or as universal output.

**Universal input**

A universal input can be used for resetting, external device monitoring (EDM), standby, or restarting the protective device. If standby is activated by a universal input, the standby must not be used for safety-related functions. Universal inputs can also be used in pairs as a static control input.
Universal output

A universal output outputs a signal depending on its configuration, e.g. if the reset pushbutton needs to be pushed or if the optics cover is contaminated. A universal output must not be used for safety functions.

3.2.5 System plug

A system plug is required to operate the safety laser scanner.

In the microScan3 Core I/O, the entire base plate forms the system plug (see figure 4, page 14).

The safety laser scanner’s internal configuration memory is integrated in the system plug. The system plug and all connecting cables can remain at the installation site when the safety laser scanner is replaced. The system plug is detached from the defective safety laser scanner and connected to the new safety laser scanner. The new safety laser scanner reads the configuration from the configuration memory when switching on.

3.2.6 Field types

During operation, the safety laser scanner uses its laser beams continuously to check whether people or objects are present in one or more areas. The areas to be checked are called fields. A distinction is made between the following field types, depending on how the safety laser scanner is used:

- Protective field
- Reference contour field
- Contour detection field
- Warning field

<table>
<thead>
<tr>
<th></th>
<th>Protective field</th>
<th>Reference contour field</th>
<th>Contour detection field</th>
<th>Warning field</th>
</tr>
</thead>
<tbody>
<tr>
<td>Safe switch off (according to EN ISO 13849-1)</td>
<td>Yes (PL d)</td>
<td>Yes (PL d)</td>
<td>Yes (PL d)</td>
<td>No</td>
</tr>
<tr>
<td>Max. sensing range of micro-Scan3</td>
<td>4.0 m or 5.5 m (depends on variant)</td>
<td>4.0 m or 5.5 m (depends on variant)</td>
<td>4.0 m or 5.5 m (depends on variant)</td>
<td>40 m</td>
</tr>
<tr>
<td>Purpose</td>
<td>Detection and protection of people</td>
<td>Tamper protection</td>
<td>e.g. door monitoring</td>
<td>Functional use (no safety-relevant use)</td>
</tr>
</tbody>
</table>

Table 2: Field types and their function

Protective field

The protective field protects the hazardous area of a machine or vehicle. As soon as the electro-sensitive protective device detects an object in the protective field, it switches the associated safety outputs to the OFF state. This signal can be passed to controllers resulting in the dangerous state coming to an end, e.g. to stop the machine or the vehicle.
Reference contour field

The reference contour field monitors a contour of the environment. The safety laser scanner switches all safety outputs to the OFF state if a contour does not match the set parameters, because, for example, the mounting situation of the safety laser scanner were changed.

National and international standards require or recommend that a reference contour is monitored, if the safety laser scanner is used in vertical operation for hazardous point protection or for access protection.

The reference contour field detects unintentional and intentional changes to the position or alignment of the safety laser scanner. Unintentional changes may be caused by vibrations for example. An example of an intentional change is deliberate tampering to disable the safety laser scanner’s functionality.
Contour detection field

The contour detection field monitors a contour of the environment. The safety laser scanner switches the associated safety outputs to the OFF state if a contour does not match the set parameters, because, for example, a door or flap is open.

The contour detection field is used for detecting changes in the environment and only switches the outputs in the current monitoring case. By contrast, the reference contour field is used for detecting changes at the safety laser scanner and switches all safety outputs.

Warning field

The warning field monitors larger areas than the protective field. Simple switching functions can be triggered with the warning field, e.g. a warning light or an acoustic signal can be triggered if a person approaches, even before the person enters the protective field.

The warning field must not be used for safety-relevant tasks.

Figure 8: Warning field, shown in yellow or orange in this document

3.2.7 Field set

A field set consists of one or more fields. The fields in a field set are monitored simultaneously.

A field set can contain various types of field.

A typical application is the use of a protective field with one or more warning fields: if a vehicle approaches a person, a warning field triggers an optical or acoustic signal. If the person does not react to this and the vehicle continues to approach, the safety laser scanner detects an object in the protective field and switches the associated safety outputs to the OFF state. The vehicle stops before it reaches the person.
3.2.8 Monitoring case

A monitoring case signals the machine status to the safety laser scanner. The safety laser scanner activates the field set, which is assigned to the monitoring case and therefore a particular machine status.

If a machine, e.g., has various operational statuses, a monitoring case can be assigned to each operational status. The safety laser scanner receives a defined signal for the current operational status via the control inputs. If there is a change of signal, the safety laser scanner switches from one monitoring case to the monitoring case that is assigned to the new signal (and so to the new operational status). Generally, one field set is assigned to each monitoring case.
3.3 Example applications

Hazardous area protection

In hazardous area protection, people are detected if they stay in a defined area. This type of protective device is suitable for machines, where it is possible to see a hazardous area completely from the reset pushbutton. When the hazardous area is entered, a stop signal is triggered and starting is prevented.

Hazardous point protection

In hazardous point protection, the approach is detected very close to the hazardous point.
The advantage of this type of protective device is that it is possible to have a short minimum distance and the operator can work more ergonomically.

**Figure 13: Hazardous point protection: hand detection**

**Access protection**

In access protection, people are detected if their whole body passes through the protective field.

This type of protective device is used for the protection of access to hazardous areas. When the hazardous area is entered, a stop signal is triggered. A person standing behind the protective device will not be detected by the ESPE.

**Figure 14: Access protection: detection of a person when accessing a hazardous area**
Mobile hazardous area protection

Mobile hazardous area protection is suitable for AGVs (automated guided vehicles), cranes and forklifts, to protect people when vehicles are moving or docking at a fixed station.

The safety laser scanner monitors the area in the direction of travel and stops the vehicle as soon as an object is located in the protective field.

Figure 15: Mobile hazardous area protection: detection of a person when a vehicle approaches
4 Project planning

4.1 Manufacturer of the machine

DANGER

Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

► Use of the safety laser scanner requires a risk assessment. Check whether additional protective measures are required.
► Comply with the applicable national regulations derived from the application (e.g., work safety regulations, safety rules, or other relevant safety guidelines).
► Apart from the procedures described in this document, the components of the safety laser scanner must not be opened.
► The safety laser scanner must not be tampered with or changed.
► Improper repair of the protective device can lead to a loss of the protective function. The protective device must only be repaired by the manufacturer or by someone authorized by the manufacturer.

4.2 Operator of the machine

DANGER

Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

► Changes to the electrical integration of the safety laser scanner in the machine control and changes to the mechanical mounting of the safety laser scanner necessitate a new risk assessment. The results of this risk assessment may require the operator of the machine to meet a manufacturer’s obligations.
► Changes to the device’s configuration may impair the protective function. The effectiveness of the protective device must be checked after any change to the configuration. The person carrying out the change is also responsible for maintaining the protective function of the device.
► Apart from the procedures described in this document, the components of the safety laser scanner must not be opened.
► The safety laser scanner must not be tampered with or changed.
► Improper repair of the protective device can lead to a loss of the protective function. The protective device must only be repaired by the manufacturer or by someone authorized by the manufacturer.

4.3 Assembly

This chapter contains important information about the design.

Information about the individual steps for mounting the device: see "Mounting", page 63.
DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Make sure that the following design requirements are met so that the safety laser scanner can fulfill its protective function.

- The safety laser scanner must be affixed so that people or parts of the body are reliably detected upon entry into the hazardous area.
- The safety laser scanner must be affixed so that no mirrors or other exceedingly reflective objects are in the protective field.
- The safety laser scanner must be affixed so that no small objects (e.g., cables) are in the protective field, even if the safety outputs do not switch to the OFF state as a result.
- The safety laser scanner must be affixed so that no obstacles disrupt the safety laser scanner’s field of view. Take additional protective measures if a risk arises due to unavoidable obstacles.
- If people can stay between the protective device and the hazardous point without being detected, check if additional protective measures (e.g., restart interlock) are required.
- Reaching under, over and around, crawling beneath and stepping over the safety laser scanner, as well as moving it, must be prevented.

Figure 16: Prevent crawling beneath

Figure 17: Prevent stepping over
DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
The optical beam path must not be disrupted, e.g. if the system is incorporated into paneling.

- Do not attach an additional front screen.
- If a viewing slit is required, make sure that its size is sufficient, see "Dimensional drawings", page 141.

NOTE
Certain optical and electromagnetic ambient conditions can affect the safety laser scanner. This may impair the machine's availability. That is to say, the safety laser scanner switches the machine off, although no people are located in the protective field.

Take note of the following for a high level of availability:

- Avoid having strong electric fields in the vicinity of the safety laser scanner. These may be caused by nearby welding or induction cables, for example.
- Prevent condensation forming on the optics cover.

4.3.1 Protection against interference from systems in close proximity to each other

A safety laser scanner can be influenced by the beams from a different laser source in close proximity to it, e.g. by another laser scanner. This may impair the machine's availability. That is to say, the affected safety laser scanner switches the machine off, although no people are situated in the protective field.

You can use the following measures to increase the availability:

- The safety laser scanner has a function for interference protection. The scan cycle time is adjusted in small increments. You can increase the availability by choosing different modes for interference protection in adjacent safety laser scanners, see "Interference protection", page 83.
- Higher multiple sampling reduces the likelihood of a laser source influencing the safety laser scanner. You can increase the availability by setting multiple sampling to the highest value permitted in your application, while taking minimum distances into account, see "Multiple sampling", page 83.
- You can further increase the availability by choosing a suitable mounting method, see "Mounting methods for protection from interference from systems in close proximity", page 153.

You can check the safety laser scanner's beam path using the Scanfinder LS-80L (part no. 6020756).

NOTE
You must comply with the standard ISO 13855 when choosing the mounting method.
4.3.2 Preventing unprotected areas

**DANGER**

Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

Mount the safety laser scanner so that people cannot enter unsecured areas. Take one or more of the measures described below as required:

- Attach deflector plates to prevent anyone standing behind.
- Mount the safety laser scanner in an undercut.
- Mount the safety laser scanner in the paneling of the machine or vehicle.
- Mount a frame to prevent access to the area.

**Unsecured areas behind the safety laser scanner**

Depending on the mounting situation, areas may result, which cannot be detected by the safety laser scanner.

The undetected areas become larger if the safety laser scanner is mounted using a mounting kit.

![Figure 18: Unsecured areas](image)

**Figure 18: Unsecured areas**

1. Length of the unsecured area
2. Width of the unsecured area

**Area where detection capability is restricted**

In close proximity (50 mm wide area in front of the optics cover), the detection capability of the safety laser scanner may be restricted. If required, this area must be secured using an undercut or frame, for example.
Mounting with deflector plates

- Attach the deflector plates ¹ so that it is not possible to step into unsecured areas.
- Attach the deflector plates so that they lie outside the scan plane.

Mounting in an undercut

- Mount the safety laser scanner in an undercut so that no-one can enter the unsecured areas.
- Make the undercut at least deep enough ¹, that it covers the unsecured areas completely and no one can enter the unsecured areas.
- Prevent crawling beneath the undercut. Design the undercut to be so low ², that no one can crawl into it.
Mounting in the machine or vehicle’s paneling

Figure 21: Mounting in vehicle paneling (example)

- If a viewing slit is required, make sure that its size is sufficient, see "Dimensional drawings", page 141.

4.3.3 Response time of the safety laser scanner

The safety laser scanner’s response time must be taken into account, among other things, so that the safety laser scanner can be positioned in a suitable location and the protective fields can be sized correctly.

The response times are specified in the technical data, see "Response times", page 137.

The response time of the safety laser scanner resulting from current settings is shown in Safety Designer.

4.3.4 Reference contour monitoring

Reference contour field

The reference contour field monitors a contour of the environment. The safety laser scanner switches all safety outputs to the OFF state if a contour does not match the set parameters, because, for example, the mounting situation of the safety laser scanner were changed.

National and international standards require or recommend that a reference contour is monitored, if the safety laser scanner is used in vertical operation for hazardous point protection or for access protection.

The reference contour field detects unintentional and intentional changes to the position or alignment of the safety laser scanner. Unintentional changes may be caused by vibrations for example. An example of an intentional change is deliberate tampering to disable the safety laser scanner’s functionality.

Vertical operation

National and international standards require or recommend that a reference contour is monitored, if the angle between access direction and scan plane exceeds +30°.
DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Use a contour from the environment as a reference to protect the protective device from inadvertent adjustment or tampering.

Configuring the reference contour field during vertical operation

Note the following points in particular when configuring the reference contour field:

- In many cases, it makes sense to use lateral vertical passage boundaries (e.g. door frames) and the floor as a reference.
- The reference contour field has a tolerance band, which can be set, around the contour. If the safety laser scanner does not detect the contour within the tolerance band, all safety outputs switch to the OFF state.
  - For high availability, it is recommended to set the tolerance band to 65 mm positive tolerance (far) and 65 mm negative tolerance (near).
  - Make sure that the tolerance band is not too wide. The reference contour field must detect a change in the position or alignment of the safety laser scanner before a dangerous gap is created between the protective field and mechanical limit.
- The following requirements apply to the protective field with respect to the reference contour field:
  - Access protection:
    - If the reference contour represents the edge of the protected opening, the distance between the edge of the protected opening and the protective field must be no more than 100 mm wide. A distance of 65 mm is recommended for high availability and sufficient protection.
    - If the reference contour does not represent the edge of the protected opening, the protective field must be larger than the protected opening. The required overrun (o) is calculated using the same formula as for hazardous point protection.
  - Hazardous point protection: the protective field must be larger than the protected opening. The required overrun (o) is calculated using the following formula:
    \[ o \geq 130 \text{ mm} - d \]
    where:
    - \( o \) = overrun of the protective field over the opening
    - \( d \) = set resolution
- You can define a number of contours in the reference contour field and so monitor various areas in the environment.
Figure 22: Tolerance band of the reference contour field (protective field within the protected opening, edge of the protected opening = reference contour)

1. TZ = tolerance band of the reference contour field
2. Distance of the protective field from the contour, to ensure availability

Figure 23: Overrun of the protective field in front of an opening

1. TZ = tolerance band of the reference contour field
2. Distance of the protective field from the contour, to ensure availability
3. \( \alpha \) = overrun of the protective field over the opening

4.3.5 Monitoring case switching time

When switching between monitoring cases, it is possible that a person may already be in the newly activated protective field when switching takes place. Only switching in time (namely before the danger arises for the person at this location) ensures protection.
DANGER
Hazard due to lack of effectiveness of the protective device

Switching of the monitoring case should be timed so that the safety laser scanner detects a person in the protective field with a sufficient minimum distance, before the dangerous state occurs.

DANGER
Hazard due to lack of effectiveness of the protective device

Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.

In addition to the parameters considered below, the switching signal’s propagation delay time up to the protective device also influences the switching duration. This includes the controls processing time, for example.

Take account of the switching signal’s propagation delay time up to the protective device.

In some cases, the process of switching between monitoring cases takes so long that the new monitoring case is not available inside the response time provided. This means that it may not be possible to detect a person in the protective field in time. In cases like this, you must start switching between monitoring cases earlier.

The following parameters influence the duration of the process:

- The set input delay (see "Input delay", page 97).
- The processing time for the chosen input.

You calculate when to switch between monitoring cases as follows

1. First calculate how long it takes to switch between monitoring cases:
   \[ t_{CSR} = t_{ID} + t_i \]
   where:
   - \( t_{CSR} \) = time required for switching between monitoring cases in milliseconds (ms)
   - \( t_{ID} \) = input delay for the control inputs in milliseconds (ms)
   - \( t_i \) = processing time for the chosen input in milliseconds (ms) (local static control input: \( t_i = 12 \text{ ms} \))

2. Then calculate how much time is available in the response time for switching between monitoring cases:
   \[ t_{CSA} = (n - 1) \times t_S \]
   where:
   - \( t_{CSA} \) = time available for switching between monitoring cases in milliseconds (ms)
   - \( n \) = set multiple sampling (default: \( n = 2 \))
   - \( t_S \) = scan cycle time (poss. incl. supplement due to interference protection) in milliseconds (ms)

3. Then check whether there is enough time available for switching between monitoring cases:
   - If \( t_{CSA} \geq t_{CSR} \), earlier start is not necessary.
   - If \( t_{CSA} < t_{CSR} \), you must start switching between monitoring cases earlier. The time advance \( t_{CSP} \) required is: \( t_{CSP} = t_{CSR} - t_{CSA} \)
NOTE
In some cases, it is not possible to define when to switch (for example because processing times of the machine vary) or the time advance means that the monitoring of an area finishes too early. Follow one of the following recommendations in these cases:

- Allow the two protective fields to partially overlap.
- Temporarily monitor both hazardous areas simultaneously.

4.3.6 Hazardous area protection

The safety laser scanner is mounted with a horizontal scan plane in a stationary application, for example on a machine where the hazardous area is not completely surrounded by a physical guard. During hazardous area protection, the safety laser scanner detects a person’s legs. The protective field is parallel to the person’s direction of approach.

![Stationary application with horizontal scan plane for hazardous area protection](image)

**Figure 24: Stationary application with horizontal scan plane for hazardous area protection**

NOTE
Mark the outline of the protective field boundaries on the floor after you have worked out the protective field size. By doing this, you allow machine operators to see the protective field boundaries and make it easier to thoroughly check the protective function at a later date.

**Protective field**

The protective field must be designed so that it detects a person at a minimum distance from the hazardous point. This distance is required to prevent a person or part of their body from reaching the hazardous area before the end of the machine’s dangerous state.

In hazardous area protection, the minimum distance typically defines the protective field size required.

If you define a number of monitoring cases with different protective fields, you must calculate the protective field size separately for each protective field used.

In many cases, a resolution of 50 mm or 70 mm is suitable for hazardous area protection.
DANGER
Hazard due to lack of effectiveness of the protective device
In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.
1. Calculate the required minimum distance for your machine using the following formulas and examples.
2. Take this calculation and the specifications in these instructions into account when mounting the safety laser scanner.
3. Take this calculation and the specifications in these instructions into account when configuring the safety laser scanner.

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
Body parts to be protected may not be detected under coarse resolution.
- Use a resolution of 70 mm or finer for hazardous area protection.
- For hazardous area protection with a resolution of 70 mm: make sure that it is possible to detect a human leg.
- For hazardous area protection with a resolution of 70 mm: mount the safety laser scanner at a height of at least 300 mm (height of the scan plane).
- If it is not possible to mount the safety laser scanner at a height of at least 300 mm, use a resolution of 50 mm.

NOTE
If the protective field needs to be as small as possible, you may have to calculate the minimum distance multiple times with different scan cycle times (iterative calculation) because of various dependencies. ¹)
Always take the actual response time into account when calculating the minimum distance, see "Response times", page 137.
1. First calculate the minimum distance on the basis of the response time for a scan cycle time of 30 ms.
2. If the calculated minimum distance is larger than the resulting protective field range (see "Protective field range", page 139), recalculate the minimum distance on the basis of the response time for a scan cycle time of 40 ms.

Calculating minimum distance
The calculation of the minimum distance is based on international and national standards and statutory requirements applicable at the place of installation of the machine.
If the minimum distance is calculated according to ISO 13855, then it depends on the following points:
- Machine stopping time (time interval between triggering the sensor function and the end of the machine’s dangerous state)
- Response time of the protective device, see "Response times", page 137
- Reach or approach speed of the person
- Resolution (detection capability) of the safety laser scanner
- Type of approach: parallel
- Parameters specified based on the application
- Supplements for general and, possibly, reflection-based measurement errors

¹) The required minimum distance depends on the response time, among other things, and therefore on the scan cycle time. The protective field range likewise depends on the scan cycle time: the protective field range is shorter for a faster scan cycle time.
• Supplement to protect against reaching over
• Height of the scan plane
• Switching time between monitoring cases

NOTE
More information is available in the ISO 13855 standard and in the Guide for Safe Machinery.

NOTE
SICK offers a stopping/run-down time measurement service in many countries.

**Calculation example of the minimum distance S according to ISO 13855**

The example shows the calculation of the minimum distance for parallel approach to the protective field. Depending on the application and the ambient conditions a different calculation may be required. (e.g., a protective field or at an arbitrary angle to the direction of approach or an indirect approach)

Calculate S using the following formula:

\[ S = 1600 \text{ mm/s} \times T + 65 \text{ mm} + Z_R + C \]

where:

- **S** = minimum distance in millimeters (mm)
- **T** = stopping/run-down time for the entire system in seconds (s)
  (Response time of the safety laser scanner + machine’s stopping/run-down time, incl. response time of the machine’s control system)
- **Z_R** = supplement for reflection-based measurement errors in millimeters (mm)
- **C** = supplement to protect against reaching over in millimeters (mm)

The reach/approach speed is already included in the formula.

**Supplement Z_R for reflection-based measurement errors**

If there is a retroreflector in the vicinity of the protective device (distance of the retroreflector from protective field ≤ 6 m), you must take the supplement \( Z_R = 350 \text{ mm} \) into account.

**Supplement C to protect against reaching over**

Under certain circumstances, a person can reach the hazardous area by reaching over, before the protective device stops the dangerous state. Supplement C prevents this.
The necessary supplement to the minimum distance depends on the height of the protective field’s scan plane. The supplement is larger if the safety laser scanner is affixed low-down than if it is affixed high-up.

**Calculating the supplement C**

- If you have sufficient free space in front of your machine, use value 1200 mm as the supplement C.
- If you want to keep the minimum distance as low as possible, use the following formula to calculate C:
  \[ C = 1200 \text{ mm} - (0.4 \times H_D) \]
  where:
  - \( H_D = \) height of the protective field above the floor in millimeters (mm).
✓ If the result is $C \geq 850$ mm, then use the calculated value as supplement $C$.
✓ If the result is $C < 850$ mm, then use $C = 850$ mm (this value corresponds to an arm's length and is valid as a minimum supplement to protect against reaching over).

**Height of the scan plane**

**DANGER**
Hazard due to lack of effectiveness of the protective device
It is possible to get around the protective device by crawling beneath.

- Prevent people from being able to crawl beneath the protective field by mounting the safety laser scanner appropriately.
- If you mount the protective device higher than 300 mm, you must use additional measures to prevent crawling beneath.

If you choose a resolution of 70 mm for hazardous area protection, it is not possible under certain circumstances to detect a human leg. This is because a beam does not hit the leg. Rather, the beams pass by the sides of the ankle (see figure 27, page 38). If you mount the safety laser scanner at a height of at least 300 mm (height of the scan plane), the scan plane is at calf height and the leg is even detected at a resolution of 70 mm (see figure 28, page 38).

**DANGER**
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
Body parts to be protected may not be detected under coarse resolution.

- Use a resolution of 70 mm or finer for hazardous area protection.
- For hazardous area protection with a resolution of 70 mm: make sure that it is possible to detect a human leg.
- For hazardous area protection with a resolution of 70 mm: mount the safety laser scanner at a height of at least 300 mm (height of the scan plane).
- If it is not possible to mount the safety laser scanner at a height of at least 300 mm, use a resolution of 50 mm.
If the height of the protective field (scan plane) is predefined and is less than 300 mm, you can calculate the required resolution using the following formula:

\[ d_r = \frac{H_D}{15} + 50 \text{ mm} \]

where:

- \( d_r \) = coarsest permissible resolution of the safety laser scanner in millimeters (mm)
- \( H_D \) = height of the protective field above the floor in millimeters (mm)

The safety laser scanner’s resolution can be set to the predefined value \( d \). If the result \( d_r \) does not match any of these values, choose a finer resolution (\( d \leq d_r \)).
Distance from walls

The availability may be impaired if the protective field stretches as far as a wall or a different object. So, plan to have a space between the protective field and the object. A space of approx. 65 mm is recommended to ensure availability.

Figure 29: Distance of the protective field from the wall

1 Recommended distance of the protective field from the wall.

4.3.7 Hazardous point protection

The safety laser scanner is mounted with a vertical scan plane in a stationary application, for example on a machine where the operator must stay close to the hazardous point. A fixed barrier with a height of at least 1200 mm is located in front of the hazardous point. The operator can reach over the barrier and through the scan plane into the hazardous point. But the operator cannot climb over the barrier. If there is no such barrier available, access protection may be required.

During hazardous point protection, the safety laser scanner detects a person’s hand or other part of their body. The protective field is orthogonal to the direction of approach of the body part. A resolution of 40 mm or finer is required to ensure detection of the hand during hazardous point protection.
Figure 30: Stationary application in vertical operation for hazardous point protection

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Never use the safety laser scanner for applications in which finger detection has to be realized. The safety laser scanner is not suitable for finger detection, because the finest resolution is 30 mm.
- Use the contour of the environment as a reference to protect the protective device from inadvertent adjustment or tampering (see “Reference contour monitoring”, page 29).

DANGER
Hazard due to lack of effectiveness of the protective device
If there is a retroreflector in the protective field level (distance of the retroreflector from protective field ≤ 6 m), it may not be possible or it may not be possible in time to detect people and parts of the body that are to be protected.

- Avoid retroreflectors in the protective field level if possible.
- If there is a retroreflector in the protective field level (distance of the retroreflector from protective field ≤ 6 m), the overrun of the protective field over the opening to be protected must be increased by the supplement $Z_R = 350$ mm.

Protective field
The protective field must be designed so that it detects access by a person at a minimum distance from the hazardous point. This distance is required to prevent a person or part of their body from reaching the hazardous area before the end of the machine’s dangerous state.

In hazardous area protection, the minimum distance typically defines the position at which the safety laser scanner is mounted.

In many cases, a resolution of 30 mm or 40 mm is suitable for hazardous point protection.
DANGER
Hazard due to lack of effectiveness of the protective device
In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

1. Calculate the required minimum distance for your machine using the following formulas and examples.
2. Take this calculation and the specifications in these instructions into account when mounting the safety laser scanner.
3. Take this calculation and the specifications in these instructions into account when configuring the safety laser scanner.

DANGER
Hazard due to lack of effectiveness of the protective device
Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.

- Always mount the safety laser scanner so that it is impossible to reach around or behind.
- Provide suitable additional measures if necessary.

NOTE
The required minimum distance depends on the safety laser scanner's set resolution. Take account of the following notes when choosing the resolution:

- If you choose a fine resolution, the protective field range is smaller and so the protective field is only suitable for smaller hazardous points. But the required minimum distance is smaller, so you can mount the safety laser scanner closer to the hazardous point.
- If you choose a coarser resolution, the protective field range is larger and so the protective field is also suitable for larger hazardous points. But the required minimum distance is larger, so you must mount the safety laser scanner further away from the hazardous point.

Calculating minimum distance
The calculation of the minimum distance is based on international and national standards and statutory requirements applicable at the place of installation of the machine.

If the minimum distance is calculated according to ISO 13855, then it depends on the following points:

- Machine stopping time (time interval between triggering the sensor function and the end of the machine’s dangerous state)
- Response time of the protective device, see "Response times", page 137
- Reach or approach speed of the person
- Resolution (detection capability) of the safety laser scanner
- Type of approach: orthogonal
- Parameters specified based on the application

NOTE
More information is available in the ISO 13855 standard and in the Guide for Safe Machinery.

NOTE
SICK offers a stopping/run-down time measurement service in many countries.
Calculation example of the minimum distance $S$ according to ISO 13855

The example shows the calculation of the minimum distance for an orthogonal approach to the protective field. A different calculation may be required depending on the application and the ambient conditions (for example, for a protective field parallel to or at any angle to the direction of approach or an indirect approach).

First, calculate $S$ using the following formula:

$$S = 2000 \text{ mm/s} \times T + 8 \times (d - 14 \text{ mm})$$

where:
- $S =$ minimum distance in millimeters (mm)
- $T =$ stopping/run-down time for the entire system in seconds (s)
  (Response time of the safety laser scanner + machine’s stopping/run-down time, incl. response time of the machine’s control system)
- $d =$ resolution of the safety laser scanner in millimeters (mm)

The reach/approach speed is already included in the formula.

✓ If the result $S$ is $\leq 100$ mm, use $S = 100$ mm.
✓ If the result $100 \text{ mm} < S \leq 500$ mm, use the calculated value as the minimum distance.

✓ If the result is $S > 500$ mm, you may be able to reduce the minimum distance using the following calculation:

$$S = 1600 \text{ mm/s} \times T + 8 \times (d - 14 \text{ mm})$$

✓ If the new value is $S > 500$ mm, use the newly calculated value as the minimum distance.
✓ If the new value $S$ is $\leq 500$ mm, then use $500$ mm as the minimum distance.

### 4.3.8 Access protection

The safety laser scanner is mounted with a vertical scan plane in a stationary application, for example on a machine, for which access to the hazardous area may be defined structurally. For access protection, the safety laser scanner detects an intrusion by a whole body. The protective field is orthogonal to the person’s direction of approach.

![Figure 31: Stationary application in vertical operation for access protection](image-url)
DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-
observance.

- Use a resolution of 200 mm or finer. Otherwise, protection will not be ensured dur‐
ing access protection.
- Use double sampling during access protection. Under certain circumstances, a
  person could pass through the protective field without being detected when using
  higher multiple sampling.
- Use the contour of the environment as a reference to protect the protective device
  from inadvertent adjustment or tampering (see “Reference contour monitoring”,
  page 29).

DANGER
Hazard due to lack of effectiveness of the protective device
If there is a retroreflector in the protective field level (distance of the retroreflector from
protective field ≤ 6 m), it may not be possible or it may not be possible in time to detect
people and parts of the body that are to be protected.

- Avoid retroreflectors in the protective field level if possible.
- If there is a retroreflector in the protective field level (distance of the retroreflector
  from protective field ≤6 m), the overrun of the protective field over the opening to
  be protected must be increased by the supplement $Z_R = 350$ mm.

Protective field
The protective field must be designed so that it detects a person at a minimum dis‐
tance from the hazardous point. This distance is required to prevent a person or part of
their body from reaching the hazardous area before the end of the machine’s danger‐
ous state.

In access protection, the minimum distance typically defines the position at which the
safety laser scanner is mounted.

The protective field must be at least 900 mm high, so that it is not possible to climb
over it.

DANGER
Hazard due to lack of effectiveness of the protective device
In the case of non-compliance, it is possible that the dangerous state of the machine
may not be stopped or not stopped in a timely manner.

1. Calculate the required minimum distance for your machine using the following for‐
mulas and examples.
2. Take this calculation and the specifications in these instructions into account
   when mounting the safety laser scanner.
3. Take this calculation and the specifications in these instructions into account
   when configuring the safety laser scanner.

Calculating minimum distance
The calculation of the minimum distance is based on international and national stand‐
ards and statutory requirements applicable at the place of installation of the machine.

If the minimum distance is calculated according to ISO 13855, then it depends on the
following points:
- Machine stopping time (time interval between triggering the sensor function and the end of the machine’s dangerous state)
- Response time of the protective device, see "Response times", page 137
- Reach or approach speed of the person
- Resolution (detection capability) of the safety laser scanner
- Type of approach: orthogonal
- Parameters specified based on the application
- Supplement to prevent reaching through

NOTE
More information is available in the ISO 13855 standard and in the Guide for Safe Machinery.

NOTE
SICK offers a stopping/run-down time measurement service in many countries.

Calculation example of the minimum distance $S$ according to ISO 13855

The example shows the calculation of the minimum distance for an orthogonal approach to the protective field. A different calculation may be required depending on the application and the ambient conditions (for example, for a protective field parallel to or at any angle to the direction of approach or an indirect approach).

$S = 1600 \text{ mm/s} \times T + 850 \text{ mm}$

where:
- $S = \text{minimum distance in millimeters (mm)}$
- $T = \text{stopping/run-down time for the entire system in seconds (s)}$

(Response time of the safety laser scanner + machine’s stopping/run-down time, incl. response time of the machine’s control system)

The approach speed is already included in the formula.

4.3.9 Mobile hazardous area protection

The safety laser scanner is mounted with a horizontal scan plane in a mobile application, for example on an automated guided vehicle. In mobile hazardous area protection, the safety laser scanner protects the hazardous area created by the vehicle’s movement. The safety laser scanner detects a person’s legs. The protective field is parallel to the direction of approach.
NOTE

- In a mobile application, a resolution of 70 mm (leg detection) is sufficient for detecting people. By contrast with stationary hazardous point protection, this is also true for a low mounting height, as the safety laser scanner moves together with the vehicle.
- In the following calculations, only the vehicle speed is taken into account, not the speed of a walking person. This is based on the assumption that the person recognizes the danger and stands still.

Protective field length

The protective field must be designed so that it detects a person at a minimum distance from the hazardous point. This distance is required to ensure that the vehicle comes to a stop before it reaches a person or an object.

In mobile hazardous area protection, the minimum distance typically defines the protective field length required. When calculating the protective field length, the impact of turning must be considered separately.

DANGER

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

1. Calculate the required minimum distance for your machine using the following formulas and examples.
2. Take this calculation and the specifications in these instructions into account when mounting the safety laser scanner.
3. Take this calculation and the specifications in these instructions into account when configuring the safety laser scanner.

If you define a number of monitoring cases with different protective fields, you must calculate the protective field size separately for each protective field used.
Calculation example for the protective field length $S_L$ according to ISO 13855

- Calculate the required protective field length $S_L$ using the formula:
  \[ S_L = S_A + 65 \text{ mm} + Z_R + Z_F + Z_B \]
  where:
  - $S_L$ = protective field length in millimeters (mm)
  - $S_A$ = stopping distance in millimeters (mm)
  - $Z_R$ = supplement for reflection-based measurement errors in millimeters (mm)
  - $Z_F$ = supplement for lack of ground clearance of the vehicle in millimeters (mm)
  - $Z_B$ = supplement for the decreasing braking force of the vehicle, from the vehicle documentation, in millimeters (mm)

Stopping distance $S_A$

The stopping distance comprises the vehicle’s braking distance and the distance covered during the safety laser scanner’s response time and the vehicle control’s response time.

**NOTE**

Please note that a vehicle’s braking distance does not increase linearly with increasing speed, but rather in a squared relationship.

![Diagram](image)

*Figure 33: Stopping distance as a function of the vehicle’s speed*

$v$ \quad speed

$S_A$ \quad stopping distance

$Z$ \quad supplements

$S_L$ \quad protective field length for the relevant range of speeds

- Calculate the stopping distance using the formula:
  \[ S_A = S_{Br} + S_{AnF} + S_{AnS} \]
  where:
  - $S_A$ = stopping distance in millimeters (mm)
  - $S_{Br}$ = braking distance, from the vehicle documentation, in millimeters (mm)
  - $S_{AnF}$ = distance covered during the vehicle control’s response time, from the vehicle documentation, in millimeters (mm)
$S_{AnS}$ = distance covered during the safety laser scanner’s response time in millimeters (mm)

The distance $S_{AnS}$ depends on the safety laser scanner’s response time and the vehicle’s speed. The distance $S_{AnS}$ is calculated using the following formula:

$$S_{AnS} = t_R \times V_{\text{max}}$$

where:

- $t_R$ = safety laser scanner’s response time in seconds (s) (see "Response times", page 137)
- $V_{\text{max}}$ = maximum speed of the vehicle, from the vehicle documentation, in millimeters per second (mm/s) (If you define a number of monitoring cases with different protective fields: $V_{\text{max}}$ = maximum speed of the vehicle in the current monitoring case)

**Supplement $Z_R$ for reflection-based measurement errors**

If there is a retroreflector in the vicinity of the protective device (distance of the retroreflector from protective field $\leq$ 6 m), you must take the supplement $Z_R = 350$ mm into account.

**Supplement $Z_F$ for lack of ground clearance**

This supplement is necessary, because, generally, a person is detected above the foot and so the braking process cannot take account of the length of the foot in front of the point of detection. A person’s foot could be injured if a vehicle has no ground clearance.

![Diagram of Supplement ZF for lack of ground clearance](image)

$B_F$ = ground clearance

$S_L$ = protective field length without a supplement for lack of ground clearance

$Z_F$ = supplement for lack of ground clearance

The flat-rate supplement for a ground clearance below 120 mm is 150 mm. This supplement may be reduced further in individual cases. Read the supplement actually required for your vehicle’s ground clearance from the following graph.
Figure 35: Minimum supplement for lack of ground clearance

**Protective field range**

The protective field must be wide enough to cover the width of the loaded vehicle with supplements for measurement error and the lack of ground clearance. When calculating the protective field width, the impact of turning must be considered separately.

**Calculation example for the protective field width $S_W$ according to ISO 13855**

- Calculate the required protective field width $S_B$ using the formula:
  \[ S_B = F_B + 2 \times (65 \text{ mm} + Z_R + Z_F) \]
  where:
  - $S_B = \text{protective field width in millimeters (mm)}$
  - $F_B = \text{vehicle width in millimeters (mm)}$
  - $Z_R = \text{supplement for reflection-based measurement errors in millimeters (mm)}$
  - $Z_F = \text{supplement for lack of ground clearance of the vehicle in millimeters (mm)}$

**NOTE**

In many cases, the safety laser scanner is mounted in the center of the vehicle. If this is not the case, you must define the protective field asymmetrically. Make sure that the supplements are located on the right and left of the vehicle.

**Supplement $Z_R$ for reflection-based measurement errors**

If there is a retroreflector in the vicinity of the protective device (distance of the retroreflector from protective field ≤ 6 m), you must take the supplement $Z_R = 350 \text{ mm}$ into account.
Supplement ZF for lack of ground clearance

This supplement is necessary, because, generally, a person is detected above the foot and so the braking process cannot take account of the length of the foot in front of the point of detection. A person’s foot could be injured if a vehicle has no ground clearance, see "Supplement ZF for lack of ground clearance", page 47.

Height of the scan plane

DANGER
Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Mount the safety laser scanner so that the maximum scan plane height is 200 mm.

People who are lying down are reliably detected if the scan plane is at a height of no more than 200 mm.

In many cases, a mounting height of 150 mm above the floor (height of the scan plane) is suitable.

Figure 36: Recommended fitting height
4.4 Integration in the electrical control

This chapter contains important information about integration in the electrical control. Information about the individual steps for electrical installation of the device: see "Electrical installation", page 69.

Information regarding pin assignment and pin configuration options: see "Pin assignment", page 71.

Requirements for use

The output signals of the protective device must be evaluated by downstream controllers such that the dangerous state of the machine can be reliably brought to an end. Depending on the safety concept, the signals are evaluated either with a safety relay or a safety controller, for example.

DANGER

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

Make sure that the following control and electrical requirements are met so the safety laser scanner can fulfill its protective function.

- It must be possible to electrically influence the control of the machine.
- Use the same earthing method for all devices that are electrically connected to the safety laser scanner.
- Power must be supplied in accordance with SELV/PELV (IEC 60204-1) for all devices that are electrically connected to the safety laser scanner.
- All devices that are electrically connected to the safety laser scanner must be supplied by the same power source.
- The control that is connected and all devices responsible for safety must comply with the required performance level and the required category (for example according to ISO 13849-1).
• When using a safety controller, different signal levels of both OSSDs in an OSSD pair must be detected depending on applicable national regulations or required reliability of the safety function. The maximum discrepancy time tolerated by the control must be selected according to the application.

• A restart interlock must be implemented depending on applicable national regulations or required reliability of the safety function. Each OSSD pair in the safety laser scanner is equipped with a configurable internal restart interlock. For safety laser scanners which do not have OSSDs, if a restart interlock is required, it must be provided in the external control.

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

Downstream contactors must be positively guided and monitored depending on applicable national regulations or required reliability of the safety function.

- Make sure that downstream contactors are monitored (external device monitoring, EDM).

---

• Each OSSD pair in the safety laser scanner is equipped with a configurable internal EDM.

The safety laser scanner complies with the regulations for electromagnetic compatibility (EMC) for the industrial sector (Radio Safety Class A).

### 4.4.1 Power supply

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

- Make sure that the following control and electrical requirements are met so the safety laser scanner can fulfill its protective function.

---

• The safety laser scanner’s external power supply must be capable of bridging a brief power failure of 20 ms, as per IEC 60204-1.

• The safety laser scanner requires a supply voltage of 24 V. Details about tolerances and further connected loads, see "Data sheet", page 132.

• The power supply must provide safe isolation according to IEC 61140 (SELV/PELV as per IEC 60204-1). Suitable power supplies are available as accessories from SICK, see "Connection technology", page 146.

• Make sure that the safety laser scanner is provided with appropriate electrical fuse protection. Electrical data for calculating what fuse is required, see "Data sheet", page 132.

• Use the same earthing method for all devices that are electrically connected to the safety laser scanner.

• Power must be supplied in accordance with SELV/PELV (IEC 60204-1) for all devices that are electrically connected to the safety laser scanner.

• All devices that are electrically connected to the safety laser scanner must be supplied by the same power source.
4.4.2 USB connection

The safety laser scanner has a USB connection for configuration and diagnostics. The USB connection complies with the USB 2.0 mini-B standard (female connector). The USB connection may only be used temporarily and only for configuration and diagnostics. More information: see "Configuration", page 73 and see “Troubleshooting”, page 121.

4.4.3 OSSDs

Safety laser scanners with local inputs and outputs can be directly integrated into the machine controller.

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

- Make sure that the following control and electrical requirements are met so the safety laser scanner can fulfill its protective function.

- A restart interlock must be implemented depending on applicable national regulations or required reliability of the safety function. Each OSSD pair in the safety laser scanner is equipped with an internal restart interlock.
- When using a safe control, different signal levels of both OSSDs in an OSSD pair must be detected depending on applicable national regulations or required reliability of the safety function. The maximum discrepancy time tolerated by the control must be selected according to the application.
- The output signals from an OSSD pair must not be connected to each other.
- In the machine controller, both signals from an OSSD pair must be processed separately.

*Figure 38: Dual-channel and isolated connection of OSSD1 and OSSD2*

- The machine must switch to the safe state if, at any time, at least one OSSD in an OSSD pair switches to the OFF state.
• Prevent the formation of a potential difference between the load and the protective device. If you connect loads to the OSSDs (safety outputs) that then also switch if controlled with negative voltage (e.g., electro-mechanical contactor without reverse polarity protection diode), you must connect the 0 V connections of these loads and those of the corresponding protective device individually and directly to the same 0 V terminal strip. In the event of a fault, this is the only way to ensure that there can be no potential difference between the 0 V connections of the loads and those of the corresponding protective device.

![Diagram](image)

*Figure 39: No potential difference between load and protective device*

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

Downstream contactors must be positively guided and monitored depending on applicable national regulations or required reliability of the safety function.

- Make sure that downstream contactors are monitored (external device monitoring, EDM).

---

• Each OSSD pair in the safety laser scanner is equipped with an internal EDM.

**Requirements for the electrical control of the machine**

The OSSDs are short-circuit protected to 24 V DC and 0 V. When the protective field is clear, the OSSDs signal the ON state with the HIGH signal level (non-isolated). If there are objects in the protective field or there is a device fault, the OSSDs signal the OFF state with the LOW signal level.

**4.4.4 Control inputs**

The safety laser scanner is equipped with control inputs.

It is possible during continuous operation to switch between various monitoring cases of the safety laser scanner via the control inputs.

Static control inputs are used for information about machine status.

When switching between monitoring cases, bear in mind that a person may already be in the protective field when switching takes place. So, you must make sure that the monitoring case is switched at the right time. Only switching in time (namely before the danger arises for the person at this location) ensures protection, see "Monitoring case switching time", page 31.
DANGER
Hazard due to lack of effectiveness of the protective device
The dangerous state may not be stopped in the event of non-compliance.
The same safety level is required for safety-related parts of the control, which switch the active protective field, as for the safety function. In many cases, this is PL d as per EN ISO 13849-1 oder SIL2 as per IEC 62061.

- Position-dependent switching must be carried out by two independently wired signal sources, such as two independent position switches.
- Manual switching that depends on the operating mode must be carried out using a suitable manual control switch.
- Use the same earthing method for all devices that are electrically connected to the safety laser scanner.
- Power must be supplied in accordance with SELV/PELV (IEC 60204-1) for all devices that are electrically connected to the safety laser scanner.
- All devices that are electrically connected to the safety laser scanner must be supplied by the same power source.

Information about electrical properties: see "Data sheet", page 132
Information about pin assignment: see "Electrical installation", page 69
Information about the configuration of the control inputs see "Inputs and outputs, local", page 93

4.4.4.1 Static control inputs

The static control input supports the following analysis method:

- Complementary analysis

You can define the switching criteria for the monitoring cases (see "Monitoring cases", page 96).

Complementary analysis

A static control input consists of two connections. To switch correctly, one connection must be switched inversely to the other. The following table shows which level must be applied at the static control input’s connections to define the logical input status 1 and 0 at the relevant control input.

<table>
<thead>
<tr>
<th>A1</th>
<th>A2</th>
<th>Logical input status (input A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>Fault</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>Fault</td>
</tr>
</tbody>
</table>

Table 3: Level at the control input’s connections during complementary analysis

4.4.5 Universal inputs, universal outputs, universal I/Os

The safety laser scanner is equipped with universal I/Os.
Universal I/O can be configured as universal input or as universal output.

A universal input can be used for resetting, external device monitoring (EDM), standby, or restarting the protective device. If standby is activated by a universal input, the standby must not be used for safety-related functions. Universal inputs can also be used in pairs as a static control input.
A universal output outputs a signal depending on its configuration, e.g. if the reset pushbutton needs to be pushed or if the optics cover is contaminated. A universal output must not be used for safety functions.

- Use the same earthing method for all devices that are electrically connected to the safety laser scanner.
- Power must be supplied in accordance with SELV/PELV (IEC 60204-1) for all devices that are electrically connected to the safety laser scanner.
- All devices that are electrically connected to the safety laser scanner must be supplied by the same power source.

Information about electrical properties: see "Technical data", page 132
Information about pin assignment: see "Electrical installation", page 69

### 4.4.6 Restart interlock

A restart interlock must be implemented depending on applicable national regulations or required reliability of the safety function.

The restart interlock prevents the machine from starting automatically, e.g., once an ESPE has been triggered during machine operation or once the operating mode of the machine has been changed.

First, the operator must press a reset pushbutton to return the protective device to monitoring status. Then, in a second step, the operator can restart the machine.

Depending on applicable national regulations, a restart interlock must be available if it is possible to stand behind the protective field.

**Reset**

The reset brings the protective device back to the monitoring state after it has sent a stop command. The reset also quits the start-up or restart interlock of a protective device, so that the machine can be restarted in a second step.

The reset must only be possible, when all safety functions and protective devices are functional.

The reset of the protective device must not introduce any movement or dangerous situations itself. The machine is only permitted to start after the reset once a separate start command has been sent.

- Manual resets are performed using a separate, manually operated device, such as a reset pushbutton.
- Automatic resets by the protective device are only permitted in special cases, if one of the following conditions is met:
  - It must not be possible for people to be in the hazardous area without triggering the protective device.
  - It must be ensured that no people are in the hazardous area during or after the reset.

**Internal restart interlock**

Each OSSD pair in the safety laser scanner is equipped with a configurable internal restart interlock. For safety laser scanners which do not have OSSDs, if a restart interlock is required, it must be provided in the external control.

When the internal restart interlock is used, the following sequence is the result for the machine operator:
1. An OSSD pair of the safety laser scanner switches to the OFF state if there is an interruption in the protective field.
2. The OSSD pair remains in the OFF state when there is no longer an object in the protective field.
3. The OSSD pair only switches back to the ON state when the operator presses the reset pushbutton, which is outside the hazardous area. If there is an object in the protective field when the reset pushbutton is pressed, the OSSD pair stays in the OFF state.
4. After the reset, the operator can restart the machine in a second step.

Figure 40: How the restart interlock works (1): no one in protective field, machine operates

Figure 41: How the restart interlock works (2): person detected in protective field, OSSDs in OFF state
Figure 42: How the restart interlock works (3): person in hazardous area, no detection in protective field, OSSDs still in OFF state

Figure 43: How the restart interlock works (4): the reset pushbutton must be pressed before restarting the machine.

**DANGER**

Hazard due to unexpected starting of the machine

- Affix the control switch for resetting the restart interlock outside the hazardous area.
- Make sure that the control switch cannot be activated by a person who is in the hazardous area.
- Also make sure that the person activating the control switch has a complete view of the hazardous area.
4.4.7 External device monitoring (EDM)

Verification of the external switching elements (external device monitoring, EDM) must be implemented depending on applicable national regulations or required reliability of the safety function.

The external device monitoring (EDM) monitors the status of downstream contactors. In order to use the external device monitoring, positively guided contactors must be used to switch off the machine. If the auxiliary contacts of the positively guided contactors are connected to the external device monitoring, the external device monitoring checks whether the contactors drop off when the OSSDs are switched off.

**NOTE**

Each OSSD pair in the safety laser scanner is equipped with a configurable internal EDM.

4.4.8 Connection diagrams

Restart interlock and external device monitoring (EDM)

The safety laser scanner can be connected directly to relays/contactors. It is operated with restart interlock and external device monitoring.

+24 V DC

**Figure 44:** Connection diagram with restart interlock and external device monitoring (EDM)

Uni-I/O 1 configured as input reset
Uni-I/O 2 configured as input external device monitoring (EDM)
Uni-I/O 3 configured as output reset required
Restart interlock and external device monitoring (EDM) via safety relay

The safety laser scanner can be integrated by means of a safety controller or a safety relay, for example the safety relay UE10-2FG. It is operated with restart interlock and external device monitoring.

+24 V DC

Figure 45: Connection diagram with restart interlock and external device monitoring (EDM) via safety relay

Uni-I/O 1 configured as input reset
Uni-I/O 2 configured as input external device monitoring (EDM)
Uni-I/O 3 configured as output reset required

4.5 Testing plan

The protective device must be tested by appropriately qualified safety personnel when commissioning, after modifications and at regular intervals.

The regular thorough checks serve to investigate the effectiveness of the protective device and discover defects because of modifications or external influences (such as damage or tampering).

The manufacturer and user must define the type and frequency of the thorough checks of the machine on the basis of the application conditions and the risk assessment. Determination of the thorough checks must be documented in a traceable manner.
• A thorough check must be carried out during commissioning and following modifications, see "Thorough check", page 107
• The regular thorough checks on the safety laser scanner must fulfill certain minimum requirements, see "Minimum requirements for the regular thorough check", page 60
• In many cases, depending on the application conditions, the risk assessment determines that further thorough checks are required, see "Recommendations for further thorough checks", page 60

A test object is required for some thorough checks. An optically opaque cylinder with a matte black surface can be used as a suitable test object. The effective diameter should match the configured resolution.

4.5.1 Minimum requirements for the regular thorough check

**DANGER**
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- The thorough checks must be carried out at least annually.
- The thorough checks must be carried out by qualified safety personnel or specially qualified and authorized personnel and must be documented in a traceable manner.

The following thorough checks must be carried out at least once a year:

- Thorough check of the principal function of the protective device, page 60
- Thorough check of the detection capability (resolution) in the context of the Thorough check of the area to be protected, page 61

If a thorough check reveals a fault, the machine should be shut down immediately. In this case, the mounting and electrical installation of the safety laser scanner must be checked by appropriately qualified safety personnel.

4.5.2 Recommendations for further thorough checks

In many cases, depending on the application conditions, the risk assessment of the machine determines that further thorough checks are required or that some thorough checks must take place more frequently.

In many cases, it makes sense to carry out the following thorough checks together with the regular thorough check:

- Thorough visual check of the machine and the protective device, page 62
- Thorough check of the relevant points on the checklist, see "Checklist for initial commissioning and commissioning", page 152

In many cases, it makes sense to carry out the following thorough checks daily:

- Thorough visual check of the machine and the protective device, page 62
- Thorough check of the principal function of the protective device, page 60

If a thorough check reveals a fault, the machine should be shut down immediately. In this case, the mounting and electrical installation of the safety laser scanner must be checked by appropriately qualified safety personnel.

4.5.3 Carrying out thorough checks

**Thorough check of the principal function of the protective device**

SICK recommends the following procedure:
Watch the display and the status LEDs above the safety laser scanner’s display. If, when the machine is switched on, at least one LED above the safety laser scanner’s display does not light up permanently, you must assume that there is a fault.

Test the function of the protective device by triggering the protective function once and observing the safety output’s reaction using the reaction of the machine, for example.

- All applications: during the thorough check, observe whether the safety laser scanner displays the interruption of the protective field using the LEDs and/or the display.
  - Stationary application (hazardous area protection, access protection, hazardous point protection):
    1. Interrupt the protective field using the supplied test object and observe whether the machine stops.
  - Mobile application (mobile hazardous area protection):
    1. Place the supplied test object in the path of the vehicle and observe whether the vehicle stops.
    2. Activate a protective field, which is interrupted by at least one test object and check the expected reaction (for example by an automatic thorough check in the safety controller).

If the thorough check reveals a fault, the machine should be shut down immediately. In this case, the mounting and electrical installation of the safety laser scanner must be checked by appropriately qualified safety personnel.

Thorough check of the area to be protected

The area to be protected and the detection capability are checked during this thorough check.

The thorough check covers the following points:

- Changes in the detection capability (thorough check of all configured fields)
- Modifications, tampering and damage to the protective device or the machine, which lead to changes in the area to be protected or the position of the protective field

SICK recommends the following procedure:

Hazardous area protection

- Position the supplied test object at a number of points at the edges of the area to be protected. The safety laser scanner must detect the test object at each position and indicate the detection. How it is indicated depends on the configuration. The number and position of sites where the thorough check is carried out must be chosen so that undetected access to the hazardous area is impossible.

- If a number of protective fields are used (in different monitoring cases for example), check the edges of all protective fields.

Access protection and hazardous point protection

- Move the supplied test object along the edges of the area to be protected. The safety laser scanner must detect the test object at each position and indicate the detection. How it is indicated depends on the configuration. The protective field must be dimensioned such that reaching around or going around it is impossible.

- If a number of protective fields are used (in different monitoring cases for example), check the edges of all protective fields.

Mobile hazardous area protection
Place the supplied test object in the path of the vehicle and check whether the vehicle comes to a stop in time.

If a number of protective fields are used (in different monitoring cases for example), check whether the vehicle comes to a stop in time in all of the protective fields.

If necessary, change the position of the test object so that a thorough check is carried out for each monitoring case to determine whether the protective field is active over the whole of the required width.

Check the height of the scan plane. The scan plane must be at a height of at least 200 mm so that people lying down can be reliably detected. For this purpose, position the supplied test object at a number of points at the edges of the area largest protective field. The safety laser scanner must detect the test object at each position and indicate the detection. How it is indicated depends on the configuration.

If the thorough check reveals a fault, the machine should be shut down immediately. In this case, the mounting and electrical installation of the safety laser scanner must be checked by appropriately qualified safety personnel.

**Thorough visual check of the machine and the protective device**

SICK recommends the following procedure:

- Check whether the machine or the protective device has been modified or tampered with such that the effectiveness of the protective device may be impaired.
- Check the following points in particular.
  - Has the machine been retrofitted?
  - Have machine parts been removed?
  - Have modifications been made to the machine’s surroundings?
  - Are there any defective cables or open cable ends?
  - Have the protective device or its parts been dismantled?
  - Is the protective device damaged?
  - Is the protective device severely contaminated?
  - Is the optics cover contaminated, scratched or destructed?
  - Has the protective device’s alignment been changed?
  - Are there any objects (e.g. cables, reflective surfaces) in the protective field?

If one of the points applies, the machine should be shut down immediately. In this case, the machine and the protective device must be checked by appropriately qualified safety personnel.
5 Mounting

5.1 Safety

Information about the requirements for properly mounting the safety laser scanner, see "Assembly", page 24.

![DANGER]

DANGER

Dangerous state of the machine

- Make sure that the dangerous state of the machine is (and remains) switched off during mounting, electrical installation, and commissioning.
- Make sure that the safety laser scanner’s outputs do not affect the machine during mounting, electrical installation, and commissioning.

![DANGER]

DANGER

Hazard due to lack of effectiveness of the protective device

If unsuitable brackets are used or if subjected to excessive vibrations, the device may become detached or damaged.

Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.

- Only use SICK-approved brackets for mounting.
- Take appropriate measures for vibration damping if vibration and shock specifications exceed the values and test conditions specified in the data sheet, see "Data sheet", page 132.

![DANGER]

DANGER

Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Do not carry out any repairs to the device components.
- Do not make any changes to or tamper with the device components.
- With the exception of the procedures described in this document, the device components must not be opened.

![NOTE]

NOTE

Mount the device in the following order.

5.2 Unpacking

- The safety laser scanner’s optics cover is an optical component. Make sure that the optics cover does not become dirty or scratched during unpacking and mounting. Prevent fingerprints on the optics cover.
- Check the components for completeness and the integrity of all parts, see "Scope of delivery", page 142.
- Please contact your respective SICK subsidiary should you have any complaints.

5.3 Mounting procedure

There are three options for mounting the safety laser scanner:
• mounting directly without a mounting kit
• mounting using mounting kit 1
• mounting using mounting kits 1 and 2

The mounting kits are built upon one another. This means that for mounting using mounting kit 2, you also need mounting kit 1.

Each mounting kit consists of one or two brackets and the screws needed to mount the safety laser scanner on the bracket.

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.

- You must take account of the minimum distances calculated for your machine, see "Assembly", page 24.
- Mount the safety laser scanner so that crawling beneath, climbing over and standing behind the protective fields is impossible.

---

**Figure 46: Prevent crawling beneath**

**Figure 47: Prevent stepping over**

---

**NOTE**

- Read this section completely before mounting the safety laser scanner.

**Mounting instructions**

- The safety laser scanner’s optics cover is an optical component. Make sure that the optics cover does not become dirty or scratched during unpacking and mounting. Prevent fingerprints on the optics cover.
- Mount the safety laser scanner so that it is protected from moisture, dirt and damage.
- Make sure that the safety laser scanner’s field of view is not restricted.
- Make sure that there are not mirrors or other very reflective objects in the protective field.
- Make sure that no small objects (e.g. cables) are in the protective field, even if the safety outputs do not switch to the OFF state as a result.
- Mount the safety laser scanner so that the status indicators are clearly visible.
- Mount the safety laser scanner so that you can plug in and pull out the system plug.
- Take appropriate measures for vibration damping if vibration and shock specifications exceed the values and test conditions specified in the data sheet, see "Data sheet", page 132.
- For machines that vibrate heavily, use thread-locking compounds to prevent the possibility of fixing screws coming loose unintentionally.
- Make sure that the safety laser scanner is aligned correctly, even during mounting: if the safety laser scanner is intended to monitor an area of 270° on a corner, the safety laser scanner may be mounted rotated by a maximum of 2.5° about the vertical axis.
- Location of the scan plane: see "Dimensional drawings", page 141.
- Take account of the tightening torque for the fixing screws:
  - M5 at rear/at side = 4.5 Nm ... 5.0 Nm
  - M4 at rear/at side = 2.2 Nm ... 2.5 Nm
  Higher tightening torques may damage the thread. Lower tightening torques do not offer sufficient protection against slipping of the safety laser scanner due to vibrations, for example.

### 5.3.1 Direct mounting

The safety laser scanner has four M5 threaded holes on the back. If you are able to drill through the mounting surface from the rear, you can mount the safety laser scanner directly using these threaded holes.

![Figure 48: Mounting the safety laser scanner directly](image)

1. Rear M5 threaded hole
2. Side M5 threaded hole

- Use either the rear or the side M5 threaded holes for direct mounting, see figure 48, page 65.
- Use all four rear or all four side M5 threaded holes for direct mounting, so that the values given in the data sheet for vibration and shock resistance are achieved.
- Maximum depth of thread engagement: 7.5 mm (see "Dimensional drawings", page 141).
- Tightening torque: 4.5 Nm ± 5.0 Nm.
5.3.2 Mounting using mounting kit 1

If you are not able to drill through the mounting surface from behind, you can use the mounting kit 1 to mount the safety laser scanner. Mounting kit 1 makes it possible to replace the safety laser scanner easily.

The mounting kit is available as mounting kit 1a without protection for the optics cover and as mounting kit 1b with protection for the optics cover, see "Accessories", page 144.

Tool required:
- TX20 Torx wrench

![Figure 49: Mounting using mounting kit 1a]

1. Make sure that the mounting bracket is oriented correctly. See the symbol on the mounting bracket.
2. Mount the mounting bracket on the mounting surface.
3. Push the safety laser scanner onto the mounted mounting bracket.
4. Use all 4 supplied M5 screws to fix the safety laser scanner on the mounting bracket.
5. Tighten the M5 screws. Tightening torque: 4.5 Nm ± 5.0 Nm.

5.3.3 Mounting using mounting kit 2

You can use mounting kit 2 to align the safety laser scanner in two planes (rotation around the transverse axis and around the depth axis). The maximum alignment angle is ±5° in each plane. You will also need mounting kit 1a or 1b for mounting using mounting kit 2.

Mounting kit 2 consists of two parts: holding plate and alignment bracket.

Tool required:
- TX20 Torx wrench
1. Make sure that the holding plate is oriented correctly. See the symbol on the holding plate.

2. Mount the holding plate on the mounting surface. Either use the two outer drill holes (10) or the two drill holes with countersink (9). Also use the drill hole in the holding tab.

   Procedure when using the drill holes with countersink (9):
   ▶ Loosen the screws (7) and remove the alignment bracket from the holding plate.
   ▶ Mount the holding plate on the mounting surface.
   ▶ Make sure that the alignment bracket is oriented correctly. See the symbol on the alignment bracket.
   ▶ Push the alignment bracket back onto the centering pin (8) and fix it on the holding plate using the M4 screws (7).

3. Make sure that the mounting bracket 1a or 1b is oriented correctly. See the symbol on the mounting bracket.
4. Use the supplied M4 screws to fix the mounting bracket 1a or 1b on the alignment bracket.
5. Push the safety laser scanner onto the mounted mounting bracket.
6. Use all 4 supplied M5 screws to fix the safety laser scanner on the mounting bracket.
7. Tighten the M5 screws. Tightening torque: 4.5 Nm ± 5.0 Nm.
8. Align the safety laser scanner. You can use a slotted screwdriver (blade width 8 mm) for fine alignment, see "Alignment", page 105.
9. Tighten the M4 screws. Tightening torque: 2.2 Nm … 2.5 Nm.
6 Electrical installation

6.1 Safety

Information about the requirements that must be met for safe integration of the safety laser scanner in the control and electronics of the machine: see "Integration in the electrical control", page 50.

Mounting should be completed before electrical installation.

---

**DANGER**

Hazard due to electrical voltage

Hazard due to unexpected starting of the machine

- Make sure that the machine is (and remains) disconnected from the power supply during the electrical installation.
- Make sure that the dangerous state of the machine is (and remains) switched off.
- Make sure that the outputs of the safety laser scanner have no effect on the machine during the electrical installation.

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

- Make sure that the following control and electrical requirements are met so the safety laser scanner can fulfill its protective function.

- Use a suitable power supply.
- Use the same earthing method for all devices that are electrically connected to the safety laser scanner.
- Power must be supplied in accordance with SELV/PELV (IEC 60204-1) for all devices that are electrically connected to the safety laser scanner.
- All devices that are electrically connected to the safety laser scanner must be supplied by the same power source.
- Connect the functional earth correctly.

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

The dangerous state may not be stopped in the event of non-compliance.

- Always connect the two OSSDs in an OSSD pair separately from one another. The two OSSDs must not be connected to each other. Otherwise, signal safety will not be ensured.
DANGER
Hazard due to lack of effectiveness of the protective device
The dangerous state may not be stopped in the event of non-compliance.

- Prevent the formation of a potential difference between the load and the protective device.

- If you connect loads to the OSSDs (safety outputs) that then also switch if controlled with negative voltage (for example electromechanical protection without reverse polarity protection diode), you must connect the 0 V connections of these loads and those of the corresponding protective device individually and directly to the same 0 V terminal strip. In the event of a fault, this is the only way to ensure that there can be no potential difference between the 0 V connections of the loads and those of the corresponding protective device.

6.2 Connection overview

The USB connection may only be used temporarily and only for configuration and diagnostics. The permanent connections are contacted via M12 plug connectors.
6.2.1 microScan3 Core

<table>
<thead>
<tr>
<th>Safety laser scanner</th>
<th>Suitable system plug</th>
<th>Plug connector</th>
</tr>
</thead>
<tbody>
<tr>
<td>microScan3 Core I/O</td>
<td>MICSXAABIZZZZ1 (part number: 2073156)</td>
<td>Connecting cable with M12 plug connector, see page 71</td>
</tr>
</tbody>
</table>

Table 4: System plug and connections – microScan3 Core

6.3 Pin assignment

You will find the pin assignment for the individual plug connectors in the following.

6.3.1 Connecting cable with M12 plug connector

Power is supplied and local inputs and outputs are connected via the connecting cable with an 8-pole, A-coded M12 male connector.

```
Figure 53: Pin assignment of the connecting cable (8-pole, A-coded M12 male connector)
```

<table>
<thead>
<tr>
<th>Pin</th>
<th>Term</th>
<th>Function</th>
<th>Wire color</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+24 V DC</td>
<td>Supply voltage (+24 V DC)</td>
<td>Brown</td>
</tr>
<tr>
<td>2</td>
<td>OSSD 1.A</td>
<td>OSSD pair 1, OSSD A</td>
<td>White</td>
</tr>
<tr>
<td>3</td>
<td>0 V DC</td>
<td>Supply voltage (0 V DC)</td>
<td>Blue</td>
</tr>
<tr>
<td>4</td>
<td>OSSD 1.B</td>
<td>OSSD pair 1, OSSD B</td>
<td>Black</td>
</tr>
<tr>
<td>5</td>
<td>Uni-I/O 1</td>
<td>Universal I/O 1, configurable:</td>
<td>Gray</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Universal input: resetting, EDM (external device monitoring), standby, restarting the device</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Universal output: contamination, fault, reset required, monitoring result (warning field)</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Uni-I/O 2</td>
<td>Universal I/O 2, configurable:</td>
<td>Pink</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Control input A1 (together with pin 7)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Universal input: resetting, EDM (external device monitoring), standby, restarting the device</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Universal output: contamination, fault, reset required, monitoring result (warning field)</td>
<td></td>
</tr>
</tbody>
</table>

Table 5: Pin assignment of the connecting cable with M12 plug connector

Subject to change without notice
<table>
<thead>
<tr>
<th>Pin</th>
<th>Term</th>
<th>Function</th>
<th>Wire color</th>
</tr>
</thead>
</table>
| 7   | Uni-I/O 3 | Universal I/O 3, configurable:  
• Control input A2 (together with pin 6)  
• Universal input: resetting, EDM (external device monitoring), standby, restarting the device  
• Universal output: contamination, fault, reset required, monitoring result (warning field) | Violet |
| 8   | FE   | Functional earth/shielding | Orange |

Table 5: Pin assignment of the connecting cable with M12 plug connector

1) Applies to the extension cables recommended as accessories, see "Accessories", page 144.
7 Configuration

This chapter describes the configuration of the safety laser scanner using Safety Designer. More information regarding the Safety Designer can be found in the operating instructions for the Safety Designer item no. 8018178.

This chapter describes configuring application parameters, monitoring levels, creating fields, configuring inputs and outputs and defining monitoring cases.

It also describes transferring configuration data to the device, creating reports and the service options offered by Safety Designer.

7.1 General requirements

This chapter describes the delivery state and the preparations necessary for configuration.

7.1.1 Delivery state

The safety laser scanner is not configured in the delivery state.

The password SICKSAFE is created for the authorized client user group.

7.2 Safety Designer

This chapter describes the basics of using Safety Designer.

7.2.1 Installation assistant

An installation assistant will help you to install Safety Designer.

1. Go to the download page. To do this on www.sick.com enter “Safety Designer” in the search field.
2. Take note of the system requirements on the download page.
3. Download the installation file from the download page. Extract it and run it.
4. Follow the notes from the setup assistant.

7.2.2 Projects

Using Safety Designer, you can configure one or more devices in a project. You can save the configuration data in a project file on the PC.

Creating a project

► Click on New project
✓ This creates and opens an empty project.

Configuring a device online (device connected to PC)

If a device is connected to the PC, Safety Designer can establish a connection to the device.

You will then configure the device online. In this case, you can transfer the configuration to the devices directly and use diagnostic functions.

► Click on Connect
✓ Safety Designer searches for connected devices, with which it can establish a connection.

Configuring a device offline (device not connected to PC)

If the device is not connected to the PC, select it from the device catalog.
You will then configure the device offline. Diagnostics functions are not available. You can connect the PC to the device later and transfer the configuration.

7.2.3 User interface

This chapter gives information about how to use the software's controls.

Figure 54: Software controls

1. Menu bar
2. Toolbar
3. Navigation
4. Work space
5. Device catalog
6. Task list and notes

7.2.4 User groups

The devices contain a hierarchy of user groups that regulate access to the devices. The user groups’ settings and passwords are part of the configuration stored in the device.

<table>
<thead>
<tr>
<th>User group</th>
<th>Password</th>
<th>Authorization</th>
</tr>
</thead>
<tbody>
<tr>
<td>Machine operator</td>
<td>Does not need a password (anyone can log in as a machine operator).</td>
<td>May import configuration from the device (as long as they are not blocked).</td>
</tr>
</tbody>
</table>

Table 6: User groups
Table 6: User groups

<table>
<thead>
<tr>
<th>User group</th>
<th>Password</th>
<th>Authorization</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maintenance technician</td>
<td>Does not have a factory-set password. The password is created by the authorized client (namely, it is not possible initially to log in as a maintenance technician).</td>
<td>May import configuration from the device. May transfer verified configuration to the device.</td>
</tr>
<tr>
<td>Authorized client</td>
<td>The password SICKSAFE is created at the factory. Change this password to protect the device against unauthorized access.</td>
<td>May import configuration from the device. May transfer verified and unverified configuration to the device. May verify configuration. Can set a password for maintenance technicians.</td>
</tr>
</tbody>
</table>

If a device's configuration is saved in its system plug, the passwords are preserved if the device is replaced.

NOTICE

If you leave a computer unattended, which is connected to devices, you must log out of the maintenance technician or authorized client user groups and change to the machine operator user group, so that unauthorized people cannot transfer configurations to the devices.

7.2.4.1 Changing user group

- Establish a connection to the device.
- In the toolbar, click on the User button.
- The Log in dialog box is opened.
- Select the desired user group.
- Enter the password and click on Log in.

7.2.5 Opening the device window – configuring devices

Open a device window to configure a device, perform diagnostics, or create reports. You have the following options:

- Click on the Device tile.
  - Or
  - In the Device tile, click the Open device window button.
  - Or
  - Open the tile menu and choose Configure.
- The device window opens. ²)

7.3 Overview

The Overview dialog box contains information about the safety laser scanner.

²) When a device is configured offline for the first time, the device selection assistant opens. This is where you select the type of device to be configured.
Figure 55: Device information

1. Device information
2. Current measurement data
3. Display with device status

**Application**
- Project name: the same name should be chosen for all devices in the project
- Application name: this name can be the same for a number of devices in the project. It highlights that these devices realize an application together, by responding to one another for example.

**Device information**
- Name: identifies the individual device.
- Type code of the safety laser scanner
- Serial number of the safety laser scanner
- Firmware version of the safety laser scanner
- Part number of the safety laser scanner

**Connection**
- Connection status
- Type of connection
Status of the system

- Application status
- Current notification from the safety laser scanner
- Configuration date for the configuration in the device
- Checksum: shows the configuration's checksum (security function) in the device, see "Checksum", page 77
- Synchronization: shows whether the configuration in Safety Designer and the configuration in the device are identical
- Configuration status

Measurement data

Shows the measurement data when a device is connected.

Display

Shows the status of the display and LEDs when a device is connected.

Establishing connection

- Check whether the safety laser scanner is connected correctly.
- Click on Establish connection.
- Safety Designer creates the connection to the safety laser scanner.

Checksum

A checksum is used as a unique identification for a configuration. Using the checksum, it is possible to work out whether two devices have the same configuration.

The checksum of the configuration in Safety Designer may not match the checksum in the device, for example if a field geometry has been modified, but not yet transferred to the device.

7.4 Identification

In the Identification dialog box, you can assign names and information to uniquely identify the application, project and devices.
Figure 56: Identification

① Parameters for the project and the application
② Parameters for the device

**Application name**

The application name can be the same for a number of devices in the project. It highlights that these devices realize an application together, by responding to one another for example.

- Enter an application name with a maximum of 32 characters.

**Project name**

The project name is used to identify an entire project. The same project name should be chosen for all devices in the project.

- Enter a project name with a maximum of 32 characters.

**User name**

The user name helps later users to find a contact for the application.

- Enter a user name with a maximum of 24 characters.
Application image

An image helps to identify the application more quickly. The application image is saved in the project file on the PC and transferred to the device. Safety Designer supports JPG files.

- Click on Select image.
- Select an image file for the application.
- ✓ The image is incorporated as a thumbnail.

Description

A description makes it easier to understand an application’s context more quickly.

- Enter a description with a maximum of 1000 characters.

Device name

If a number of safety laser scanners are used in an application or in a project, a unique device name helps to tell the individual devices apart.

- Give each device a unique device name.

7.5 Application

Define the following parameters for an application:
Figure 57: Application

1. Basic settings for the application
2. Settings for the device, which relate to the application

**Application type**

The type of application depends on the application of the safety laser scanner:

- Select application type.
- **✓ Mobile**
  Mobile hazardous area protection is suitable for AGVs (automated guided vehicles), cranes and forklifts, to protect people when vehicles are moving or docking. The safety laser scanner monitors the area in the direction of travel and stops the vehicle as soon as an object is located in the protective field.
- **✓ Stationary**
  The safety laser scanner's position is fixed. The safety laser scanner is mounted horizontally (for hazardous area protection) or vertically (for hazardous point protection and access protection).

**Display language**

The safety laser scanner's display outputs notifications and statuses (see "Buttons and display", page 110). Multiple languages are available for the display.

- Select a language that the operator understands.
- **✓** The safety laser scanner outputs the notifications in the set language.
Display orientation

If you mount the safety laser scanner upside down, you can rotate the orientation of the display through 180°.

- Choose the option **Normal** or **Upside down** for display orientation.
- ✓ The preview shows the display’s orientation.

7.6 Monitoring plane

A safety laser scanner’s scan plane forms its monitoring plane.

Define the following parameters:

- Parameters for the monitoring plane
- Parameters for the safety laser scanner

![Diagram of Monitoring plane](image)

**Figure 58: Monitoring plane**

1. Parameters for the monitoring plane
2. Parameters for the safety laser scanner

7.6.1 Parameters for the monitoring plane

For the monitoring plane, you can configure a name, the object resolution, multiple sampling, and the orientation of the monitoring plane.
At first, the object resolution and multiple sampling configured for the monitoring plane apply for all fields. If necessary, make changes to each individually at a later date. If you do this, Safety Designer will indicate this in the settings for the monitoring plane.

**Name of the monitoring plane**

You can use the name to identify monitoring planes when creating fields and monitoring cases and also in reports.

- Enter a descriptive name for the monitoring plane (such as “Vertical protection” or “Right hazardous area”).
- The name is used to identify the monitoring planes.

**Mounting orientation**

People approach the monitoring plane parallel or orthogonally, depending on the orientation of the protective field in your application (see "Project planning", page 24).

- **Horizontal**
  Typically, for a horizontal approach, the requirement is to detect the leg. The typical object resolution is leg (70 mm).

- **Vertical (hazardous point protection)**
  Typically, for hazardous point protection, the requirement is to detect a hand. The typical object resolution is hand (40 mm).

- **Vertical (access protection)**
  Typically, for access protection, the requirement is to detect a person. The typical object resolution is body (200 mm).

**Reference contour monitoring**

**NOTE**

If the monitoring plane has a vertical orientation, typically a contour (such as the floor, a part of the machine bed, or an access threshold) is defined and monitored as a reference contour. A reference contour field is used for this, see "Reference contour field", page 84.

1. Check the option **Activate reference contour monitoring**.
- The point “Reference contour field” is shown in the navigation. Here you can configure the reference contour field required for your application.

**Object resolution**

The object resolution defines the size that an object must be to allow it to be reliably detected. The following object resolutions are available:

- 30 mm = hand detection
- 40 mm = hand detection
- 50 mm = leg detection
- 70 mm = leg detection
- 150 mm = body detection
- 200 mm = body detection

- Choose the object resolution.
- Objects the same size as or larger than the chosen object resolution are reliably detected.

**NOTE**

The configurable object resolution has an influence on the protective field range available. The finer the object resolution configured for the safety laser scanner, the shorter the available protective field range.
The protective field range is shown to you, see “Parameters for the safety laser scanner”, page 83.

Multiple sampling

DANGER
Hazard due to lack of effectiveness of the protective device
Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.
A higher multiple sampling increases the response time.
  ► Make a note of the safety laser scanner’s new response time in Safety Designer.
  ► Adjust the minimum distance from the hazardous point to the new response time.

Multiple sampling indicates how often an object has to be scanned before the safety laser scanner reacts. A higher multiple sampling reduces the possibility that insects, weld sparks or other particles cause the machine to be shut down. You will increase the machine’s availability.

A multiple sampling of 2 is the minimum setting.
1. Increase the multiple sampling up to 16.
✓ An object must be this many times.

<table>
<thead>
<tr>
<th>Recommended multiple sampling</th>
<th>Application</th>
</tr>
</thead>
<tbody>
<tr>
<td>2×</td>
<td>Stationary application: such as horizontal hazardous area protection or vertical hazardous point protection under clean ambient conditions</td>
</tr>
<tr>
<td>2×</td>
<td>Stationary application: such as vertical access protection Only 2-time multiple sampling may be used for vertical access protection.</td>
</tr>
<tr>
<td>4×</td>
<td>Mobile application</td>
</tr>
<tr>
<td>8×</td>
<td>Stationary application: such as horizontal hazardous area protection under dusty ambient conditions</td>
</tr>
</tbody>
</table>

Table 7: Recommended multiple sampling

7.6.2 Parameters for the safety laser scanner

Configure the parameters for the safety laser scanner.

Interference protection

If you mount several safety laser scanners in close proximity to each other, this can lead to mutual interference. You will prevent mutual interference in neighboring safety laser scanners if you choose different settings for interference protection.

Modes 1 to 4 are available. Interference protection influences the scan cycle time and therefore the response time.

- Mode 1 = + 0 ms per scan cycle
- Mode 2 = + 1 ms per scan cycle
- Mode 3 = + 2 ms per scan cycle
- Mode 4 = + 3 ms per scan cycle.
Configure a different mode for each safety laser scanner that is mounted in close proximity.
✓ The resulting response time is shown.

Scan cycle time
You can configure the scan cycle time. The safety laser scanner’s scan cycle time influences the response time and the protective field range.
- 40 ms: full protective field range, increased availability in dusty conditions for example
- 30 ms: smaller protective field range with shorter response time
✓ Select scan cycle time.
✓ The resulting response time and the range of the fields are shown.

NOTE
The safety laser scanner’s response time depends on the scan cycle time, interference protection and multiple sampling, see "Response times", page 137. In addition to the safety laser scanner’s response time, further signal transmission and processing also influence the time up until the end of the dangerous state.

A graphic shows how the configuration affects the available ranges.

7.7 Reference contour field
If you have activated the option Reference contour monitoring, the Reference contour field dialog box is shown. Draw the reference contour field on the basis of the values determined during project planning (see "Reference contour monitoring", page 29).

The reference contour field monitors a contour of the environment. The safety laser scanner switches all safety outputs to the OFF state if a contour does not match the set parameters, because, for example, the mounting situation of the safety laser scanner were changed.
Choose the tool for drawing the reference contour field.

Draw a line along the spatial contour as a reference.

First, use the mouse to click the desired contour.
Click to add the corners of the contour.
Finally, double-click the contour.

The reference contour field is displayed.

Multiple sampling and object resolution

**DANGER**

Hazard due to lack of effectiveness of the protective device

Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.

A higher multiple sampling increases the response time.

Make a note of the safety laser scanner’s new response time in Safety Designer.
Adjust the minimum distance from the hazardous point to the new response time.

Safety Designer initially uses multiple sampling and the object resolution of the monitoring plane for the fields.
If necessary, define multiple sampling and the object resolution for each field individually.

1. Select multiple sampling.
   ✓ Multiple sampling indicates how often an object has to be scanned before the safety laser scanner reacts.

2. Select object resolution.
   ✓ The object resolution defines the size that an object must be to allow it to be reliably detected.

**Tolerance band**

A contour has a positive and a negative tolerance band. The cut-off path goes to the OFF state if the safety laser scanner does not detect the contour inside the tolerance band.

- Enter the **Positive tolerance (far)**.
  ✓ The tolerance away from the safety laser scanner is defined.

- Enter the **Negative tolerance (near)**.
  ✓ The tolerance toward the safety laser scanner is defined.

### 7.8 Fields

Using the field editor, you can configure the safety laser scanner’s field sets in a graphical user interface. The number of configurable fields depends on the safety laser scanner variant, see "Variants", page 15.

The edge length or the diameter of each field must be at least as large as the selected object resolution.
7.8.1 Using the field editor

In the **Fields** area, you can draw the fields in a field set using the tools in the toolbar. You can create field sets and fields in the **Field set** area. In the area below, you can define the field type, enter the name and, configure multiple sampling and the object resolution, if necessary.

**Toolbar**

Using the tools in the field editor, you can draw the fields in a field set or masked areas inside the fields.

- **Arrow tool**, for marking objects
- **Hand tool**, for moving the work space
- **Draw reference contour field** or **contour detection field**
- **Draw field using points**

*Table 8: Buttons on the toolbar*
Draw rectangle
Draw circle
Draw circle segment
Mask areas (see "Drawing points that cannot be monitored", page 92). Use the drawing functions for fields to draw the masked areas. The buttons are crosshatched.
Edit a field using coordinates (see "Editing fields using coordinates", page 92)
Push the object into the foreground or background
Select field design
Calculate field
Zoom in
Zoom out
Zoom to area
Zoom to work space
Show snapshot of the spatial contour. Clicking again clears the spatial contour shown.
Show live spatial contour
Paste background image (see see "Background image", page 91)
Open field editor settings

Table 8: Buttons on the toolbar

Field display
Safety Designer displays the field types in different colors.

<table>
<thead>
<tr>
<th>Protective field</th>
<th>Warning field</th>
<th>Reference contour field and contour detection field</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red</td>
<td>Yellow</td>
<td>Turquoise</td>
</tr>
</tbody>
</table>

Table 9: Colors of the field types

Create fields and field sets

NOTE
You can only create the number of fields and field sets allowed in the safety laser scanner’s performance package. If the maximum number of fields and field sets has already been used, it is not possible to create any more fields or field sets.
Create the fields in a field set in the same order that you need them in the monitoring case table (see "Cut-off paths", page 97). For example, if you choose protective field, warning field, the protective field acts on cut-off path 1 and the warning field acts on cut-off path 2.
Add field to field set
Add field set
Duplicate field set
Delete field or field set
Hide or show field sets and fields
Manage field-set templates (see "Creating field-set templates", page 90)

Add field:
- Activate the field set to which you would like to add a field.
- Click on Add field to field set.
✓ Another field is added to the active field set.

Add field set:
The menu contains a simple field-set template and may contain user-defined field-set templates.
- Choose Simple field set.
✓ A field set containing one field is created.
- Enter a unique name for the field set under Name.
- Add further fields to the field set, if necessary.

Duplicate field set:
1. Activate the field set which you would like to duplicate.
2. Click on Duplicate field set.
✓ The field set is duplicated and pasted in as a copy.

Manage field-set templates:
1. Click on Manage templates.
✓ The available templates are shown.
2. Edit the field-set template or create a new field-set template (see "Creating field-set templates", page 90).

Field name and field type
Assign a unique name and select a field type for each field. Change the multiple sampling or the object resolution of a field, if required.
1. Select the field to be edited.
2. Enter the name of the field.
3. Select the field type see "Field types", page 17.

Multiple sampling and object resolution

DANGER
Hazard due to lack of effectiveness of the protective device
Persons or parts of the body to be protected may not be recognized or not recognized in time in case of non-observance.
A higher multiple sampling increases the response time.
- Make a note of the safety laser scanner’s new response time in Safety Designer.
- Adjust the minimum distance from the hazardous point to the new response time.

Safety Designer initially uses multiple sampling and the object resolution of the monitoring plane for the fields.
If necessary, define multiple sampling and the object resolution for each field individually.

1. Select multiple sampling.
   ✓ Multiple sampling indicates how often an object has to be scanned before the safety laser scanner reacts.
2. Select object resolution.
   ✓ The object resolution defines the size that an object must be to allow it to be reliably detected.

**Tolerance band**

A contour has a positive and a negative tolerance band. The cut-off path goes to the OFF state if the safety laser scanner does not detect the contour inside the tolerance band.

- Enter the **Positive tolerance (far)**.
  ✓ The tolerance away from the safety laser scanner is defined.
- Enter the **Negative tolerance (near)**.
  ✓ The tolerance toward the safety laser scanner is defined.

**Field-set name**

Assign a unique name for each field set.

1. Select the field set to be edited.
2. Enter the name of the field set.

### 7.8.2 Creating field-set templates

If you require the same combination of fields a number of times, you can create a field-set template.

You can edit field-set templates using the Manage field sets tool.

Example: you define a field-set template with protective field, warning field1 and warning field2.

![Field set template](image)

**Creating a field-set template**

- Click on **Add field-set template**.
- Enter the name for the template.
- Define the number of fields.
- ✓ A selection field is shown for each field.
- Select the **Field types** for the fields.
- Enter the **Field names**.
- Click on **Apply**.
- ✓ The field-set template is saved.
7.8.3 Background image

You can select a background image for the field editor. For example, the plan view of the machine to be protected can be used as a sample.

The background image is saved in the project file on the PC. It is not transferred to the device.

You can use the Edit background image tool to choose a background image.

Safety Designer supports PNG, BMP and JPG files.

- Click on Background image in the toolbar.
- The Background image dialog box opens.
- Click on Search....
- Select the file for the background image.
- Safety Designer displays the background image.
- Enter the X position, Y position and rotation in the field editor’s coordinates system.
- Enter the width and height.
- Enter the Opacity.
  You can then freely move, scale or rotate the background image in the field editor.
- If required, click the option Lock position of background image.
- It is no longer possible to change the background image in the field editor.

7.8.4 Settings for the field editor

You can edit settings for the field editor.

You can open the settings using the tool Edit field editor settings.

Tolerance band

A contour has a positive and a negative tolerance band. The cut-off path goes to the OFF state if the safety laser scanner does not detect the contour inside the tolerance band.
Enter the **Positive tolerance (far)**.
✓ The tolerance away from the safety laser scanner is defined.
► Enter the **Negative tolerance (near)**.
✓ The tolerance toward the safety laser scanner is defined.

**Drawing area**
You can use a Cartesian or a polar coordinates system and select the colors for the grid and the drawing area.
► Choose the option **Cartesian**.
✓ The coordinates system is shown as a Cartesian coordinates system.
► Choose the option **Polar**.
✓ The coordinates system is shown as a polar coordinates system.
► Select **Color of grid**.
✓ The field editor’s grid is displayed in the chosen color.
► Select **Color of drawing area**.
✓ The field editor’s drawing area is displayed in the chosen color.

### 7.8.5 Editing fields using coordinates

You can use coordinates to edit fields. The appropriate input fields are displayed for the shape of the field. The example shows a dialog box for a rectangular field.

![Figure 59: Editing fields using coordinates](image)

The reference points for the X and Y values are as follows:
- Rectangle: top left corner
- Circle: center point
- Circle sector: center point
- Polygon: each point individually
- Contour line: each point individually

### 7.8.6 Drawing in points that cannot be monitored

The area to be monitored is scanned radially ①. For this reason, shadows ② are formed by objects in the room ② (support columns, separator grids, etc.). The safety laser scanner cannot monitor these areas.
Figure 60: Area that cannot be monitored

1. Protective field
2. Marked columns
3. Area that cannot be monitored

Drawing masked areas

You can draw in objects, which limit the safety laser scanner’s field of view, as masked areas. The masked area casts a shadow, so unmonitored areas may be created. The field editor shows the shadowing of the masked area 3.

- Click on the tool Mask areas.
- The tools you can use to draw fields are shown crosshatched.
- Choose a drawing tool.
- Draw the masked area.
- The masked area is crosshatched in gray.
- The field editor shows the shadowing of the masked area.

7.9 Inputs and outputs, local

Assign different input or output signals to the safety laser scanner’s connections.
Overview: plug connector of the safety laser scanner

Pin assignment

Available signals

Remove signal from connection

Further settings for some signals

### Connection overview

Safety Designer shows the safety laser scanner’s plug connector in the center of the dialog box.

### Pin assignment

Safety Designer shows the plug connector with the individual pins.

#### Assigning signals to the pins

Safety Designer shows the available input or output signals on the right under **Signals**.

- Click on **Signal type** (for example on control inputs).
- The menu shows the possible control inputs.
- Drag the signal towards the pins.
- Possible pins for the connection are highlighted. Safety Designer checks for any restrictions that may apply. For example, an OSSD cannot be placed on an input.
- Drop the signal on the pin.
- The signal name is shown on the right next to the pins.
Removing signals

- Click on the signal.
- Drag the signal on to the trash-can symbol.
✓ The pins are free again.

7.9.1 Further settings for some signals

Safety Designer shows the setting options for some signals under Further settings at bottom right.

DANGER
Hazard due to lack of effectiveness of the protective device
Hazard due to unexpected starting of the machine
By configuring the restart interlock for an OSSD pair, you can influence the restart interlock behavior for the application.

- Take account of the notes in the project planning chapter.

Restart interlock for the OSSD pair

The safety laser scanner has three options for the restart interlock behavior for the OSSD pair (see "Restart interlock", page 55):

- Instant restart without restart interlock: if there is no longer an object in the protective field, the safety laser scanner immediately switches the OSSDs to the ON state.
- Restart interlock, reset required: if the operator activates the restart or reset control switch, the safety laser scanner switches the OSSDs to the ON state.
- Automatic restart after ...: if there is no longer an object in the protective field, the safety laser scanner switches the OSSDs to the ON state after the configured delay.

External device monitoring (EDM)

An input must be configured for external device monitoring (EDM). This input must be correctly connected to the electric control (see "External device monitoring (EDM)", page 58).

If external device monitoring is activated, the safety laser scanner checks whether voltage is applied at the external device monitoring (EDM) input after the OSSDs have been switched off.

If no voltage is applied at the input after the OSSDs have been switched off, the safety laser scanner changes to the locking state and does not switch the OSSDs back to the ON state.

Configuring the restart interlock and external device monitoring (EDM)

Details for the restart interlock and for EDM: see "Restart interlock", page 55, see "External device monitoring (EDM)", page 58.

- Select the option Immediate restart without restart interlock.
✓ The OSSDs switch to the ON state if there is no longer an object in the protective field.
- Choose the option Restart interlock, reset required.
✓ The OSSDs only switch to the ON state if the operator activates the reset control switch.
- Choose the option Automatic restart after ... and enter the delay time.
✓ The OSSDs switch to the ON state if there is no longer an object in the protective field for the specified duration.
- Activate **External device monitoring (EDM)**.
- ✓ The OSSDs only switch to the ON state if the external device monitoring was successful.

### 7.10 Monitoring cases

You can create monitoring case tables and possible switching criteria for the monitoring cases in the monitoring case editor (see "Monitoring case", page 20). You can also create the monitoring cases and their input conditions and assign the field sets.

![Figure 61: Monitoring case editor](image)

1. Settings for the whole monitoring case table
2. Settings for the individual monitoring case
3. Input conditions for a monitoring case
4. Cut-off paths
5. Field set in the monitoring case and in the cut-off path
6. Configured field sets
7. Areas for defined cut-off behavior
8. Remove field set from a monitoring case
7.10.1 Settings for monitoring case tables

Name
Enter a name for the monitoring case table, which is as descriptive as possible, in the Name field.

Inputs used
Choose the inputs that you would like to use for switching between monitoring cases in the monitoring case table.

Input delay
If appropriate, select a delay for the inputs in the field Input delay.

If your control device, which you use to switch the static control inputs, cannot switch to the appropriate input condition within 12 ms (for example because of the switch’s bounce times), you must configure an input delay. For the input delay, select a time in which your control device can switch in a defined way to a corresponding input condition. You can increase the delay time incrementally.

The following empirical values exist for the switching time using various methods:

<table>
<thead>
<tr>
<th>Switching method</th>
<th>Required input delay</th>
</tr>
</thead>
<tbody>
<tr>
<td>Electronic switching via control, complementary electronic outputs with 0 ms to 12 ms bounce time</td>
<td>12 ms</td>
</tr>
<tr>
<td>Tactile controls (relays)</td>
<td>30 ms ... 150 ms</td>
</tr>
<tr>
<td>Control via independent sensors</td>
<td>130 ms ... 480 ms</td>
</tr>
</tbody>
</table>

Table 10: Empirical values for the required input delay

Also, take account of the notes relating to when to switch between monitoring cases (see “Monitoring case switching time”, page 31).

7.10.2 Settings for monitoring cases

Name
Enter a name for the monitoring case, which is as descriptive as possible, in the Name field. If you create a lot of monitoring cases, you should consider a naming concept that makes it possible to identify the monitoring cases easily (for example right cornering, left cornering).

Passive state
If you activate this option, the safety laser scanner changes to the passive state as soon as the input conditions for this monitoring case exist.

7.10.3 Input conditions

For each monitoring case, choose the input conditions for which the monitoring case will be activated.

- Activate the combination of inputs for each monitoring case.
- ✓ The relevant monitoring case is activated for exactly this combination.
- ✓ Combinations which are invalid or already assigned are marked.

7.10.4 Cut-off paths

You can create cut-off paths and define the outputs switched by the cut-off paths (Example: the protective fields switch the OSSD pair and the warning fields switch a universal output).
You need a cut-off path for every field in a field set. If the field sets have different sizes, use the field set with the most fields as a guide.

**Creating and entering a name**
1. Create a cut-off path for every field in the largest field set.
2. Enter a descriptive name for each cut-off path.

**Assigning an OSSD pair**
- Place a check in the box for the OSSD pair.
  ✓ The OSSD pair is assigned to the cut-off path.

**Assigning unsafe outputs**
- Place a check in the box for the universal output(s).
  ✓ The universal output is assigned to the cut-off path.

**7.10.5 Assigning field sets**

**Assigning a field set to a monitoring case**
The field sets that have been created are shown in the area **Field sets** on the right.
1. Create cut-off paths, see "Cut-off paths", page 97.
2. Drag the field set onto the monitoring case.
  ✓ The fields in a field set are arranged as they were drawn in the field editor (for example protective field, warning field, warning field).

**Deleting the assignment of a field set from the monitoring case**
- Drag the field set from the monitoring case table onto the trash-can symbol.
  ✓ The field set is removed from the relevant monitoring case.

**Defined cut-off behavior**

**DANGER**
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
The function **Always ON** has the same effect as a field which is always clear. In a monitoring case with the **Always ON** function, the cut-off path containing this function is permanently in the ON state.

- Drag the **Always OFF** function onto the cut-off path.
  ✓ The field is viewed as being permanently interrupted (if the monitoring case becomes active, the cut-off path is always in the OFF state).
- Drag the **Always ON** function onto the cut-off path.
  ✓ The field is viewed as being permanently clear (if the monitoring case becomes active, the cut-off path is always in the ON state).

If fields have not been assigned to certain cells in a monitoring case table, Safety Designer assigns the **Always OFF** function to these cells.

**7.11 Simulation**
You can visualize the result of the set configuration in the simulation.
1. Show or hide field types
2. Simulation tools
3. Select input conditions
4. Display the cut-off paths

**Simulation components and options**

- Display the status of OSSD pairs and the status of cut-off paths
- Get feedback about which monitoring case is active for the selected input sample (default: monitoring case 1 is active)
- You can switch inputs, monitoring cases, etc. virtually using symbols and observe the result
- You can mark a field in the simulation as interrupted and check which result is triggered by an object in the relevant field
7.12 Transfer

Transferring configuration

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
When transferring the configuration, the protective device’s existing configuration may be overwritten.

- Check the configuration carefully before transfer.
- Make sure that the desired device is connected during transfer.

At first, the configuration only exists as a project, namely as a configuration file. The configuration must be transferred to the device.
The compatibility of the configuration is checked during transfer.
You can start the safety function manually to test the safety laser scanner with the new configuration see "Starting and stopping safety function", page 101.

Verifying configuration

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
By verifying the configuration, you can confirm that the configuration complies with the planned safety function and fulfills the requirements in the risk assessment.

- Check the configuration report carefully before confirming verification.
- If the configuration deviates from the planned safety function or does not fulfill the requirements in the risk assessment, verification must not be confirmed.

The configuration must be verified to ensure that the safety function is implemented correctly.
During verification, Safety Designer reads back the transferred configuration from the safety laser scanner. It compares the configuration with the configuration saved in Safety Designer. If both configurations are identical, Safety Designer displays the configuration report. If the user confirms that this is correct, the system is considered to be verified.

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
If the configuration is verified, the device automatically starts the safety function after switching on.
If the configuration is not verified, the safety laser scanner may not be operated as a protective device. You can start the safety function manually to test the safety laser scanner and the configuration. The test operation has a time limit.

- Only operate the safety laser scanner as a protective device if the configuration is verified.
Transferring and verifying the configuration of an individual safety laser scanner

- If the checksums on the PC and the device differ, click on Transfer.
- The transfer process is shown in Safety Designer and on the device.
- As soon as the transfer process has completed, Safety Designer shows this.

- Then click on Verify.
- Safety Designer displays the configuration report.
- Check the configuration report and if appropriate, click on Confirm.
- Device configuration is shown as verified.

7.13 Starting and stopping safety function

In some situations, it is possible to start or stop the safety function manually.

- Start starts the safety function.
- Stop stops the safety function.

Table 11: Starting and stopping safety function

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
If the configuration is verified, the device automatically starts the safety function after switching on.
If the configuration is not verified, the safety laser scanner may not be operated as a protective device. You can start the safety function manually to test the safety laser scanner and the configuration. The test operation has a time limit.
- Only operate the safety laser scanner as a protective device if the configuration is verified.

7.14 Reports

You can show a device’s data with a report. You have the option of saving and archiving these data as a PDF.
Safety Designer creates a report as soon as you click on Report in the navigation.
National and international standards promote or recommend specific data and the person responsible for it. The required data is included in the report.

1. Print the report.
2. Write down the responsible person on the report.
3. Archive the report.
You compose the contents of a report individually.

1. Select the contents of the report under Settings for reports.

✓ Safety Designer creates a report with the selected contents.

7.15 Service

This section describes service options you have with Safety Designer on the safety laser scanner.

7.15.1 Device restart

If you have problems with the device, you can restart the device or subsections of the device (safety function, connections, additional functions).

Restarting safety function

- The fastest type of restart
- Serious faults remain, even if the cause has been rectified (for example a locking state because of a supply voltage which is too low)
• Communication with the device remains intact (connections for configuration, safety function and data not relating to safety)

• Communication beyond the device is not impaired

### Restarting safety function and connections

• The device’s function is also re-established after serious faults if the cause has been rectified

• Communication with the device is interrupted (connections for configuration, safety function and data not relating to safety). The device sets up communication again automatically after restarting.

• Communication beyond the device is not impaired

### Restarting device completely

• The device behaves exactly as it does when the power supply is switched off and back on again

• The device’s function is also re-established after serious faults if the cause has been rectified

• Communication with the device is interrupted (connections for configuration, safety function and data not relating to safety)

• Communication beyond the device is interrupted. This may also affect devices which communicate beyond the device.

### 7.15.2 Factory settings

Before reconfiguring the device, you can reset all settings to factory settings.

### Resetting safety function to factory settings

• The configuration for the safety function is reset to factory settings

• Communication beyond the device is not impaired

### Resetting whole device to factory settings

• The configuration for the safety function is reset to factory settings

• The configuration of device communication is reset to factory settings (connections for configuration, safety function and data not relating to safety)

### 7.15.3 Managing passwords

#### Assigning or changing passwords

The password must be between 1 and 8 characters long.

- Establish a connection to the device.
- In the device window, under Service, choose the entry User password.
- Choose the user group in the User password window.
- Enter the new password twice and use Accept to confirm.
- If you are requested to log in, log in as an Authorized customer.
- The new password is valid for the user group immediately.

#### Resetting a password

If you have forgotten a password, you can reset it.

- Request the form for resetting your password from SICK support.
- Connect to the device in Safety Designer.
- In the device window, under Service, choose the entry User password.
- Choose the option Reset password in the User password window.
- Transmit the serial number shown and the device counter together with the product number and the type code on the form to SICK support.
✓ You will then receive a reset code.
▲ Enter the reset code under Password reset and use Accept to confirm.
✓ The passwords are reset to factory settings (SICKSAFE for an authorized client, no password for machine operators. It is not possible for maintenance technicians to log in). The configuration is not changed.

7.15.4 Optics cover calibration

After replacing an optics cover (see "Replacing the optics cover", page 115), adjust the safety laser scanner’s measurement system to the new optical cover.

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

During operation, the safety laser scanner constantly measures the degree of contamination on the optics cover. For a new optics cover to function perfectly, an optics cover calibration needs to be carried out initially. This serves as a reference for contamination measurement (status = uncontaminated).

▲ Carry out an optics cover calibration every time the optics cover is replaced.
▲ Carry out the optics cover calibration at room temperature (10 °C to 30 °C).
▲ Only carry out the optics cover calibration using a new optics cover.
▲ Make sure that the entire system is clear of contamination when the calibration is carried out.

▲ Click on Yes in the Replacement column.
▲ Check that the front screen is clean.
▲ Click on Yes in the Cleanliness check column.
▲ Click on Start calibration in the Calibration column.
✓ The calibration process starts. Typically, this process can take up to a minute. A progress bar shows the progress.
▲ Do not switch off the safety laser scanner and do not break the connection between the PC and the safety laser scanner during the calibration.
✓ The end of the calibration is shown.
8 Commissioning

8.1 Safety

DANGER
Hazard due to lack of effectiveness of the protective device

▸ Before operating the protected machine for the first time, make sure that the machine is first checked and released by qualified safety personnel.
▸ Only operate the machine when the protective device is functioning properly.

DANGER
Dangerous state of the machine
During commissioning, the machine or the protective device may not yet behave as you have planned.

▸ Make sure that there is no-one in the hazardous area during commissioning.

DANGER
Hazard due to lack of effectiveness of the protective device
When changes are made to the machine, the effectiveness of the protective device may be affected unintentionally.

▸ After every change to the machine and changes to the integration or operational and secondary conditions of the safety laser scanner, check the protective device for effectiveness and recommission as specified in this chapter.

Before initial commissioning, project planning, mounting, electrical installation and configuration must be completed in accordance with the following chapters:

▸ Project planning, page 24
▸ Mounting, page 63
▸ Electrical installation, page 69
▸ Configuration, page 73

8.2 Alignment

The following options are available to you for precisely aligning the safety laser scanner using mounting kit 2a:
8.3 Switching on

After switching on, the safety laser scanner performs various internal tests. The OFF LED illuminates continually. The ON LED is off.

The start procedure lasts approx. ten seconds.
When the start procedure is complete, the status LEDs and the display show the safety laser scanner’s current operational status.

![Figure 64: Status LEDs]

When the start procedure is complete, the status LEDs and the display show the safety laser scanner’s current operational status.

<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
<th>Color</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>OFF state</td>
<td>Red</td>
<td>Shines red when the OSSD pair is in the OFF state.</td>
</tr>
<tr>
<td>2</td>
<td>ON state</td>
<td>Green</td>
<td>Shines green when the OSSD pair is in the ON state.</td>
</tr>
<tr>
<td>3</td>
<td>Warning field</td>
<td>Yellow</td>
<td>Shines yellow if at least one warning field is interrupted.</td>
</tr>
<tr>
<td>4</td>
<td>Restart interlock</td>
<td>Yellow</td>
<td>Flashes if restart interlock is configured with reset and the restart interlock has been triggered. The operator must press the reset pushbutton.</td>
</tr>
</tbody>
</table>

Table 12: Status LEDs

The OFF state and ON state LEDs can be found in multiple locations on the safety laser scanner. Three sets are arranged in pairs on the base of the optics cover. These LEDs can also be seen in many cases when it is not possible to see the display, e.g. due to the mounting situation or because it is hidden from the operator’s position.

More information about what the LEDs mean and the symbols and information shown on the display: see "Troubleshooting", page 121.

8.4 Thorough check

Requirements for the thorough check during commissioning and in certain situations

The protective device and its application must be thoroughly checked in the following situations:

- Before commissioning
- After changes to the configuration or the safety function
- After changes to the mounting, the alignment or the electrical connection
- After exceptional events, for example after tampering has been detected, after modification of the machine or after replacing components

The thorough check ensures the following:

- Compliance with all relevant regulations and effectiveness of the protective device for all of the machine’s operating modes. This includes the following points:
  - compliance with standards
  - correct use of the protective device
  - suitable configuration and safety function
  - correct alignment
- The documentation matches the state of the machine, incl. the protective device
- The verified configuration report matches the desired project planning (see "Verifying configuration", page 100)
The thorough checks must be carried out by qualified safety personnel or specially qualified and authorized personnel and must be documented in a traceable manner.

**Recommended thorough checks**

In many cases, it makes sense to carry out the following thorough checks during commissioning and in certain situations:

- Thorough check of the relevant points on the checklist, see "Checklist for initial commissioning and commissioning", page 152
- Thorough visual check of the machine and the protective device, page 62
- Thorough check of the principal function of the protective device, page 60
- Thorough check of the area to be protected, page 61
- Make sure that the operating personnel has been instructed in the protective device’s function before starting work on the machine. The instruction is the responsibility of the machine operator and must be carried out by qualified personnel.
9 Operation

9.1 Safety

**DANGER**
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Maintenance work, alignment work, fault diagnoses, and any changes to the integration of the protective device in the machine must only be carried out by qualified personnel.
- The effectiveness of the protective device must be checked following such work.

**NOTE**
This document does not provide instructions for operating the machine in which the safety laser scanner is integrated.

9.2 Regular thorough check

The protective device must be checked regularly. The type and frequency of thorough checks is defined by the manufacturer and the operating entity of the machine, see "Testing plan", page 59.

The regular thorough checks serve to investigate the effectiveness of the protective device and detect any ineffectiveness due to modifications or external influences (such as damage or tampering).

- Carry out the thorough checks according to the instructions from the manufacturer and the machine operator.

9.3 LEDs

![Figure 65: microScan3 – LEDs](image)

1. Status LEDs
2. Additional LEDs

Four status LEDs are located directly above the display.
Table 13: Status LEDs

<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
<th>Color</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>OFF state</td>
<td>Red</td>
<td>Shines red when the OSSD pair is in the OFF state.</td>
</tr>
<tr>
<td>2</td>
<td>ON state</td>
<td>Green</td>
<td>Shines green when the OSSD pair is in the ON state.</td>
</tr>
<tr>
<td>3</td>
<td>Warning field</td>
<td>Yellow</td>
<td>Shines yellow if at least one warning field is interrupted.</td>
</tr>
<tr>
<td>4</td>
<td>Restart interlock</td>
<td>Yellow</td>
<td>Flashes if restart interlock is configured with reset and the restart interlock has been triggered. The operator must press the reset pushbutton.</td>
</tr>
</tbody>
</table>

The OFF state and ON state LEDs can be found in multiple locations on the safety laser scanner. Three sets are arranged in pairs on the base of the optics cover. These LEDs can also be seen in many cases when it is not possible to see the display, e.g. due to the mounting situation or because it is hidden from the operator’s position.

9.4 Buttons and display

The safety laser scanner is equipped with four buttons and a graphical display. You can use the buttons to show information on the display and make simple settings.

NOTE
The display language is set using Safety Designer during configuration. The display language and the configuration cannot be changed using the buttons on the display.
Buttons

Figure 67: Buttons on microScan3

1. You can use the arrow buttons to change between various displays and menu items.
2. You can use the back button to change to the previous display or a higher-level menu item.
3. You can use the OK button to show details for current information or confirm a menu point. Press the OK button twice to call up the menu.

If you do not press any pushbuttons for a time, the display changes back to the status display.

Status display

The display shows current information about the safety laser scanner’s status. The display switches off after approx. 60 s if all fields are clear and no other notification is displayed.

- If the display is switched off, press any pushbutton to activate the display.
- Press any pushbutton to obtain more details about the displayed status information.
- If there are a number of pages with detailed information, this is shown in the top right of the display.
- Press the arrow buttons to change between a number of pages with detailed information.

<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Green Check]</td>
<td>All devices and configurations</td>
<td>All fields clear, OSSD pair in ON state. The number at bottom right indicates the active monitoring case.</td>
</tr>
<tr>
<td>![Red X]</td>
<td>Devices with an OSSD pair</td>
<td>OSSD pair in OFF state.</td>
</tr>
<tr>
<td>![Red Down Arrow]</td>
<td>Configuration with restart interlock</td>
<td>Protective field is clear, reset can take place.</td>
</tr>
</tbody>
</table>

Table 14: Overview of status information
<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Configuration with automated restart after a time" /></td>
<td>Configuration with automated restart after a time</td>
<td>Protective field is clear, configured time to restart expires.</td>
</tr>
<tr>
<td><img src="image" alt="Warning field interrupted" /></td>
<td>Configuration with at least one warning field</td>
<td>Warning field interrupted (left column: number of interrupted warning fields, right column: number of warning fields in the current monitoring case).</td>
</tr>
<tr>
<td><img src="image" alt="All devices and configurations" /></td>
<td>All devices and configurations</td>
<td>Fault. All safety outputs in the OFF state. More information: see &quot;Fault display&quot;, page 125.</td>
</tr>
<tr>
<td><img src="image" alt="Contamination warning" /></td>
<td>All devices and configurations</td>
<td>Contamination warning. Check the optics cover for damage. Clean the optics cover.</td>
</tr>
<tr>
<td><img src="image" alt="Contamination fault" /></td>
<td>All devices and configurations</td>
<td>Contamination fault. All safety outputs in the OFF state. Check the optics cover for damage. Clean the optics cover.</td>
</tr>
<tr>
<td><img src="image" alt="Fault in the external device monitoring" /></td>
<td>Configuration with external device monitoring (EDM)</td>
<td>Fault in the external device monitoring (EDM). OSSD pair in OFF state.</td>
</tr>
<tr>
<td><img src="image" alt="Tamper protection" /></td>
<td>Configuration with reference contour field</td>
<td>Tamper protection. The safety laser scanner does not detect a contour in the set tolerance band. All safety outputs in the OFF state.</td>
</tr>
<tr>
<td><img src="image" alt="Tamper protection" /></td>
<td>All devices and configurations</td>
<td>Tamper protection. The safety laser scanner does not detect a contour in an area of at least 90° (maximum measuring range 40 m). All safety outputs in the OFF state.</td>
</tr>
<tr>
<td><img src="image" alt="Safety function stopped" /></td>
<td>All devices and configurations</td>
<td>Safety function stopped. All safety outputs in the OFF state. Restart the device using the keypad or Safety Designer.</td>
</tr>
<tr>
<td><img src="image" alt="Application stopped" /></td>
<td>All devices and configurations</td>
<td>A valid input signal is not yet applied at the control inputs. All safety outputs in the OFF state. After switching on, the safety laser scanner waits for a valid input signal. During this time, an invalid input signal does not result in a fault.</td>
</tr>
</tbody>
</table>

*Table 14: Overview of status information*
<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>![No Configuration!]</td>
<td>All devices</td>
<td>The device is not configured. The device is in the as-delivered state or has been reset to factory settings. All safety outputs in the OFF state.</td>
</tr>
<tr>
<td>![Passive State!]</td>
<td>All devices and configurations</td>
<td>Passive state. All safety outputs in the OFF state. Press any pushbutton to obtain more information.</td>
</tr>
</tbody>
</table>

Table 14: Overview of status information

Menu

The menu offers access to the three main areas: device information, diagnostics information and settings.

- Press the OK button ④ twice in succession to call up the menu.
- Change to the desired menu point using the arrow buttons ①, ②.
- Confirm the desired menu point using the OK button ④.
- Use the same pushbuttons to navigate through the submenus.
- Press the back button ③ to return to the higher-level menu point.
- Press the back button ③ multiple times to return to the status display. If you do not press any pushbuttons for a time, the display likewise changes back to the status display.

Device information

You will find information about the following subjects in the device information area:

- Hardware: for example type code, material number, serial numbers, firmware versions
- Configuration: for example device name, application name, checksum, date of last configuration

Diagnostics

You will find information about the following subjects in the diagnostics area:

- Intrusion history: position and time of the last 10 objects in a protective field that have led to an OSSD pair switching to the OFF state.
- Message history: code and designation of the last 10 error messages.
- Service: operating hours, number of power-ups, currently measured contamination of the optics cover.

Settings

You have the following options in the settings area:

- Set the display’s brightness and contrast.
- Restart the safety laser scanner.
10 Maintenance

10.1 Safety

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

► Do not carry out any repairs to the device components.
► Do not make any changes to or tamper with the device components.
► With the exception of the procedures described in this document, the device components must not be opened.

10.2 Regular cleaning

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

► Regularly check the degree of contamination on all components based on the application conditions.

Depending on the ambient conditions, the optics cover must be cleaned regularly and in the event of contamination. For example, static charges can cause dust particles to be attracted to the optics cover.

NOTE
The display shows a contamination warning if the optics cover is contaminated and needs to be cleaned soon. If it is not cleaned and the contamination continues to increase, the safety laser scanner switches to the OFF state for safety reasons and the display shows a contamination fault.

► Check the optics cover for damage.
► Clean the optics cover in time.

DANGER
Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

► Make sure that the optical properties of the optics cover are not changed by:
  ○ beading water, mist, frost, or ice formation. If necessary, remove any residues of this type or any other form of contamination and restart the safety laser scanner.
  ○ Damage. Replace damaged optics covers.
  ○ Substances containing oil or fat. Substances like this may impair the detection capability of the safety laser scanner. Therefore keep the optics cover free from substances containing oil or fat.
DANGER
Hazard due to unexpected starting of the machine

➤ Make sure that the dangerous state of the machine is and remains switched off during cleaning.
➤ Make sure that the safety laser scanner’s outputs do not affect the machine during cleaning.

NOTICE

➤ Do not use aggressive or abrasive cleaning agents.
➤ We recommend anti-static cleaning agents.
➤ We recommend using the anti-static plastic cleaner (SICK product number 5600006) and the SICK lens cloth (SICK product number 4003353).

Clean the optics cover as follows
1. Use a clean, soft brush to remove dust from the optics cover.
2. Moisten a clean, soft towel with anti-static plastic cleaner and use it to wipe the optics cover.
3. Check the effectiveness of the protective device, see "Thorough check of the principal function of the protective device", page 60.

10.3 Replacing the optics cover

If the optics cover is scratched or damaged, you must replace the optics cover. Order the replacement optics cover from SICK (see "Spare parts", page 143).

DANGER
Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

During operation, the safety laser scanner constantly measures the degree of contamination on the optics cover. For a new optics cover to function perfectly, an optics cover calibration needs to be carried out initially. This serves as a reference for contamination measurement (status = uncontaminated).

➤ Carry out an optics cover calibration every time the optics cover is replaced.
➤ Carry out the optics cover calibration at room temperature (10 °C to 30 °C).
➤ Only carry out the optics cover calibration using a new optics cover.
➤ Make sure that the entire system is clear of contamination when the calibration is carried out.
NOTICE

- The safety laser scanner’s optics cover is an optical component. Make sure that the optics cover does not become dirty or scratched during unpacking and mounting. Prevent fingerprints on the optics cover. Wear the gloves supplied with the new optics cover during replacement.
- The optics cover may only be replaced by qualified safety personnel in a dust- and dirt-free environment.
- Never replace the optics cover during continuous operation, as dust particles could penetrate into the safety laser scanner.
- You must prevent contamination on the inside of the optics cover, for example due to fingerprints.
- Do not use an additional sealant, such as silicone, for sealing the optics cover. Any vapors that are created may damage the optical components.
- Mount the optics cover according to the following instructions, to ensure IP65 leak tightness of the housing.
- Use new optics covers exclusively as a replacement.
- You must provide ESD protection during the replacement of the optics cover.

NOTICE

Enclosure rating IP65 only applies if the safety laser scanner is closed and the system plug is mounted.

Replace the optics cover as follows:

Tool required:
- TX10 torque wrench

![Diagram of fixing screws for the optics cover]

Figure 69: Fixing screws for the optics cover

1. Fixing screw

1. Make sure that the environment is clean and clear of fog, moisture, and dust.
2. First, clean the safety laser scanner from the outside, so that no foreign bodies penetrate into the open device.
3. Unscrew the fixing screws for the optics cover.
4. Slowly and carefully detach the optics cover from the safety laser scanner. If the optics cover’s seal sticks to the safety laser scanner, carefully detach the optics cover using a screwdriver.

5. If necessary, remove contamination from the sealing groove and the bearing surface of the safety laser scanner. Use residue-free plastic cleaners (see "Cleaning agent", page 146).

6. Check whether the mirror on the motor is dirty and, if necessary, remove dirt using an optic brush.

7. Set 1.0 Nm tightening torque on the torque wrench.

8. During the following steps, wear the gloves supplied with the new optics cover.

9. Take the new optics cover out of the packaging and remove the seal’s protective cap.

10. Remove any packaging residue if necessary.

11. Carefully push the optics cover over the mirror. Make sure that the optics cover does not touch the mirror.

12. Place the optics cover onto the safety laser scanner. Make sure that the optics cover rests over the whole area without any gaps.

13. Screw in new fixing screws, see figure 69, page 116.

14. Tighten the screws using the set tightening torque.

15. Make sure that the optics cover is clear of dirt and damage.

**Recommission the safety laser scanner as follows**

1. Properly remount the safety laser scanner, see "Mounting", page 63.

2. Recreate all of the electrical connections to the safety laser scanner.

3. Carry out the optics cover adjustment, see "Optics cover calibration", page 104.

4. Start the safety function using Safety Designer, see "Starting and stopping safety function", page 101.

5. Check the effectiveness of the protective device.
   - Generally, the protective device is checked exactly as during commissioning, see "Thorough check", page 107.
   - If during the project planning the possible tolerances of the device have been considered and it is ensured that neither the configuration nor the wiring, nor the alignment of the safety laser scanner have been changed, a function test is sufficient, see "Thorough check of the principal function of the protective device", page 60.

### 10.4 Replacing the safety laser scanner

If the safety laser scanner is damaged or defective, you must replace it.

**DANGER**

Hazard due to lack of effectiveness of the protective device

Persons and parts of the body to be protected may not be recognized in case of non-observance.

If an unsuitable configuration is saved in the system plug, the dangerous state is not ended or is not ended in time.

- Make sure that after replacement, the same system plug or a system plug with the same configuration is used.
- Make sure that the safety laser scanner is aligned correctly after the replacement.

**NOTICE**

Enclosure rating IP65 only applies if the safety laser scanner is closed and the system plug is mounted.
NOTICE
Plug in the system plug carefully.
Do not force it.
The contacts may break off or bend if too much force is used.

Tool required:
- TX10 Torx wrench
- TX20 Torx wrench

10.4.1 Replacing the safety laser scanner without system plug

In many cases, you can reuse the existing bracket and the existing system plug. Detach the defective safety laser scanner from the bracket and the system plug. Then, mount the new safety laser scanner on the bracket and the system plug. When the new safety laser scanner is switched on for the first time, it reads the configuration from the system plug and can be used without having to be reconfigured.

Procedure:
1. Make sure that the environment is clean and clear of fog, moisture, and dust.
2. Unscrew screws in the system plug and remove the system plug from the defective safety laser scanner.
3. Unscrew screws from the bracket and remove the defective safety laser scanner from the bracket.
4. Remove the protective film from the opening on the new safety laser scanner.
5. Mount the system plug on the new safety laser scanner, see "Replacing the system plug", page 119.
6. Mount the new safety laser scanner, see "Mounting", page 63.
7. Check the effectiveness of the protective device.
   - Generally, the protective device is checked exactly as during commissioning, see "Thorough check", page 107.
   - If during the project planning the possible tolerances of the device have been considered and it is ensured that neither the configuration nor the wiring, nor the alignment of the safety laser scanner have been changed, a function test is sufficient, see "Thorough check of the principal function of the protective device", page 60.

NOTE
In certain cases (in the event of dust, high air humidity), it may make sense not to disconnect the system plug and the safety laser scanner initially. In these cases, proceed as follows:
1. Disconnect the M12 plug connector from the system plug.
2. Unscrew screws from the bracket and remove the defective safety laser scanner from the bracket.
3. Move the safety laser scanner with the system plug to a clean location (e.g., office, maintenance areas).
4. Unscrew screws in the system plug and remove the system plug from the defective safety laser scanner.
5. See above for further steps.

10.4.2 Completely replacing the safety laser scanner

1. Disconnect the M12 plug connector from the system plug.
2. Unscrew screws from the bracket and remove the defective safety laser scanner from the bracket.
3. Mount the new safety laser scanner, see "Mounting", page 63.
4. Configure the safety laser scanner, see "Configuration", page 73.
5. Perform commissioning again, taking particular care to conduct all of the thorough checks described, see "Commissioning", page 105.

10.5 Replacing the system plug

If the system plug is damaged or defective, you must replace it.

**NOTICE**
Enclosure rating IP65 only applies if the safety laser scanner is closed and the system plug is mounted.

**NOTICE**
Plug in the system plug carefully.
Do not force it.
The contacts may break off or bend if too much force is used.

microScan3 Core I/O: replacing the system plug

Tool required:
- TX10 Torx wrench

Procedure:
1. Make sure that the environment is clean and clear of fog, moisture, and dust.
2. Disconnect the M12 plug connector from the system plug.
3. If necessary: move the safety laser scanner to a clean location.
4. Unscrew screws in the defective system plug and remove the system plug from the safety laser scanner.
5. Make sure that the seal is seated correctly (①).
6. Carefully place the new system plug onto the safety laser scanner at the back (②).
7. Carefully fold the system plug onto the safety laser scanner (③).
8. Screw in the system plug using the captive screws. Tightening torque: 1.4 Nm
9. Perform commissioning again, see "Commissioning", page 105. In particular, carry out all of the described thorough checks, see "Thorough check", page 107.

![Figure 70: Mount the system plug on the microScan3 Core I/O](image-url)
10.6 Regular thorough check

The protective device must be checked regularly. The type and frequency of thorough checks is defined by the manufacturer and the operating entity of the machine, see "Testing plan", page 59.

The regular thorough checks serve to investigate the effectiveness of the protective device and detect any ineffectiveness due to modifications or external influences (such as damage or tampering).

- Carry out the thorough checks according to the instructions from the manufacturer and the machine operator.
11 Troubleshooting

11.1 Safety

DANGER Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
- Immediately put the machine out of operation if the behavior of the machine cannot be clearly identified.
- Immediately put the machine out of operation if you cannot clearly identify or allocate the fault, or if you cannot safely remedy the fault.
- Secure the machine such that it cannot be switched on unintentionally.

DANGER Hazard due to unexpected starting of the machine
- When any work is taking place, use the protective device to secure the machine or to ensure that the machine is not switched on unintentionally.

DANGER Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.
- Do not carry out any repairs to the device components.
- Do not make any changes to or tamper with the device components.
- With the exception of the procedures described in this document, the device components must not be opened.

NOTE If you cannot remedy the fault with the help of the information provided in this chapter, please contact your respective SICK subsidiary.

11.2 Diagnostic LEDs

The safety laser scanner has diagnostic LEDs for initial diagnostics. Every safety laser scanner has four status LEDs above the display.

11.2.1 Status LEDs

Four status LEDs are located directly above the display.

Figure 71: Status LEDs
<table>
<thead>
<tr>
<th>Number</th>
<th>Function</th>
<th>Color</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>①</td>
<td>OFF state</td>
<td>Red</td>
<td>Shines red when the OSSD pair is in the OFF state.</td>
</tr>
<tr>
<td>②</td>
<td>ON state</td>
<td>Green</td>
<td>Shines green when the OSSD pair is in the ON state.</td>
</tr>
<tr>
<td>③</td>
<td>Warning field</td>
<td>Yellow</td>
<td>Shines yellow if at least one warning field is interrupted.</td>
</tr>
<tr>
<td>④</td>
<td>Restart interlock</td>
<td>Yellow</td>
<td>Flashes if restart interlock is configured with reset and the restart interlock has been triggered. The operator must press the reset pushbutton.</td>
</tr>
</tbody>
</table>

Table 15: Status LEDs

The OFF state and ON state LEDs can be found in multiple locations on the safety laser scanner. Three sets are arranged in pairs on the base of the optics cover. These LEDs can also be seen in many cases when it is not possible to see the display, e.g. due to the mounting situation or because it is hidden from the operator's position.

11.3 Diagnostics using the display

The display supplies information about the status of the safety laser scanner, and for diagnostics and troubleshooting.

11.3.1 Status display

The display shows current information about the safety laser scanner’s status. The display switches off after approx. 60 s if all fields are clear and no other notification is displayed.

- If the display is switched off, press any pushbutton to activate the display.
- Press any pushbutton to obtain more details about the displayed status information.
- If there are a number of pages with detailed information, this is shown in the top right of the display.
- Press the arrow buttons to change between a number of pages with detailed information.

<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Green Check]</td>
<td>All devices and configurations</td>
<td>All fields clear, OSSD pair in ON state. The number at bottom right indicates the active monitoring case.</td>
</tr>
<tr>
<td>![Red X]</td>
<td>Devices with an OSSD pair</td>
<td>OSSD pair in OFF state.</td>
</tr>
<tr>
<td>![Arrow]</td>
<td>Configuration with restart interlock</td>
<td>Protective field is clear, reset can take place.</td>
</tr>
<tr>
<td>![Hourglass]</td>
<td>Configuration with automated restart after a time</td>
<td>Protective field is clear, configured time to restart expires.</td>
</tr>
</tbody>
</table>

Table 16: Overview of status information
<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>!01/02</td>
<td>Configuration with at least one warning field</td>
<td>Warning field interrupted (left column: number of interrupted warning fields, right column: number of warning fields in the current monitoring case).</td>
</tr>
<tr>
<td>!C1 fault</td>
<td>All devices and configurations</td>
<td>Fault. All safety outputs in the OFF state. More information: see &quot;Fault display&quot;, page 125.</td>
</tr>
<tr>
<td>!Display flashes</td>
<td>All devices and configurations</td>
<td>Contamination warning. Check the optics cover for damage. Clean the optics cover.</td>
</tr>
<tr>
<td>!Display flashes</td>
<td>All devices and configurations</td>
<td>Contamination fault. All safety outputs in the OFF state. Check the optics cover for damage. Clean the optics cover.</td>
</tr>
<tr>
<td>!Configuration with external device monitoring (EDM)</td>
<td></td>
<td>Fault in the external device monitoring (EDM). OSSD pair in OFF state.</td>
</tr>
<tr>
<td>!Configuration with reference contour field</td>
<td></td>
<td>Tamper protection. The safety laser scanner does not detect a contour in the set tolerance band. All safety outputs in the OFF state.</td>
</tr>
<tr>
<td>!X!&lt;</td>
<td>All devices and configurations</td>
<td>Tamper protection. The safety laser scanner does not detect a contour in an area of at least 90° (maximum measuring range 40 m). All safety outputs in the OFF state.</td>
</tr>
<tr>
<td>!Application stopped</td>
<td>All devices and configurations</td>
<td>Safety function stopped. All safety outputs in the OFF state. Restart the device using the keypad or Safety Designer.</td>
</tr>
<tr>
<td>!Waiting for inputs</td>
<td>All devices and configurations</td>
<td>A valid input signal is not yet applied at the control inputs. All safety outputs in the OFF state. After switching on, the safety laser scanner waits for a valid input signal. During this time, an invalid input signal does not result in a fault.</td>
</tr>
<tr>
<td>!No Configuration!</td>
<td>All devices</td>
<td>The device is not configured. The device is in the as-delivered state or has been reset to factory settings. All safety outputs in the OFF state.</td>
</tr>
</tbody>
</table>

*Table 16: Overview of status information*
Table 16: Overview of status information

<table>
<thead>
<tr>
<th>Display</th>
<th>Device or configuration</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="display" /></td>
<td>All devices and configurations</td>
<td>Passive state. All safety outputs in the OFF state. Press any pushbutton to obtain more information.</td>
</tr>
</tbody>
</table>

11.3.2 Detailed diagnostics

The safety laser scanner is equipped with four buttons and a graphical display. You can use the buttons to show information on the display and make simple settings.

**NOTE**
The display language is set using Safety Designer during configuration. The display language and the configuration cannot be changed using the buttons on the display.

**Buttons**

![Buttons on microScan3](image)

1. You can use the arrow buttons to change between various displays and menu items.
2. You can use the back button to change to the previous display or a higher-level menu item.
3. You can use the OK button to show details for current information or confirm a menu point. Press the OK button twice to call up the menu.

If you do not press any pushbuttons for a time, the display changes back to the status display.

**Menu**

![Menu](image)

The menu offers access to the three main areas: device information, diagnostics information and settings.
Press the OK button ④ twice in succession to call up the menu.
Change the desired menu point using the arrow buttons ①, ②.
Confirm the desired menu point using the OK button ④.
Use the same pushbuttons to navigate through the submenus.
Press the back button ③ to return to the higher-level menu point.
Press the back button ③ multiple times to return to the status display. If you do not press any pushbuttons for a time, the display likewise changes back to the status display.

Device information
You will find information about the following subjects in the device information area:
• Hardware: for example type code, material number, serial numbers, firmware versions
• Configuration: for example device name, application name, checksum, date of last configuration

Diagnostics
You will find information about the following subjects in the diagnostics area:
• Intrusion history: position and time of the last 10 objects in a protective field that have led to an OSSD pair switching to the OFF state.
• Message history: code and designation of the last 10 error messages.
• Service: operating hours, number of power-ups, currently measured contamination of the optics cover.

Settings
You have the following options in the settings area:
• Set the display’s brightness and contrast.
• Restart the safety laser scanner.

11.3.3 Fault display
If there is a fault, the display shows a warning symbol, a type of fault and a fault code on a red flashing background.

![C1 fault](image)

**Figure 74: Fault display**

- The two-character fault type will help you during troubleshooting.
- The eight-character fault code in the bottom line helps SICK support during the detailed fault analysis.
- By pressing any pushbutton, you will obtain more information about the fault and for troubleshooting. You can use the arrow buttons to change to further pages with additional information.
- You will find an overview of the two-character fault types and what they mean in the following table.
- You will find detailed information in Safety Designer’s message history about the individual faults and information about events not shown by the display.
<table>
<thead>
<tr>
<th>Fault type</th>
<th>Brief description</th>
<th>Cause</th>
<th>Troubleshooting</th>
</tr>
</thead>
<tbody>
<tr>
<td>C1</td>
<td>Faulty configuration</td>
<td>The configuration is faulty.</td>
<td>Reconfigure the device.</td>
</tr>
<tr>
<td>C2</td>
<td>Incompatible configuration</td>
<td>The configuration in the system plug does not match the device's functionality.</td>
<td>Check the device variant. Replace the device or reconfigure the device.</td>
</tr>
<tr>
<td>C3</td>
<td>Incompatible firmware</td>
<td>The configuration in the system plug does not match the device's firmware version.</td>
<td>Check the device's firmware version. Replace the device or reconfigure the device.</td>
</tr>
<tr>
<td>E1</td>
<td>Fault in the safety laser scanner</td>
<td>The safety laser scanner has an internal fault.</td>
<td>Perform a device restart using the display or Safety Designer or interrupt the power supply for at least 2 seconds. If this does not rectify the fault, replace the safety laser scanner and send it to the manufacturer for repair.</td>
</tr>
<tr>
<td>E2</td>
<td>Fault in the system plug</td>
<td>The system plug has an internal fault.</td>
<td>Perform a device restart using the display or Safety Designer or interrupt the power supply for at least 2 seconds. If this does not fix the fault, replace the system plug.</td>
</tr>
<tr>
<td>E3</td>
<td>Fault in the system plug</td>
<td>The system plug has an internal fault.</td>
<td>Perform a device restart using the display or Safety Designer or interrupt the power supply for at least 2 seconds. If this does not fix the fault, replace the system plug.</td>
</tr>
<tr>
<td>E4</td>
<td>Incompatible system plug</td>
<td>The system plug is unsuitable for the safety laser scanner.</td>
<td>Check the part number or the type code. Replace the system plug.</td>
</tr>
<tr>
<td>F1</td>
<td>Current too high at an OSSD</td>
<td>The current is too high at an OSSD. The limit has been exceeded for current allowed short-term or permanently.</td>
<td>Check the connected switching element.</td>
</tr>
<tr>
<td>F2</td>
<td>OSSD short-circuit to 24 V</td>
<td>There is a short-circuit to 24 V at an OSSD.</td>
<td>Check the wiring.</td>
</tr>
<tr>
<td>F3</td>
<td>OSSD short-circuit to 0 V</td>
<td>There is a short-circuit to 0 V at an OSSD.</td>
<td>Check the wiring.</td>
</tr>
<tr>
<td>F4</td>
<td>Short-circuit between two OSSDs</td>
<td>There is a short-circuit between two OSSDs.</td>
<td>Check the wiring.</td>
</tr>
</tbody>
</table>

Table 17: Fault types
<table>
<thead>
<tr>
<th>Fault type</th>
<th>Brief description</th>
<th>Cause</th>
<th>Troubleshooting</th>
</tr>
</thead>
<tbody>
<tr>
<td>F9</td>
<td>General OSSD fault</td>
<td>At least one OSSD is showing unexpected behavior.</td>
<td>Check the wiring of the OSSDs.</td>
</tr>
<tr>
<td>L2</td>
<td>Invalid configuration of the external device monitoring (EDM)</td>
<td>The configuration of the external device monitoring (EDM) is invalid. The configuration is unsuitable for the wiring.</td>
<td>Check whether the external device monitoring is connected correctly. Use Safety Designer to check the configuration.</td>
</tr>
<tr>
<td>L3</td>
<td>Fault in the external device monitoring (EDM)</td>
<td>A faulty signal is applied at the external device monitoring (EDM). The allowed tolerance time has been exceeded.</td>
<td>Check whether the connectors are wired correctly and operating correctly.</td>
</tr>
<tr>
<td>L8</td>
<td>Fault in the reset input</td>
<td>An invalid signal is applied at a reset input. The reset button has been pressed for too long, has been pressed too frequently, or is defective.</td>
<td>Check whether the reset pulse fulfills the requirements.</td>
</tr>
<tr>
<td>L9</td>
<td>Short-circuit at the reset input</td>
<td>Exactly the same signal is applied at a reset input as at another input, an OSSD or an output. There is possibly a short-circuit.</td>
<td>Check the wiring for cross-circuits.</td>
</tr>
<tr>
<td>N1</td>
<td>Invalid input signal</td>
<td>The signal applied at the control inputs is not assigned to a monitoring case. The signal is applied for longer than the set input delay + 1 s.</td>
<td>Use Safety Designer to check the configuration. Check the machine’s work process.</td>
</tr>
<tr>
<td>N2</td>
<td>Defective sequence of monitoring cases</td>
<td>The current input conditions do not match the configured sequence of monitoring cases.</td>
<td>Use Safety Designer to check the configuration. Check the machine’s work process.</td>
</tr>
<tr>
<td>N3</td>
<td>Invalid input signal</td>
<td>The signal applied at the static control inputs does not match the complementary condition. The signal is applied for longer than the set input delay + 1 s.</td>
<td>Check the control of the control inputs.</td>
</tr>
<tr>
<td>T1</td>
<td>Temperature error</td>
<td>The Safety laser scanner’s operating temperature has exceeded or fallen below the permitted range.</td>
<td>Check whether the safety laser scanner is being operated in accordance with the permissible ambient conditions.</td>
</tr>
</tbody>
</table>

*Table 17: Fault types*
### Diagnostics using Safety Designer

The following diagnostics tools are available in the device window:

- Data recorder
- Message history

The following interfaces are suitable for diagnostics:

- USB 2.0 mini-B (female connector). The USB connection may only be used temporarily and only for configuration and diagnostics.

#### Data recorder

You can use the data recorder to record the device’s signals continuously. The measurement data are not transmitted and shown for every scan cycle, depending on the interface and your capacity.
The data is saved in a data recorder diagnostics file.

The data recorder diagnostics file can be run in the data recorder.

1. Import configuration from the device.
2. Drag the signals you would like to record from the signal list on the right and drop them into the data recorder area.

- Start recording
- Stop recording
- Change settings

**Typical applications**

- Check spatial geometry
- Check where a person can stay or when a person is detected
- Check input information about the current monitoring case
- Check why OSSDs have switched
11.4.2 Message history

![Message history diagram]

**Figure 76: Message history**

1. Message history
2. Display filter
3. Details about the selected message

All events, such as faults, warnings and information are stored in the message history. Safety Designer shows details about the events in the bottom part of the window, ways to solve them are also shown.
12 Decommissioning

12.1 Protection of the environment

The safety laser scanner is designed to minimize its impact on the environment. It uses a minimum of energy and resources.

- Always act in an environmentally responsible manner at work. For this reason, please note the following information regarding disposal.

12.2 Disposal

Always dispose of serviceability devices in compliance with local/national rules and regulations with respect to waste disposal.

NOTE

We would be pleased to be of assistance on the disposal of this device. Contact us.
13  Technical data

13.1  Variant overview

Ordering information: see "microScan3 ordering information", page 142.

microScan3 Core
- A maximum of eight fields can be configured
- Available as microScan3 Core I/O with local inputs and outputs
- microScan3 core I/O with three universal I/Os

<table>
<thead>
<tr>
<th>Type code</th>
<th>OSSD pairs</th>
<th>Protective field range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MICS3-AAAZ40AZ1P01</td>
<td>1</td>
<td>≤ 4.0 m</td>
</tr>
<tr>
<td>MICS3-AAAZ55AZ1P01</td>
<td>1</td>
<td>≤ 5.5 m</td>
</tr>
</tbody>
</table>

*Table 18: Variants of the microScan3 Core I/O*

13.2  Data sheet

13.2.1  microScan3 Core

Features

<table>
<thead>
<tr>
<th>Feature</th>
<th>microScan3 Core I/O</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protective field range</td>
<td></td>
</tr>
<tr>
<td>Devices with a max. protective field range of 4.0 m</td>
<td>≤ 4.0 m, details: see &quot;Sensing range&quot;, page 139</td>
</tr>
<tr>
<td>Devices with a max. protective field range of 5.5 m</td>
<td>≤ 5.5 m, details: see &quot;Sensing range&quot;, page 139</td>
</tr>
<tr>
<td>Warning field range</td>
<td>≤ 40 m</td>
</tr>
<tr>
<td>Fields</td>
<td>≤ 8</td>
</tr>
<tr>
<td>Simultaneously monitored fields</td>
<td>≤ 4</td>
</tr>
<tr>
<td>Field sets</td>
<td>≤ 8</td>
</tr>
<tr>
<td>Monitoring cases</td>
<td>≤ 2</td>
</tr>
<tr>
<td>Scanning angle</td>
<td>275° (–47.5° … 227.5°)</td>
</tr>
<tr>
<td>Protective field resolution</td>
<td>30 mm, 40 mm, 50 mm, 70 mm, 150 mm, 200 mm</td>
</tr>
<tr>
<td>Angular resolution</td>
<td></td>
</tr>
<tr>
<td>Scan cycle time 30 ms</td>
<td>0.51°</td>
</tr>
<tr>
<td>Scan cycle time 40 ms</td>
<td>0.39°</td>
</tr>
<tr>
<td>Response time</td>
<td>≥ 70 ms, details: see &quot;Response times&quot;, page 137</td>
</tr>
<tr>
<td>Scan cycle time</td>
<td>30 ms or 40 ms (adjustable)</td>
</tr>
<tr>
<td>Generally necessary suggested protective field</td>
<td>65 mm</td>
</tr>
<tr>
<td>Supplement for retroreflectors on scan plane with distance &lt; 6 m to protective field boundary</td>
<td>350 mm</td>
</tr>
<tr>
<td>Deviation from ideal flatness of scan field at 5.5 m</td>
<td>≤ ±100 mm</td>
</tr>
</tbody>
</table>

*Table 19: microScan3 Core: features*
Table 19: microScan3 Core: features

### Safety technology parameters

<table>
<thead>
<tr>
<th>microScan3 Core I/O</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>Type 3 (EN 61496-1)</td>
</tr>
<tr>
<td>Safety integrity level</td>
<td>SIL 2 (IEC 61508)</td>
</tr>
<tr>
<td>Category</td>
<td>Category 3 (EN ISO 13849-1)</td>
</tr>
<tr>
<td>SIL claim limit</td>
<td>SILCL 2 (EN 62061)</td>
</tr>
<tr>
<td>Performance level</td>
<td>PL d (EN ISO 13849-1)</td>
</tr>
<tr>
<td>PFHₐ (mean probability of a dangerous failure per hour)</td>
<td>$8 \times 10^{-8}$</td>
</tr>
<tr>
<td>$T_m$ (mission time)</td>
<td>20 years (EN ISO 13849-1)</td>
</tr>
<tr>
<td>Safe state when a fault occurs</td>
<td>At least one OSSD is in the OFF state.</td>
</tr>
</tbody>
</table>

Table 20: microScan3 Core: safety technology parameters

### Interfaces

<table>
<thead>
<tr>
<th>microScan3 Core I/O</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>OSSD pairs</td>
<td>1</td>
</tr>
<tr>
<td>Automatic restart of OSSDs after</td>
<td>2 s ... 60 s (configurable)</td>
</tr>
<tr>
<td>Power supply</td>
<td>Male connector, M12, 8 pin, A-coded (common male connector for power supply and inputs and outputs)</td>
</tr>
<tr>
<td>Length of cable (power supply tolerance ±5%)</td>
<td>Length of cable with wire cross-section 0.25 mm² ≤ 35 m</td>
</tr>
<tr>
<td>Local inputs and outputs</td>
<td>Male connector, M12, 8 pin, A-coded (common male connector for power supply and inputs and outputs)</td>
</tr>
<tr>
<td>Length of cable with wire cross-section 0.25 mm²</td>
<td>≤ 35 m</td>
</tr>
<tr>
<td>Configuration and diagnostic interface</td>
<td>USB 2.0</td>
</tr>
<tr>
<td>Type of interface</td>
<td>USB 2.0 mini-B (female connector)</td>
</tr>
<tr>
<td>Transfer rate</td>
<td>≤ 12 Mbit/s</td>
</tr>
<tr>
<td>Length of cable</td>
<td>≤ 5 m</td>
</tr>
</tbody>
</table>

Table 21: microScan3 Core: interfaces
## Electrical data

<table>
<thead>
<tr>
<th>Operating data</th>
<th>microScan3 Core I/O</th>
</tr>
</thead>
<tbody>
<tr>
<td>Protection class</td>
<td>III (EN 61140/IEC 61140)</td>
</tr>
<tr>
<td>Supply voltage $U_v$</td>
<td>24 V DC (16.8 V ... 30 V DC) (SELV/PELV) (^1)</td>
</tr>
<tr>
<td>Residual ripple</td>
<td>±5% (^2)</td>
</tr>
<tr>
<td>Start-up current at 24 V</td>
<td>≤ 3 A</td>
</tr>
<tr>
<td>Current consumption at 24 V</td>
<td></td>
</tr>
<tr>
<td>- No output load</td>
<td>Typ. 0.3 A</td>
</tr>
<tr>
<td>- With maximum output load</td>
<td>Typ. 1.4 A</td>
</tr>
<tr>
<td>- In passive state, no output load</td>
<td>Typ. 0.27 A</td>
</tr>
<tr>
<td>Power consumption</td>
<td></td>
</tr>
<tr>
<td>- No output load</td>
<td>Typ. 7 W</td>
</tr>
<tr>
<td>- With maximum output load</td>
<td>Typ. 34 W</td>
</tr>
<tr>
<td>- In passive state, no output load</td>
<td>Typ. 6.5 W</td>
</tr>
<tr>
<td>Power-up delay</td>
<td>≤ 12 s</td>
</tr>
<tr>
<td>Safety outputs (OSSD)</td>
<td></td>
</tr>
<tr>
<td>Type of output</td>
<td>2 PNP semiconductors for each OSSD pair, short-circuit protected, cross-circuit monitored</td>
</tr>
<tr>
<td>Output voltage for ON state (HIGH)</td>
<td>$(U_v - 2.7 V) \ldots U_v$</td>
</tr>
<tr>
<td>Output voltage for OFF state (LOW)</td>
<td>0 V ... 2 V</td>
</tr>
<tr>
<td>Output current for ON state (HIGH)</td>
<td>≤ 250 mA per OSSD</td>
</tr>
<tr>
<td>Leakage current (^3)</td>
<td>≤ 250 µA</td>
</tr>
<tr>
<td>Load inductance</td>
<td>≤ 2.2 H</td>
</tr>
<tr>
<td>Load capacity</td>
<td>≤ 2.2 µF in series with 50 Ω</td>
</tr>
<tr>
<td>Switching frequency (no toggling and no simultaneous monitoring)</td>
<td>Depending on the load inductance</td>
</tr>
<tr>
<td>Permissible resistivity between load and device</td>
<td>≤ 2.5 Ω</td>
</tr>
<tr>
<td>Test pulse range</td>
<td>≤ 300 µs (typ. 230 µs)</td>
</tr>
<tr>
<td>Test pulse interval</td>
<td></td>
</tr>
<tr>
<td>- Scan cycle time 30 ms</td>
<td>240 ms ... 264 ms (typ. 240 ms)</td>
</tr>
<tr>
<td>- Scan cycle time 40 ms</td>
<td>320 ms ... 344 ms (typ. 320 ms)</td>
</tr>
<tr>
<td>Duration of OFF state</td>
<td>≥ 80 ms</td>
</tr>
<tr>
<td>Discrepancy time (offset between switching from OSSD2 and OSSD1 within an OSSD pair)</td>
<td>≤ 1 ms (typ. 25 µs)</td>
</tr>
</tbody>
</table>

| Universal output, universal I/O (configured as output) | |
| Output voltage HIGH | $(U_v - 3.7 V) \ldots U_v$ |

Table 22: microScan3 Core: electrical data
### microScan3 Core I/O

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output voltage LOW</td>
<td>0 V ... 2 V</td>
</tr>
<tr>
<td>Output current HIGH</td>
<td>≤ 200 mA</td>
</tr>
<tr>
<td>Leakage current</td>
<td>≤ 0.5 mA</td>
</tr>
<tr>
<td>Power-up delay</td>
<td>40 ms</td>
</tr>
<tr>
<td>Power-down delay</td>
<td>40 ms</td>
</tr>
<tr>
<td><strong>Static control input, universal input, universal I/O (configured as input)</strong></td>
<td></td>
</tr>
<tr>
<td>Input voltage HIGH</td>
<td>24 V (13 V ... 30 V)</td>
</tr>
<tr>
<td>Input voltage LOW</td>
<td>0 V (–30 V ... 5 V)</td>
</tr>
<tr>
<td>Input current HIGH</td>
<td>3 mA ... 6 mA</td>
</tr>
<tr>
<td>Input current LOW</td>
<td>0 mA ... 2 mA</td>
</tr>
<tr>
<td>Input resistance at HIGH</td>
<td>Typ. 5 kΩ</td>
</tr>
<tr>
<td>Input capacity</td>
<td>10 nF</td>
</tr>
<tr>
<td>Input frequency (max. switching frequency when used as control input)</td>
<td>≤ 20 Hz</td>
</tr>
<tr>
<td>Sampling time</td>
<td>4 ms</td>
</tr>
<tr>
<td>Response time at EDM after switching on OSSDs (when used as EDM input)</td>
<td>300 ms</td>
</tr>
<tr>
<td>Actuating duration of control switch for reset (when used as reset input)</td>
<td>60 ms ... 30 s</td>
</tr>
<tr>
<td>Actuating duration of the switch for standby (when used as standby input)</td>
<td>≥ 120 ms</td>
</tr>
</tbody>
</table>

**Table 22: microScan3 Core: electrical data**

1) The external power supply must bridge a brief power failure of 20 ms as specified in IEC 60204-1. Suitable power supplies are available as accessories from SICK.
2) The voltage level must not fall below the specified minimum voltage.
3) In the event of a fault (interruption of the 0 V cable), the specified leak current at most flows in the OSSD cable. The downstream control element must detect this state as the OFF state.

### Mechanical data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensions (W × H × D)</td>
<td>110 mm × 135 mm × 110 mm</td>
</tr>
<tr>
<td>Weight (including system plug)</td>
<td>1.15 kg</td>
</tr>
<tr>
<td>Housing material</td>
<td>Aluminum</td>
</tr>
<tr>
<td>Housing color</td>
<td>RAL 9005 (black) and RAL 1021 (colza yellow)</td>
</tr>
<tr>
<td>Optics cover material</td>
<td>Polycarbonate</td>
</tr>
<tr>
<td>Optics cover surface</td>
<td>Outside has a scratch-resistant coating</td>
</tr>
</tbody>
</table>

**Table 23: microScan3 Core: mechanical data**

### Ambient data

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Enclosure rating 1)</td>
<td>IP65 (IEC 60529)</td>
</tr>
</tbody>
</table>

**Table 24: microScan3 Core: ambient data**
<table>
<thead>
<tr>
<th>microScan3 Core I/O</th>
<th>Ambient operating temperature</th>
<th>-10 °C ... 50 °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Storage temperature</td>
<td>-25 °C ... 70 °C</td>
<td></td>
</tr>
<tr>
<td>Air humidity</td>
<td>≤ 95%, non-condensing</td>
<td></td>
</tr>
<tr>
<td>Vibration resistance 3)</td>
<td>IEC 60068-2-6</td>
<td></td>
</tr>
<tr>
<td></td>
<td>IEC 61496-1, clause 4.3.3.1 and 5.4.4.1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>CLC/TS 61496-3, clause 5.4.4.1</td>
<td></td>
</tr>
<tr>
<td>Frequency range</td>
<td>10 Hz ... 150 Hz</td>
<td></td>
</tr>
<tr>
<td>Amplitude</td>
<td>0.35 mm (10 Hz ... 60 Hz), 5 g (60 Hz ... 150 Hz)</td>
<td></td>
</tr>
<tr>
<td>Shock resistance 3)</td>
<td>IEC 60068-2-27</td>
<td></td>
</tr>
<tr>
<td>Standards</td>
<td>IEC 61496-3, clause 5.4.4.4.2 and clause 5.4.4.3</td>
<td></td>
</tr>
<tr>
<td>Single shock</td>
<td>15 g, 11 ms</td>
<td></td>
</tr>
<tr>
<td>Continuous shock</td>
<td>10 g, 16 ms</td>
<td></td>
</tr>
</tbody>
</table>

Table 24: microScan3 Core: ambient data

1) The specified enclosure rating is only valid if the safety laser scanner is closed, the system plug is mounted and all of the safety laser scanner’s M12 system plugs are closed using a male cable connector or using a protective cap.

2) IEC 61496-1, no. 4.3.1 and no. 5.4.2, CLC/TS 61496-3, no. 4.3.1 and no. 5.4.2. Condensation has an influence on normal operation.

3) In direct mounting.

Miscellaneous data

<table>
<thead>
<tr>
<th>microScan3 Core I/O</th>
<th>Wavelength</th>
<th>845 nm</th>
</tr>
</thead>
<tbody>
<tr>
<td>Detectable remission</td>
<td>1.8% ... several 1000%</td>
<td></td>
</tr>
<tr>
<td>Maximum homogeneous contamination of the optics cover without preventing the detection capability 3)</td>
<td>30%</td>
<td></td>
</tr>
<tr>
<td>Light beam diameter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>At front screen</td>
<td>18 mm</td>
<td></td>
</tr>
<tr>
<td>At 4.0 m distance</td>
<td>12 mm</td>
<td></td>
</tr>
<tr>
<td>At 5.5 m distance</td>
<td>20 mm</td>
<td></td>
</tr>
<tr>
<td>Divergence of collimated beam</td>
<td>0.17 °</td>
<td></td>
</tr>
<tr>
<td>Receiving angle</td>
<td>0.75 °</td>
<td></td>
</tr>
<tr>
<td>Pulse duration</td>
<td>Typ. 4 ns</td>
<td></td>
</tr>
<tr>
<td>Average output power</td>
<td>9.2 mW</td>
<td></td>
</tr>
<tr>
<td>Laser class</td>
<td>1M</td>
<td></td>
</tr>
</tbody>
</table>

Table 25: microScan3 Core: miscellaneous data

1) In the event of heavy contamination, the safety laser scanner displays a contamination fault and switches all safety outputs to the OFF state.
13.3 Response times

The protective device’s response time is the maximum time between the occurrence of the event leading to the sensor’s response and supply of the switch-off signal to the protective device’s interface (for example OFF state of the OSSD pair).

---

**DANGER**

Hazard due to lack of effectiveness of the protective device

In the case of non-compliance, it is possible that the dangerous state of the machine may not be stopped or not stopped in a timely manner.

In addition to the protective device’s response time, further signal transmission and processing also influence the time up until the end of the dangerous state. This includes a control’s processing time and the response times of downstream contactors, for example.

> Take the time for further signal transmission and processing into account.

---

**Response time**

The safety laser scanner’s response time depends on the following parameters:

- Scan cycle time
- Set interference protection
- Set multiple sampling

You can calculate the response time using the following formula:

\[ t_R = (t_S + t_I) \times n + t_O \]

The following rules apply:

- \( t_R \) = response time
- \( t_S \) = scan cycle time
  - Setting “40 ms”: \( t_S = 40 \) ms
  - Setting “30 ms”: \( t_S = 30 \) ms
- \( t_I \) = time for interference protection
  - Mode 1 (default): \( t_I = 0 \) ms
  - Mode 2: \( t_I = 1 \) ms
  - Mode 3: \( t_I = 2 \) ms
  - Mode 4: \( t_I = 3 \) ms
- \( n \) = set multiple sampling
  - Preset and with vertical protection \( n = 2 \).
  - Multiple sampling can be changed for the safety laser scanner or for each individual field (2 \( \leq n \leq 16 \)).
- \( t_O \) = time for processing and output
  - Dependent on output used:
    - OSSD pair 1: \( t_O = 10 \) ms

<table>
<thead>
<tr>
<th>Scan cycle time (t_S)</th>
<th>Interference protection, mode (t_I)</th>
<th>Output (t_O)</th>
<th>( t_R ) = response time for multiple sampling n</th>
</tr>
</thead>
<tbody>
<tr>
<td>30 ms</td>
<td>1 OSSD pair 1</td>
<td>n \times 30 \text{ ms} + 10 \text{ ms}</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 OSSD pair 1</td>
<td>n \times 31 \text{ ms} + 10 \text{ ms}</td>
<td></td>
</tr>
<tr>
<td></td>
<td>3 OSSD pair 1</td>
<td>n \times 32 \text{ ms} + 10 \text{ ms}</td>
<td></td>
</tr>
<tr>
<td></td>
<td>4 OSSD pair 1</td>
<td>n \times 33 \text{ ms} + 10 \text{ ms}</td>
<td></td>
</tr>
</tbody>
</table>

*Table 26: Response time of an individual safety laser scanner*
<table>
<thead>
<tr>
<th>Scan cycle time ($t_s$)</th>
<th>Interference protection, mode ($t_i$)</th>
<th>Output ($t_o$)</th>
<th>$t_R$ = response time for multiple sampling $n$</th>
</tr>
</thead>
<tbody>
<tr>
<td>40 ms</td>
<td>1 OSSD pair 1</td>
<td>$n \times 40\ ms + 10\ ms$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 OSSD pair 1</td>
<td>$n \times 41\ ms + 10\ ms$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>3 OSSD pair 1</td>
<td>$n \times 42\ ms + 10\ ms$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>4 OSSD pair 1</td>
<td>$n \times 43\ ms + 10\ ms$</td>
<td></td>
</tr>
</tbody>
</table>

Table 26: Response time of an individual safety laser scanner

13.4 Course of the OSSD test over time

The safety laser scanner tests the OSSDs at regular intervals. To do this, the safety laser scanner switches each OSSD briefly (for max. 300 μs) to the OFF state and checks whether this channel is voltage-free during this time.

Make sure that the machine’s control does not react to these test pulses and the machine does not switch off.

![Switch-off tests](image1)

**Figure 77: Switch-off tests**

- $t_s$ Scan cycle time
  - Setting “30 ms”: $t_s = 30$ ms
  - Setting “40 ms”: $t_s = 40$ ms

![Duration and time offset for the switch-off tests in an OSSD pair](image2)

**Figure 78: Duration and time offset for the switch-off tests in an OSSD pair**

- $t_s$ Scan cycle time
  - Setting “30 ms”: $t_s = 30$ ms
  - Setting “40 ms”: $t_s = 40$ ms
13.5 Sensing range

Protective field range

The effective protective field range depends on the variant, on the set scan cycle time and on the set object resolution.

<table>
<thead>
<tr>
<th>Resolution</th>
<th>Scan cycle time 40 ms</th>
<th>Scan cycle time 30 ms</th>
</tr>
</thead>
<tbody>
<tr>
<td>≥ 70 mm</td>
<td>5.50 m (^1)</td>
<td>4.00 m (^2)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>50 mm</td>
<td>3.50 m</td>
<td>3.00 m</td>
</tr>
<tr>
<td>40 mm</td>
<td>3.00 m</td>
<td>2.30 m</td>
</tr>
<tr>
<td>30 mm</td>
<td>2.30 m</td>
<td>1.70 m</td>
</tr>
</tbody>
</table>

Table 27: Protective field range

\(^1\) Devices with a max. protective field range of 5.5 m.

\(^2\) Devices with a max. protective field range of 4 m.

Range for warning fields

For non-safety applications (warning fields), the safety laser scanner has a larger range than the maximum protective field range. The requirements for size and remission of objects to be detected are illustrated in the following graphs as a function of the desired range.

\[ d \quad \text{Required minimum size of the object in mm} \]

\[ D \quad \text{Range in m} \]

\(^1\) Scan cycle time = 30 ms

\(^2\) Scan cycle time = 40 ms

Figure 79: Range and object size for warning fields
Figure 80: Range and necessary remission for warning fields

- **R**: Necessary minimum remission in %
- **D**: Range in m
- 1: Black shoe leather
- 2: Matt black paint
- 3: Gray cardboard
- 4: Writing paper
- 5: White plaster
- 6: Reflectors > 2000%, reflective tapes > 300%
13.6 Dimensional drawings

Figure 81: microScan3 Core I/O

All dimensions in mm.

1. Mirror rotational axis
2. Scan plane
3. Required viewing slit
14 Ordering information

14.1 Scope of delivery

- Safety laser scanner with system plug
- Safety note
- Mounting Instructions
- Operating instructions for download: www.sick.com

14.2 microScan3 ordering information

<table>
<thead>
<tr>
<th>Integration in the control</th>
<th>Protective field range</th>
<th>Type code</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>I/O</td>
<td>≤ 4.0 m</td>
<td>MICS3-AAZ40AZ1P01</td>
<td>1075842</td>
</tr>
<tr>
<td>I/O</td>
<td>≤ 5.5 m</td>
<td>MICS3-AAZ55AZ1P01</td>
<td>1075843</td>
</tr>
</tbody>
</table>

Table 28: microScan3 Core ordering information
15 Spare parts

15.1 microScan3 without system plug

<table>
<thead>
<tr>
<th>Integration in the control</th>
<th>Protective field range</th>
<th>Spare part for</th>
<th>Type code</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>I/O</td>
<td>≤ 4.0 m</td>
<td>1075842</td>
<td>MICS3-AAAZ40AZ1</td>
<td>1067360</td>
</tr>
<tr>
<td>I/O</td>
<td>≤ 5.5 m</td>
<td>1075843</td>
<td>MICS3-AAAZ55AZ1</td>
<td>1067875</td>
</tr>
</tbody>
</table>

Table 29: microScan3 Core without system plug

15.2 System plug

<table>
<thead>
<tr>
<th>Spare part for</th>
<th>Connection type</th>
<th>Type code</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>microScan3 Core I/O</td>
<td>Cable with plug connector</td>
<td>MICSX-ABIZZZZZ1</td>
<td>2073156</td>
</tr>
</tbody>
</table>

Table 30: microScan3 system plug ordering information

15.3 Additional spare parts

<table>
<thead>
<tr>
<th>Part</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Optics cover (with gloves)</td>
<td>2073673</td>
</tr>
</tbody>
</table>
16 Accessories

16.1 Brackets

<table>
<thead>
<tr>
<th>Part</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mounting kit 1a</td>
<td>2073851</td>
</tr>
<tr>
<td>Mounting kit 1b (with protection for optics cover)</td>
<td>2074242</td>
</tr>
<tr>
<td>Mounting kit 2a (alignment bracket, only together with mounting kit 1a or 1b)</td>
<td>2073852</td>
</tr>
</tbody>
</table>

Table 31: Brackets ordering information

Dimensional drawings

Figure 82: Mounting kit 1a

All dimensions in mm.

1. Mirror rotational axis
2. Scan plane
3. Countersink for M5 countersunk screw
Figure 83: Mounting kit 1b

All dimensions in mm.

1 Mirror rotational axis
2 Scan plane
3 Countersink for M5 countersunk screw

Figure 84: Mounting kit 2a

All dimensions in mm.
16 ACCESSORIES

16.2 Connection technology

<table>
<thead>
<tr>
<th>Part</th>
<th>Type code</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>M12 connecting cable, 8 pin, unshielded</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Female connector (straight), 2 m cable, open end</td>
<td>DOL-1208G02MD25KM1</td>
<td>2079314</td>
</tr>
<tr>
<td>Female connector (straight), 5 m cable, open end</td>
<td>DOL-1208G05MD25KM1</td>
<td>2079315</td>
</tr>
<tr>
<td>Female connector (straight), 10 m cable, open end</td>
<td>DOL-1208G10MD25KM1</td>
<td>2079316</td>
</tr>
<tr>
<td>Configuration cable</td>
<td></td>
<td></td>
</tr>
<tr>
<td>USB mini-B male connector, 3 m cable, USB A male connector</td>
<td>6042517</td>
<td></td>
</tr>
<tr>
<td>Power supply</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output 24 V DC, 50 W (2.1 A), SELV, PELV, NEC Class 2 power supply, input 120 V ... 240 V AC</td>
<td>7028789</td>
<td></td>
</tr>
<tr>
<td>Output 24 V DC, 95 W (3.9 A), SELV, PELV, NEC Class 2 power supply, input 100 V ... V/220 V ... 240 V AC</td>
<td>7028790</td>
<td></td>
</tr>
</tbody>
</table>

Table 32: Connection technology ordering information

16.3 Alignment aid

<table>
<thead>
<tr>
<th>Part</th>
<th>Type code</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scanfinder</td>
<td>LS-80L</td>
<td>6020756</td>
</tr>
</tbody>
</table>

16.4 Cleaning agent

<table>
<thead>
<tr>
<th>Part</th>
<th>Part number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Anti-static plastic cleaner</td>
<td>5600006</td>
</tr>
<tr>
<td>Lens cloth</td>
<td>4003353</td>
</tr>
</tbody>
</table>
### Glossary

<table>
<thead>
<tr>
<th>Term</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Contour detection field</strong></td>
<td>The contour detection field monitors a contour of the environment. The safety laser scanner switches the associated safety outputs to the OFF state if a contour does not match the set parameters, because, for example, a door or flap is open.</td>
</tr>
<tr>
<td><strong>Control input</strong></td>
<td>A control input receives signals, e.g. from the machine or from the control. Use of control inputs is how the protective device receives information about the conditions at the machine, e.g. if there is a change of operating mode. If the protective device is configured appropriately, it will activate a different monitoring case after receiving a new control input. The control input information must be transmitted reliably. Generally, at least two separate channels are used to do this. A control input can be realized as a static control input or a dynamic control input.</td>
</tr>
</tbody>
</table>
| **Dangerous state** | A dangerous state is a status of the machine or facility, where people may be injured. Protective devices prevent this risk if the machine is operated within its intended use. The figures in this document always show the dangerous state of the machine as movement of a machine part. In practice, there are different dangerous states, such as:  
- Machine movements  
- Electrical parts  
- Visible and invisible beam  
- A combination of multiple hazards |
| **EDM** | External device monitoring |
| **Electro-sensitive protective device** | An electro-sensitive protective device is a device or system of devices for safety-related detection of people or parts of the body. It is used to protect people from machines and facilities that pose a risk of injury. It triggers the machine or facility to adopt a safe state before a person is exposed to a hazardous situation. Examples include safety light curtains and safety laser scanners. |
| **ESD** | Electrostatic discharge |
| **ESPE** | Electro-sensitive protective device |
| **External device monitoring** | The external device monitoring (EDM) monitors the status of downstream contactors. In order to use the external device monitoring, positively guided contactors must be used to switch off the machine. If the auxiliary contacts of the positively guided contactors are connected to the external device monitoring, the external device monitoring checks whether the contactors drop off when the OSSDs are switched off. |
| **Field set** | A field set consists of one or more fields. The fields in a field set are monitored simultaneously. A field set can contain various types of field. A typical application is the use of a protective field with one or more warning fields: if a vehicle approaches a person, a warning field triggers an optical or acoustic signal. If the person does not react to this and the vehicle continues to approach, the safety laser scanner detects an object in the protective field and switches the associated safety outputs to the OFF state. The vehicle stops before it reaches the person. |
Monitoring case

A monitoring case signals the machine status to the safety laser scanner. The safety laser scanner activates the field set, which is assigned to the monitoring case and therefore a particular machine status.

If a machine, e.g., has various operational statuses, a monitoring case can be assigned to each operational status. The safety laser scanner receives a defined signal for the current operational status via the control inputs. If there is a change of signal, the safety laser scanner switches from one monitoring case to the monitoring case that is assigned to the new signal (and so to the new operational status). Generally, one field set is assigned to each monitoring case.

OFF state

The OFF state is the status of the outputs of the protective device, where the controlled machine is triggered to quit its dangerous state and the start-up of the machine is prevented (e.g., the voltage at the OSSDs is LOW, so that the machine is switched off and remains still).

OSSD

Output signal switching device: signal output for the protective device, which is used for stopping the dangerous movement.

An OSSD is a safety switching output. The functionality of each OSSD is tested periodically. OSSDs are always connected in pairs and must undergo dual-channel analysis for safety reasons. An OSSD pair is formed from two OSSDs that are connected and analyzed together.

PFHd

Probability of dangerous failure per hour

PL

Performance Level (ISO 13849/EN ISO 13849)

Protective field

The protective field protects the hazardous area of a machine or vehicle. As soon as the electro-sensitive protective device detects an object in the protective field, it switches the associated safety outputs to the OFF state. This signal can be passed to controllers resulting in the dangerous state coming to an end, e.g. to stop the machine or the vehicle.

A horizontal or vertical protective field is required, depending on the application. The electro-sensitive protective device can therefore be mounted in horizontal or vertical alignment, depending on the requirements.

Reference contour field

The reference contour field monitors a contour of the environment. The safety laser scanner switches all safety outputs to the OFF state if a contour does not match the set parameters, because, for example, the mounting situation of the safety laser scanner were changed.

National and international standards require or recommend that a reference contour is monitored, if the safety laser scanner is used in vertical operation for hazardous point protection or for access protection.
Reset

When a protective device has sent a stop command, the stopped state must be maintained until a reset device is activated and the machine can be restarted in a second step.

The reset brings the protective device back to the monitoring state after it has sent a stop command. The reset also quits the start-up or restart interlock of a protective device, so that the machine can be restarted in a second step.

The reset must only be possible, when all safety functions and protective devices are functional.

The reset of the protective device must not introduce any movement or dangerous situations itself. The machine is only permitted to start after the reset once a separate start command has been sent.

- Manual resets are performed using a separate, manually operated device, such as a reset pushbutton.
- Automatic resets by the protective device are only permitted in special cases, if one of the following conditions is met:
  - It must not be possible for people to be in the hazardous area without triggering the protective device.
  - It must be ensured that no people are in the hazardous area during or after the reset.

Resolution

The resolution of an active opto-electronic protective device (also known as the sensor detection capability) is the minimum size of an object for it to be reliably detected.

Response time

The protective device’s response time is the maximum time between the occurrence of the event leading to the sensor’s response and supply of the switch-off signal to the protective device’s interface (for example OFF state of the OSSD pair).

Restart interlock

The restart interlock prevents the machine from automatically starting up, for example after a protective device has responded while the machine is operating or after changing the machine’s operating mode.

The restart interlock can be implemented in the protective device or in the safety controller.

A command to reset the protective device must be given, for example using a reset pushbutton, before the machine can be restarted.

Retroreflector

A retroreflector is a reflective material that extensively reflects the incoming beam regardless of the alignment of the reflector mainly in the direction back to the source of the beam (retroflection). In contrast to this, other bright or reflective materials reflect the incoming light in another direction (incoming angle equals outgoing angle). Examples of retroreflectors include rear reflectors on bicycles, high-visibility vests, and the reflective points on guideposts.

Safety output

A safety output provides safety-related information.

Safety outputs are OSSDs, for example, or safety-related information on a safety-related network.

Scan cycle time

The scan cycle time is the time required for the mirror of a safety laser scanner to complete one rotation.

SIL

Safety integrity level

SILCL

SIL claim limit: (IEC 62061/EN 62061)

Static control input

A static control input is a dual-channel control input, which evaluates a signal level as the value 0 or 1 on each channel. The signal states of one or more static control inputs give a unique signal pattern. This signal pattern activates a monitoring case.
<table>
<thead>
<tr>
<th>Universal I/O</th>
<th>Universal I/O can be configured as universal input or as universal output.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Universal input</td>
<td>A universal input can be used for resetting, external device monitoring (EDM), standby, or restarting the protective device. If standby is activated by a universal input, the standby must not be used for safety-related functions. Universal inputs can also be used in pairs as a static control input.</td>
</tr>
<tr>
<td>Universal output</td>
<td>A universal output outputs a signal depending on its configuration, e.g. if the reset pushbutton needs to be pushed or if the optics cover is contaminated. A universal output must not be used for safety functions.</td>
</tr>
<tr>
<td>Warning field</td>
<td>The warning field monitors larger areas than the protective field. Simple switching functions can be triggered with the warning field, e.g. a warning light or an acoustic signal can be triggered if a person approaches, even before the person enters the protective field. The warning field must not be used for safety-relevant tasks.</td>
</tr>
</tbody>
</table>
18     Annex

18.1   Compliance with EU directives

EU declaration of conformity (excerpt)

The undersigned, representing the following manufacturer herewith declares that the
product is in conformity with the provisions of the following EU directive(s) (including all
applicable amendments), and that the respective standards and/or technical specifica-
tions are taken as the basis.

Complete EU declaration of conformity for download

You can call up the EU declaration of conformity and the current operating instructions
for the protective device by entering the part number in the search field at
www.sick.com (part number: see the type label entry in the “Ident. no.” field).
## Checklist for initial commissioning and commissioning

Checklist for manufacturers/installers installing electro-sensitive protective devices (ESPE)

The details on the items listed below must be available at the latest when the system is commissioned for the first time, depending, however, on the various applications the requirements of which must be reviewed by the manufacturer/installer.

This checklist should be retained and kept with the machine documentation to serve as reference during recurring tests.

This checklist does not replace the initial commissioning, nor the regular inspection by qualified safety personnel.

<table>
<thead>
<tr>
<th>Requirement</th>
<th>Yes</th>
<th>No</th>
</tr>
</thead>
<tbody>
<tr>
<td>Have the safety rules and regulations been observed in compliance with the directives/standards applicable to the machine?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the applied directives and standards listed in the declaration of conformity?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Does the protective device comply with the required PL/SIL claim limit and PFHd in accordance with EN ISO 13849-1/EN 62061 and the required type in accordance with EN 61496-1?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Is the access to the hazardous area/hazardous point only possible through the protective field of the ESPE?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Have appropriate measures been taken to protect (mechanical protection) or monitor (protective devices) any persons or objects in the hazardous area when protecting a hazardous area or hazardous point, and have these devices been secured or locked to prevent their removal?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are additional mechanical protective measures fitted and secured against manipulation which prevent reaching below, above or around the ESPE?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Has the maximum shutdown and/or stopping time of the machine been measured, specified and documented (at the machine and/or in the machine documentation)?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Has the ESPE been mounted such that the required minimum distance from the nearest hazardous point has been achieved?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the ESPE devices properly mounted and secured against manipulation after adjustment?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the required protective measures against electric shock in effect (protection class)?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Is the control switch for resetting the protective devices (ESPE) or restarting the machine present and correctly installed?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the outputs of the ESPE (OSSD) integrated according to required PL/SILCL compliant with EN ISO 13849-1/EN 62061 and does the integration correspond to the comply with the circuit diagrams?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Has the protective function been checked in compliance with the test notes of this documentation?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the specified protective functions effective at every operating mode that can be set?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Are the switching elements activated by the ESPE, e.g. contactors, valves, monitored?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Is the ESPE effective over the entire period of the dangerous state?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Once initiated, will a dangerous state be stopped when switching the ESPE on or off and when changing the operating mode, or when switching to another protective device?</td>
<td>☐</td>
<td>☑</td>
</tr>
<tr>
<td>Has the “Important Information” label for the daily check been attached such that it is well visible for the operator?</td>
<td>☐</td>
<td>☑</td>
</tr>
</tbody>
</table>
18.3 Mounting methods for protection from interference from systems in close proximity

You can choose a suitable mounting method for particularly high availability. In many cases, you can use the following examples as a guide.

**NOTE**
You must comply with the standard ISO 13855 when choosing the mounting method.

Mount several safety laser scanners offset and parallel to one another

![Figure 85: Mounting two safety laser scanners with the optics cover facing upward](image1)

![Figure 86: Mounting two safety laser scanners with the optics cover facing downward](image2)
The following mounting method has the advantage that both safety laser scanners can be mounted at a similar height. Nonetheless, there is enough space between the scan planes.

![Diagram of mounting method](image)

**Figure 87:** Mounting the upper safety laser scanner with the optics cover facing upward and mounting the lower safety laser scanner with the optics cover facing downward

![Diagram of alternative mounting method](image)

**Figure 88:** Mounting the upper safety laser scanner with the optics cover facing downward and mounting the lower safety laser scanner with the optics cover facing upward

**Mount several safety laser scanners crosswise**

If you tilt opposite safety laser scanners with respect to one another, both safety laser scanners must be tilted upward. (If mounted upside down, both safety laser scanners must be tilted downward.)

In any event, ensure that the protective field is at the right height so that crawling beneath and climbing over are prevented and so that the set resolution matches the mounting height.
Figure 89: Mounting two safety laser scanners opposite one another

If you tilt neighboring safety laser scanners toward one another, the safety laser scanners can be tilted upward or downward.

In any event, ensure that the protective field is at the right height so that crawling beneath and climbing over are prevented and so that the set resolution matches the mounting height.

Figure 90: Mounting two safety laser scanners next to one another
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