

ELS35-0CA0A024A

ELS/ELM35

MOTOR FEEDBACK SYSTEMS



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Ordering information

Туре	part no.
ELS35-0CA0A024A	1133558

Other models and accessories → www.sick.com/ELS_ELM35

Illustration may differ



Detailed technical data

Features

Items supplied	M3 mounting screws for stator coupling not included with delivery. ELM35-0CA0A024A motor feedback system (1133559). Packaging unit 40 pcs.
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Safety-related parameters

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Position	
Resolution per revolution	24 bit
System accuracy	\pm 120 $^{\prime\prime},$ Typical, mounting tolerances acc. to mounting instruction $^{1)}$
Signal noise (σ)	10 ″ ²)
Number of the absolute ascertainable revolutions	_
Available memory area	2,048 Byte

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	BiSS C

Electronics

Connection type	Male connector, 6-pin 1)

 $^{^{1)}}$ 4-wire: Communication interface RS-485 (BiSS C BP3), 2-wire: Power interface.

 $^{^{2)}}$ Repeatability standard deviation in accordance with DIN 1319-1:1995.

²⁾ (±10 %) BISS C.

Recommended supply voltage	5 V ²⁾
Current consumption	Max. 150 mA

 $^{^{1)}}$ 4-wire: Communication interface RS-485 (BiSS C BP3), 2-wire: Power interface.

Mechanics

Shaft version	Blind hollow shaft
Shaft diameter	6 mm
Weight	≤ 0.1 kg
Operating speed	6,000 min ⁻¹ , Continuous 7,500 min ⁻¹ , short-term
Angular acceleration	- 100,000 rad/s²
Permissible movement static	\pm 0.5 mm axial $^{1)}$ \pm 0.1 mm radial
Permissible movement dynamic	± 0.05 mm radial

 $^{^{1)}}$ Temperature expansion, mechanical attachment.

Ambient data

Operating temperature range	-20 °C +105 °C
Storage temperature range	-20 °C +105 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 5 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2: 2016, EN 61000-6-4: 2006, IEC 6100-6-7: 2014 $^{1)}$
Enclosure rating	IP20 (IEC 60529-1)

¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Certificates

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590

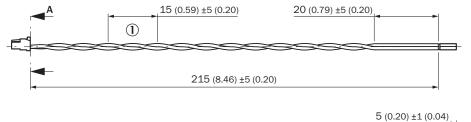
²⁾ (±10 %) BISS C.

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ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing Connecting cable

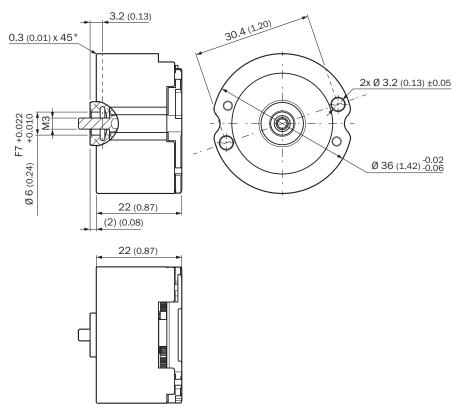




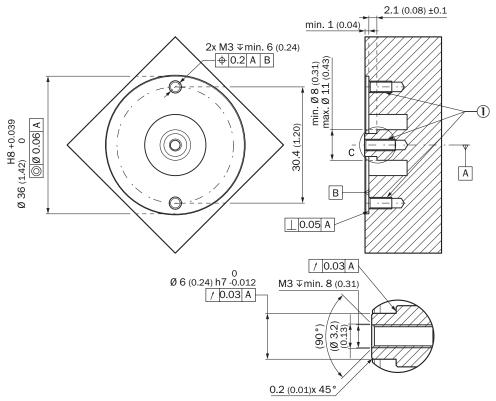
Dimensions in mm (inch)

- ① Lay length
- ② Semi-stripped

Dimensional drawing Blind hollow shaft

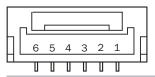


Attachment specifications



① $3 \times M3$ drill holes, screw with hex key size, s = 2.5 mm

PIN assignment



PIN	Signal	Explanation	
1	U_S	Supply voltage range for the encoder (is between +4.5 V DC and +5.5 V DC)	Pair
2	GND	Ground connection of the sensor	
3	Tx- / SL-	Slave data output, minus	Pair
4	Tx+ / SL+	Slave data output, plus	
5	Rx- / MA-	Master clock input, minus	Pair
6	Rx+ / MA+	Master clock input, plus	

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For us, that is "Sensor Intelligence."

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