



PLOC2D-621-10RB

PLOC2D

ROBOT GUIDANCE SYSTEMS







Ordering information

Туре	part no.
PLOC2D-621-10RB	1118608

Other models and accessories → www.sick.com/PLOC2D



Detailed technical data

Features

Product name		PLOC2D-FIX0012
System features		Stand-alone sensor with easy teach, for localization of parts using 2D measurements
Example field of view		For details see field of view diagram
Working distance		70 mm 1,500 mm
Light source		
In	iternal lighting	LED, visible red light, 617 nm, ± 15 nm
In	iternal lighting	LED, visible blue light, 470 nm, ± 15 nm
F	eedback spot	LED, visible green light, 525 nm, ± 15 nm
A	djustment aid	Laser, visible red light, 630 nm 680 nm
Laser class		1, complies with 21 CFR 1040.10 except for the conformance according to "Laser Notice No. 50" from June 24, 2007 (IEC 60825-1:2014) EN 60825-1:2014
Optical focus		Adjustable focus (electric)
LED class		Risk group 1 (low risk, IEC 62471 (2006-07) / EN 62471 (2008-09))
Localization principle		Shape comparison
Sensor resolution		1,280 px x 1,024 px (1.3 MP)
Lens		
Mou	unting method	Integrated
	Focal length	9.6 mm
Technology		2D snapshot, image analysis
Description		Basic resolution 2D localization of parts in medium fields of view at medium reading distances

Mechanics/electronics

Connection type	1 x M12, 17-pin male connector (serial, I/Os, voltage supply) 1 x M12, 4-pin female connector (Ethernet)
Supply voltage	24 V, ± 20 %
Power consumption	4 W, ± 20 %
Housing material	Aluminum die cast
Housing color	Light blue (RAL 5012)

 $^{^{1)}}$ When using optics cover and male connector.

Window material	PMMA
Dimensions (L x W x H)	71 mm x 43 mm x 35.6 mm
Weight	170 g
Enclosure rating	IP65 ¹⁾

 $^{^{1)}}$ When using optics cover and male connector.

Performance

Part localization time	$\!<\!0.5\!$ seconds for the first part in the image and then $\!<\!100$ ms for additional parts in the image
Localization accuracy	± 0.5 px, ± 0.1°
Output data	X, Y (mm), rotation around Z (degrees)

Interfaces

Ethernet	✓
Data transmission rate	100 Mbit/s
Protocol	TCP/IP XML and CSV (robot), TCP/IP (operator) PROFINET EtherNet/IP™ FTP
Electrical connection	M12 female connector, 4-pin
Supply voltage	
Electrical connection	Male connector M12, 17-pin
User interface	Web server
Data storage and retrieval	Image and data logging via microSD memory card and external FTP

Ambient data

Ambient temperature, operation	0 °C +50 °C, permissible relative humidity: 0% 90% (non-condensing)		
Ambient temperature, storage	-20 °C +70 °C ¹⁾		
Shock load	EN 60068-2-27:2009-05		
Vibration load	EN 60068-2-6:2008-02		

 $^{^{1)}}$ Permissible relative humidity: 0% ... 90% (non-condensing).

General notes

• •	Camera, complete with integrated optics and illumination PLOC2D software
• •	

Classifications

ECLASS 5.0	27381501
ECLASS 5.1.4	27381501
ECLASS 6.0	27381590
ECLASS 6.2	27381590
ECLASS 7.0	27381590
ECLASS 8.0	27381590
ECLASS 8.1	27381590
ECLASS 9.0	27381590
ECLASS 10.0	27381590

PLOC2D-621-10RB | PLOC2D

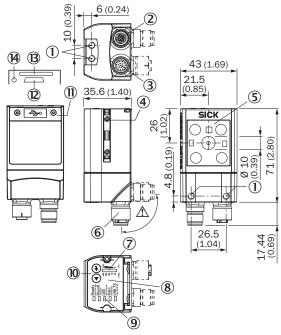
ROBOT GUIDANCE SYSTEMS

ECLASS 11.0	27381591
ECLASS 12.0	27381591

Certificates

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
China RoHS	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

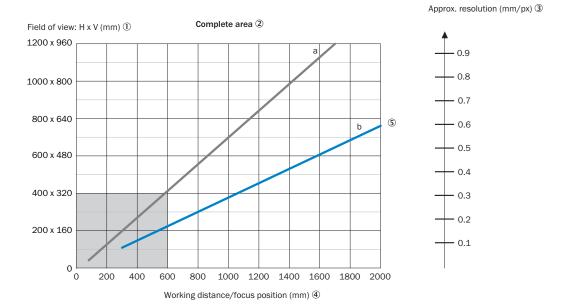
Dimensional drawing

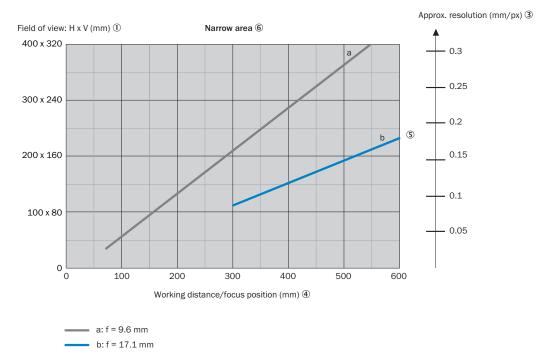


Dimensions in mm (inch)

- ① M5 blind tapped holes, 5 mm deep (4 x), for mounting the sensor
- 2 "Ethernet" connection, 4-pin M12 female connector, D-coded
- ③ "Power/Serial Data/CAN/I/O" connection, 17-pin M12 male connector, A-coded
- 4 sliding nut M5, 5.5 mm deep (2 x), for mounting (as alternative)
- ⑤ reading window with internal illumination LEDs (4 x)
- 6 swivel connector unit
- ⑦ Bar graph
- ® beeper (under housing cover)
- 1 Function button (2 x)
- ① Cover (flap)
- @ "USB" connection (female connector, 5-pin, type Micro-B) interface for temporary use (service)
- (3) Slot for microSD memory card
- (4) LED for microSD memory card

Characteristic curve





Take into account the following aspects when designing the application: the field of view geometry of the device, and the position of the field of view in the space in front of the device. Possible angles at which the objects can arise in relation to the device. For the planned working distance: resultant field of view length and width as well as the approximate resolution.

- ① Field of view: Horizontal x vertical in mm
- ② complete area
- ③ approximate resolution in mm/px
- 4 Working distance/Focus position in mm
- \bigcirc Focal length of lens, here example for f = 17.1 mm
- 6 Narrow range

PLOC2D-621-10RB | PLOC2D

ROBOT GUIDANCE SYSTEMS

Recommended accessories

Other models and accessories → www.sick.com/PLOC2D

	Brief description	Туре	part no.
Commissionin	ng aids and test equipment		
	 Product: Test equipment Description: Target for alignment and calibration, A3-size 	PLOC2D align- ment and cali- bration target A3	4092645

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

WORLDWIDE PRESENCE:

Contacts and other locations -www.sick.com

