

DFS60B-BDZZ00S98

DFS60

**INCREMENTAL ENCODERS** 



Illustration may differ

## Ordering information

| Туре             | part no. |  |
|------------------|----------|--|
| DFS60B-BDZZ00S98 | 1090159  |  |

Other models and accessories → www.sick.com/DFS60

#### Detailed technical data

### **Features**

| Special device            | ✓   |
|---------------------------|---|
| Specialty                 | Customized Encoderflange Customized stator coupling Electrical interface: 4.5 V 32 V, SinCos 1.0 VPP (differential) M12 8-pin male connector with customized pin assignment |
| Standard reference device | DFS60B-BDNC01024  |
| Additional information    | Meurer internal ordering information: 5082017   |

## Safety-related parameters

| MTTF <sub>D</sub> (mean time to dangerous failure) | 300 years (EN ISO 13849-1) <sup>1)</sup> |
|--|--|
| ,  | 300 years (LIV 100 13045-1)              |

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

### Performance

| Sine/cosine periods per revolution                 | 1,024                               |
|--|-------------------------------------|
| Measuring step                                     | 90°, electric/pulses per revolution |
| Measuring step deviation at binary number of lines | ± 0.008°                            |
| Error limits                                       | ± 0.05°                             |

### Interfaces

| Communication interface         | Incremental                                    |
|---------------------------------|--|
| Communication Interface detail  | Sin/Cos 1)                                     |
| Number of signal channels       | 6-channel                                      |
| 0-set function via hardware pin | <b>√</b>                                       |
| 0-SET function                  | H-active, L = 0 - 3 V, H = 4,0 - $U_s V^{(2)}$ |
| Initialization time             | 40 ms  |
| Output frequency                | ≤ 200 kHz                                      |
| Operating current               | 40 mA (without load)                           |
| Power consumption               | ≤ 0.7 W (without load)                         |
| Load resistance                 | ≤ 120 Ω  |

 $<sup>^{1)}</sup>$  1.0 V<sub>SS</sub> (differential).

 $<sup>^{2)}</sup>$  Only with devices with M23 connector in connection with electrical interfaces M, U, V and W.

### **Electronics**

| Connection type                         | Male connector, M12, 8-pin, radial, Customer-specific pin assignment |
|---|--|
| Supply voltage                          | 4.5 32 V   |
| Reference signal, number                | 1  |
| Reference signal, position              | 90°, electronically, gated with Sinus and Cosinus                    |
| Short-circuit protection of the outputs | <b>✓</b> ¹)  |

 $<sup>^{1)}\,\</sup>mathrm{Short\text{-}circuit}$  opposite to another channel, US or GND permissable for maximum 30 s.

## Mechanics

| Mechanical design              | Blind hollow shaft                    |
|--------------------------------|---------------------------------------|
| Shaft diameter                 | 10 mm<br>Front clamp                  |
| Weight                         | + 0.2 kg                              |
| Shaft material                 | Stainless steel                       |
| Flange material                | Aluminum                              |
| Housing material               | Aluminum die cast                     |
| Start up torque                | 0.8 Ncm (+20 °C)                      |
| Operating torque               | 0.6 Ncm (+20 °C)                      |
| Permissible movement static    | ± 0.3 mm (radial)<br>± 0.5 mm (axial) |
| Permissible movement dynamic   | ± 0.1 mm (radial)<br>± 0.2 mm (axial) |
| Operating speed                | ≤ 6,000 min <sup>-1 1)</sup>          |
| Moment of inertia of the rotor | 40 gcm <sup>2</sup>                   |
| Bearing lifetime               | 3.6 x 10^10 revolutions               |
| Angular acceleration           | $\leq 500,000 \text{ rad/s}^2$        |

 $<sup>^{1)}</sup>$  Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

| EMC                           | According to EN 61000-6-2 and EN 61000-6-3  |
|-------------------------------|---|
| Enclosure rating              | IP67, Housing side, male connector (IEC 60529) $^{1)}$ IP65, shaft side (IEC 60529) |
| Permissible relative humidity | 90 % (Condensation not permitted)   |
| Operating temperature range   | -40 °C +100 °C <sup>2)</sup><br>-30 °C +100 °C <sup>3)</sup>                        |
| Storage temperature range     | -40 °C +100 °C, without package   |
| Resistance to shocks          | 70 g, 6 ms (EN 60068-2-27)  |
| Resistance to vibration       | 30 g, 10 Hz 2,000 Hz (EN 60068-2-6)   |

<sup>&</sup>lt;sup>1)</sup> With mating connector fitted.

# Classifications

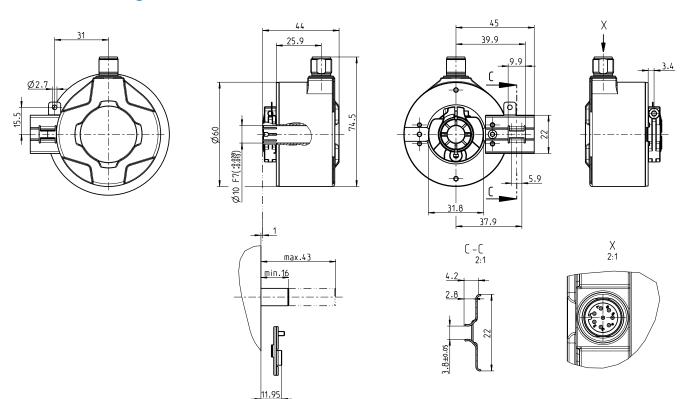
| ECLASS 5.0   | 27270501 |
|--------------|----------|
| ECLASS 5.1.4 | 27270501 |

<sup>&</sup>lt;sup>2)</sup> Stationary position of the cable.

<sup>3)</sup> Flexible position of the cable.

| ECLASS 6.0     | 27270590 |
|----------------|----------|
| ECLASS 6.2     | 27270590 |
| ECLASS 7.0     | 27270501 |
| ECLASS 8.0     | 27270501 |
| ECLASS 8.1     | 27270501 |
| ECLASS 9.0     | 27270501 |
| ECLASS 10.0    | 27270501 |
| ECLASS 11.0    | 27270501 |
| ECLASS 12.0    | 27270501 |
| ETIM 5.0       | EC001486 |
| ETIM 6.0       | EC001486 |
| ETIM 7.0       | EC001486 |
| ETIM 8.0       | EC001486 |
| UNSPSC 16.0901 | 41112113 |

# Dimensional drawing



Dimensions in mm (inch)

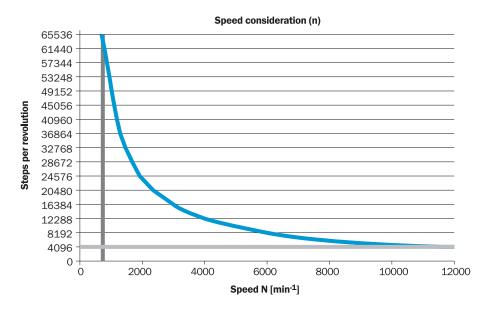
## PIN assignment

Ansicht Gerätestecker M12 an Leitung/Gehäuse



| Pin, 8-pin, M12 |                             |   |
|-----------------|-----------------------------|---|
| connector       | SIN/COS 1.0 V <sub>PP</sub> | Explanation   |
|                 |                             |   |
| 1               | GND                         | Ground connection of the encoder  |
| 2               | +U <sub>S</sub>             | Supply voltage (volt-free to housing)   |
| 3               | COS+                        | Signal cable  |
| 4               | COS-                        | Signal cable  |
| 5               | SIN+                        | Signal cable  |
| 6               | SIN-                        | Signal cable  |
| 7               | N.C.                        | Not assigned  |
| 8               | N.C.                        | Not assigned  |
| Shield          | Shield                      | Shield connected to housing on side of encoder. Connected to ground on side of control. |

# maximum revolution range



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Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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