

SICK.COM



DATA SHEET

DFS60I-BGPM65536

DFS60
Incremental encoders

SICK Sensor Intelligence

INCREMENTAL ENCODERS

DFS60I-BGPM65536

ORDERING INFORMATION

Type	part no.
DFS60I-BGPM65536	1085770

Further device versions and accessories at www.sick.com/DFS60



Illustration may differ



DETAILED TECHNICAL DATA

SAFETY-RELATED PARAMETERS

MTTF _D (mean time to dangerous failure)	300 years (EN ISO 13849-1) ¹⁾
--	--

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

PERFORMANCE

Pulses per revolution	65,536 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at binary number of lines	± 0.0015°
Error limits	± 0.03°

¹⁾ See maximum revolution range.

INTERFACES

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms, 30 ms ¹⁾

¹⁾ With mechanical zero pulse width.

Output frequency	≤ 820 kHz
Load current	≤ 30 mA
Operating current	40 mA (without load)
Power consumption	≤ 0.7 W (without load)
Load resistance	≥ 120 Ω

¹⁾ With mechanical zero pulse width.

ELECTRONICS

Connection type	Cable, 8-wire, radial, 5 m
Supply voltage	4.5 ... 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{1) 2)}

¹⁾ Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

²⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

MECHANICS

Mechanical design	Blind hollow shaft
Shaft diameter	14 mm Front clamp
Weight	+ 0.5 kg
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Housing material	Stainless steel V2A
Start up torque	1 Ncm (+20 °C)
Operating torque	0.5 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.05 mm (radial) ± 0.01 mm (axial)
Operating speed	≤ 6,000 min ⁻¹ ¹⁾
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

AMBIENT DATA

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side (IEC 60529) IP67, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C ¹⁾ -30 °C ... +100 °C ²⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)

¹⁾ Stationary position of the cable.

²⁾ Flexible position of the cable.

Resistance to vibration	10 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)
-------------------------	---

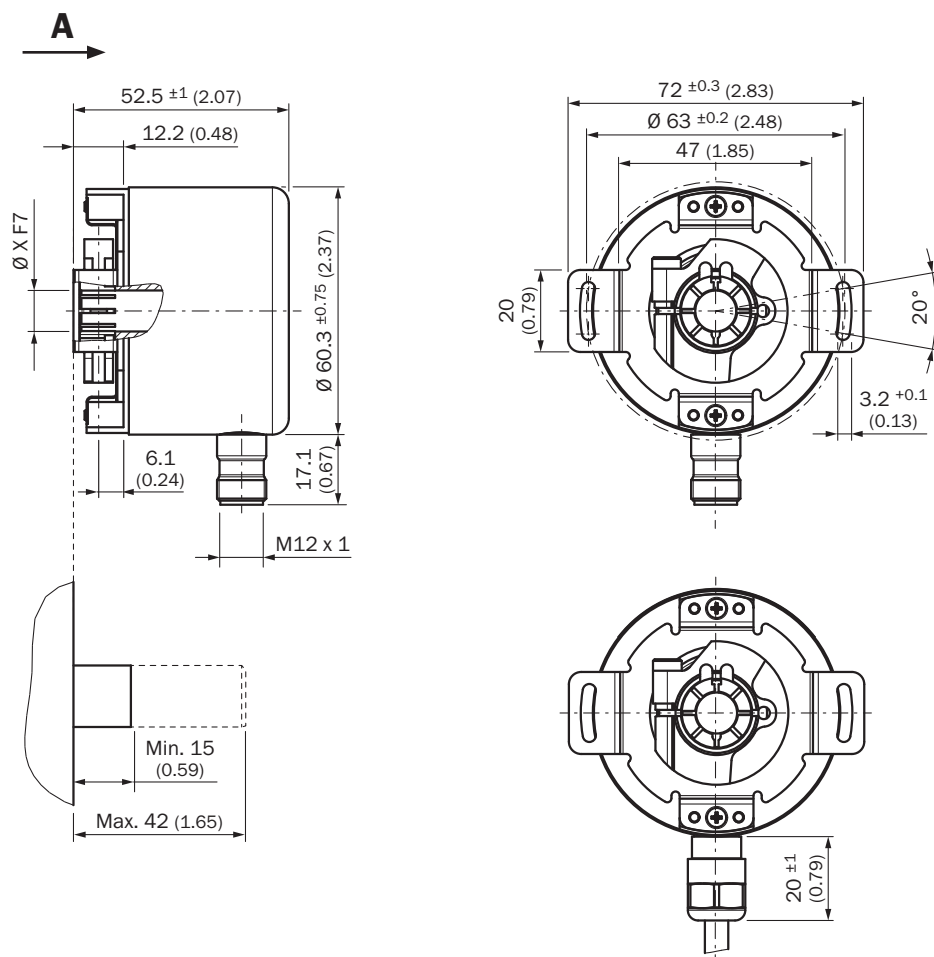
¹ Stationary position of the cable.

² Flexible position of the cable.

CERTIFICATES

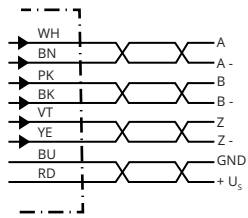
EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China RoHS	✓
cULus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

DIMENSIONAL DRAWING



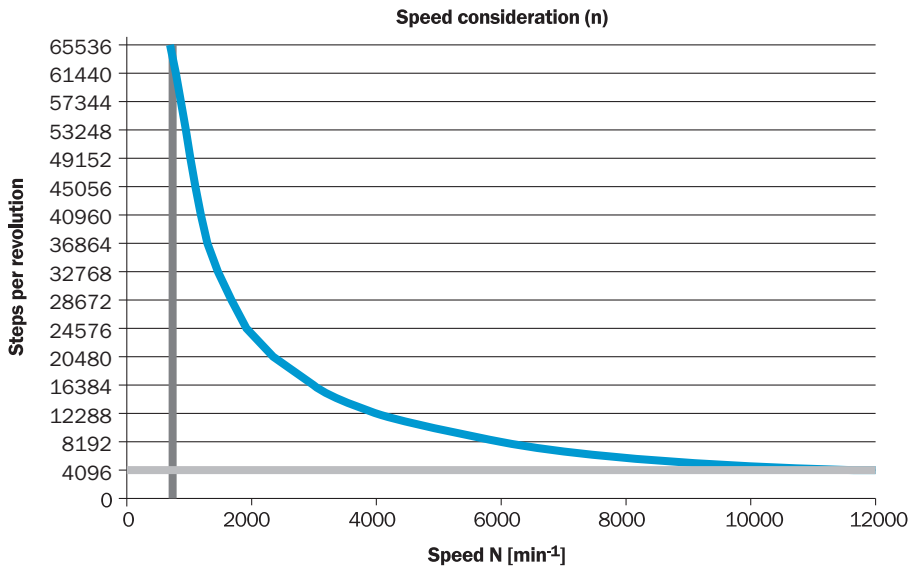
Dimensions in mm (inch)

PIN ASSIGNMENT

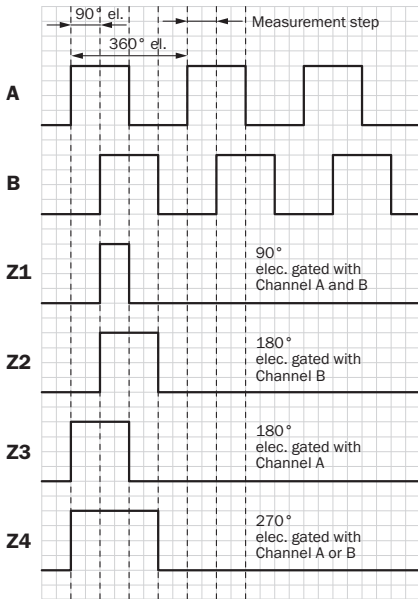


Male connector M12, 8-pin	Connector M12, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V _{pp}	Explanation
1	7	Brown	A	COS-	Signal wire
2	6	White	A	COS+	Signal wire
3	9	Black	B	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	Z	Z	Signal wire
6	11	Purple	Z	Z	Signal wire
7	12	Blue	GND	GND	Ground connection
8	5	Red	+U _s	+U _s	Supply voltage
-	2	-	N.c.	N.c.	Not assigned
-	3	-	N.c.	N.c.	Not assigned
-	1	-	N.c.	N.c.	Not assigned
-	10 ¹⁾	-	0-SET ¹⁾	N.c.	Set zero pulse ¹⁾
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

MAXIMUM REVOLUTION RANGE



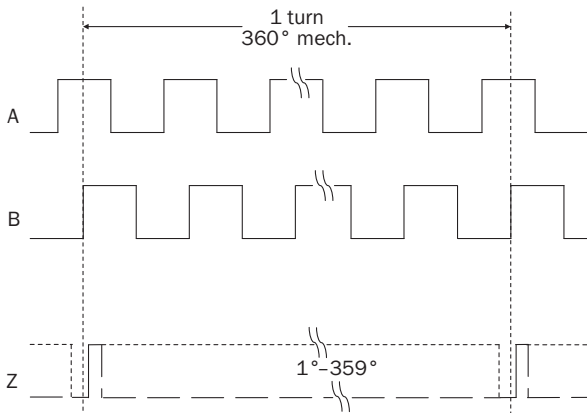
DIAGRAMS ELECTRICAL ZERO PULSE WIDTH CAN BE CONFIGURED TO 90°, 180°, OR 270°. WIDTH OF THE ZERO PULSE IN RELATION TO A PULSE PERIOD.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

DIAGRAMS MECHANICAL ZERO PULSE WIDTH 1° TO 359° PROGRAMMABLE. WIDTH OF THE ZERO PULSE IN RELATION TO A MECHANICAL REVOLUTION OF THE SHAFT.



Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

Further information as well as suitable accessories, example applications and downloads such as CAD dimensional models, operating instructions and software can be found at www.sick.com/1085770



SICK AG
WALDKIRCH
GERMANY
SICK.COM

SICK AT A GLANCE

SICK is a leading global technology company for intelligent sensors and integrated solutions in industrial automation. Our technologies set benchmarks, making your industrial processes more efficient, safer and more sustainable – both in logistics and manufacturing operations.

SICK combines sensor intelligence with industry expertise and certified consulting services. We provide the ideal foundation for scalable as well as tailor-made automation solutions and create added value along the entire value chain. Our close partnerships with our customers are more than just a promise: Together, we optimize productivity, improve quality, protect health and safety, and help build a sustainable future. All with empathy and trust.

Since 1946, we have been developing innovative technologies with passion and a pioneering spirit. With a global network in around 40 countries, SICK has a global presence and is always close by. The company's headquarters are located in Waldkirch near Freiburg, Germany. Our customers benefit from our understanding of both local and global requirements, which enables us to deliver tailor-made solutions

SICK
Sensor Intelligence