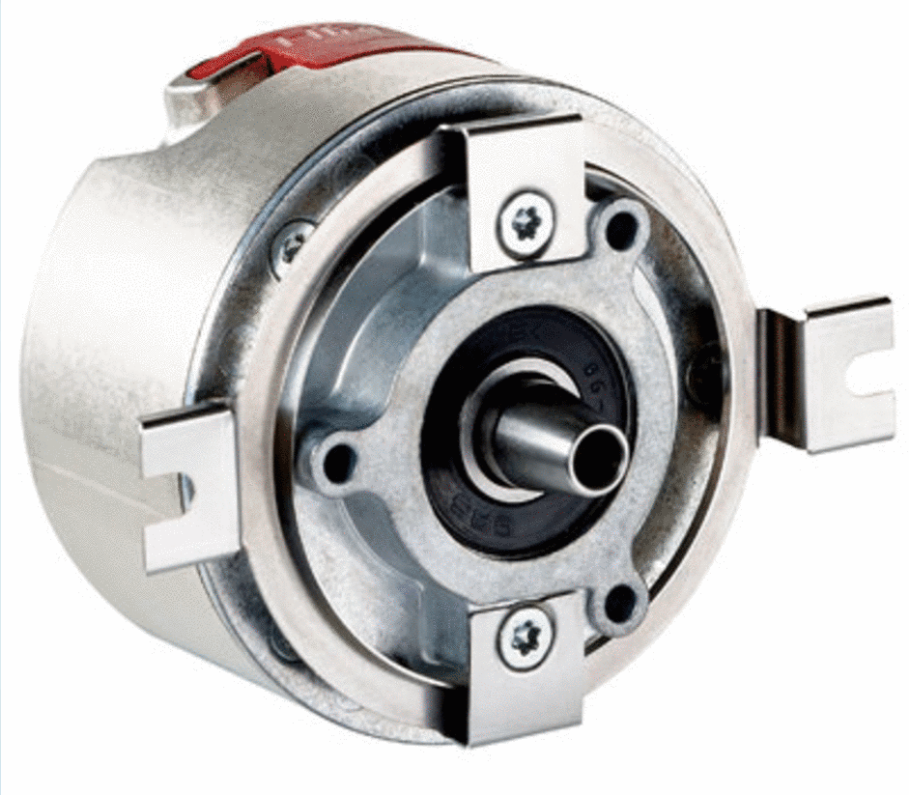
Data sheet



EFM50-2KF0A023A

EFS/EFM50

MOTOR FEEDBACK SYSTEMS

SICK
Sensor Intelligence.

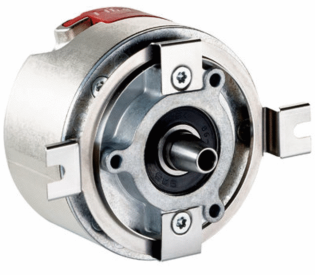


Illustration may differ

Ordering information

Type	part no.
EFM50-2KF0A023A	1073504

Other models and accessories ➜ www.sick.com/EFS_EFM50

Detailed technical data

Safety-related parameters

Safety integrity level	SIL 2 (IEC 61508), SILCL2 (EN 62061) [1]
Category	20 years
Systematic suitability	SC 3 (IEC61508)
Test rate	1 h
Maximum demand rate	216 µs
Performance level	PL d (EN ISO 13849)
Safety-related resolution	Channel 1 = 23 bit, channel 2 = 12 bit
PFH (mean probability of a dangerous failure per hour)	3,8 x 10^-8
Safety-related accuracy	± 0.09°

[1] For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

Performance

Position	
Resolution per revolution	23 bit
System accuracy	± 50 ″
Signal noise (σ)	± 2 ″
Number of the absolute ascertainable revolutions	4,096
Available memory area	8,192 Byte
Measurement step per revolution	8,388,608
Measurement principle	Optical

Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction “A” (see dimensional drawing)
Communication interface	HIPERFACE DSL®
Initialization time	Max. 500 ms [1]

[1] From reaching a permitted operating voltage.
[2] Without sensor tolerance; at −17 °C ... +167 °C: NTC +-2K (103 GT); PTC+-3K (KTY84/130/PT1000).

Measurement external temperature resistance	32-bit value, without prefix (1 Ω) 0 ... 209.600 Ω [2]

[1] From reaching a permitted operating voltage.
[2] Without sensor tolerance; at −17 °C ... +167 °C: NTC +-2K (103 GT); PTC+-3K (KTY84/130/PT1000).

Electronics

Connection type	Male connector, 4-pin
Supply voltage	7 V ... 12 V
Warm-up time voltage ramp	Max. 180 ms [1]
Current consumption	≤ 150 mA [2]
Output frequency for the digital positionvalue	0 kHz ... 75 kHz

[1] Duration of the voltage ramp between 0 and 7.0 V, see diagram “Current consumption” in the diagram section.
[2] Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

Mechanics

Shaft version	Tapered shaft
Flange type / stator coupling	Stator coupling
Dimensions	See dimensional drawing
Weight	0.2 kg
Moment of inertia of the rotor	10 gcm²
Operating speed	≤ 9,000 min⁻¹
Angular acceleration	≤ 200,000 rad/s²
Start up torque	≤ 0.4 Ncm
Permissible radial shaft movement	± 0.2 mm [1]
Permissible axial shaft movement	± 0.95 mm
Permissible movement static	± 0.5 mm, ± 0.95 mm radial, axial
Permissible movement dynamic	± 0.1 mm radial
Life of ball bearings	See diagram 3

[1] Permitted when using the elastomer stator coupling. When the spring plate stator coupling is being used, voltage-free mounting is assumed.

Ambient data

Operating temperature range	–30 °C ... +115 °C [1]
Storage temperature range	–40 °C ... +120 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-3 and IEC 61326-3-1 [2]
Enclosure rating	IP40, with mating plug inserted and closed cover (IEC 60529-1)

[1] The max. internal sensor temperature may not exceed 125 °C. The defined measuring point on the encoder (see dimensional drawing) must be used for measuring the operating temperature. For typical values for self-heating, see diagram 3 (electrical) and diagram 4 (mechanical).
[2] EMC according to the listed standards is guaranteed if the motor feedback system with mating plug inserted is connected to the central grounding point of the motor controller via a cable shield. If other screening concepts are used, users must perform their own tests.

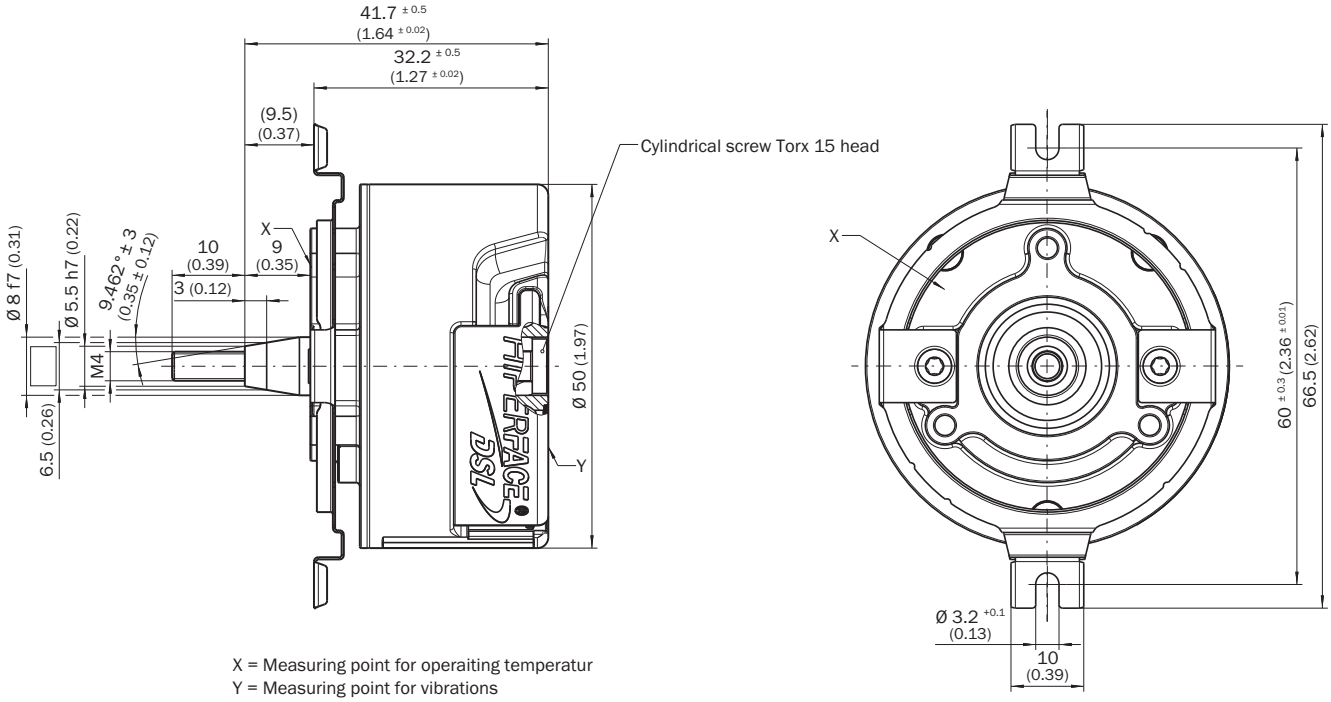
Certificates

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
China RoHS	✓
EC-Type-Examination approval	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

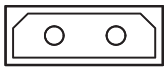
Dimensional drawing



X = Measuring point for operaiting temperatur
Y = Measuring point for vibrations

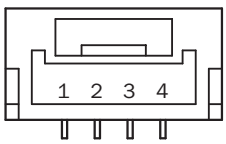
Dimensions in mm (inch)

PIN assignment Temperature sensor pin assignment



PIN	Signal	Explanation
1	T+	Thermistor connection
2	T-	Thermistor connection (to ground)
Recommended outer diameter of set of stranded wires: 2.2 mm ± 0.1 mm		
Recommended mating connector: Harwin M80-8990205		

PIN assignment Supply/Communication pin assignment



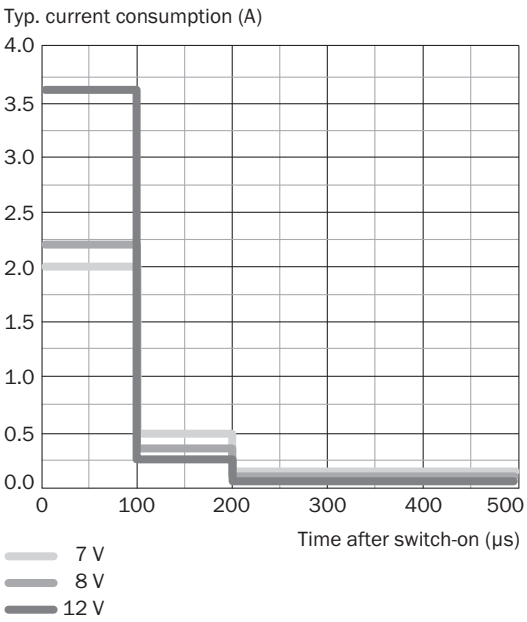
integrated in motor cable = J, K

PIN	Signal	Explanation
1	–	Not connected - no function
2	$+U_S$/DSL+	Supply 7 V ... 12 V
3	GND/DSL-	Ground connection

PIN	Signal	Explanation
4	–	Not connected - no function
Recommended outer diameter of set of stranded wires: 4 mm +0/-0.3 mm Recommended mating connector: JST (GHR-04V-S)		

Diagrams Power consumption

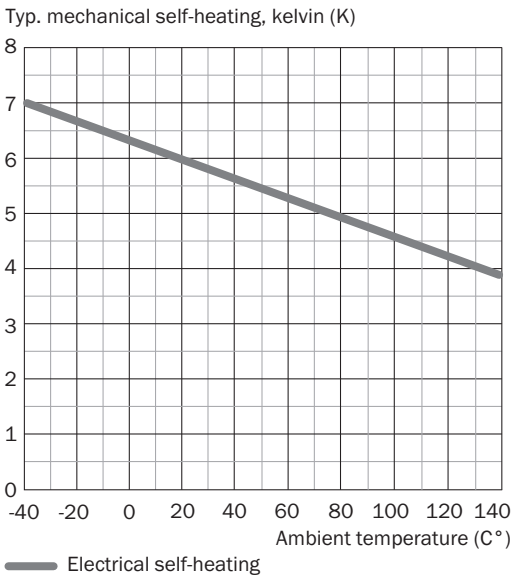
Diagram 2



This diagram shows the switch-on current

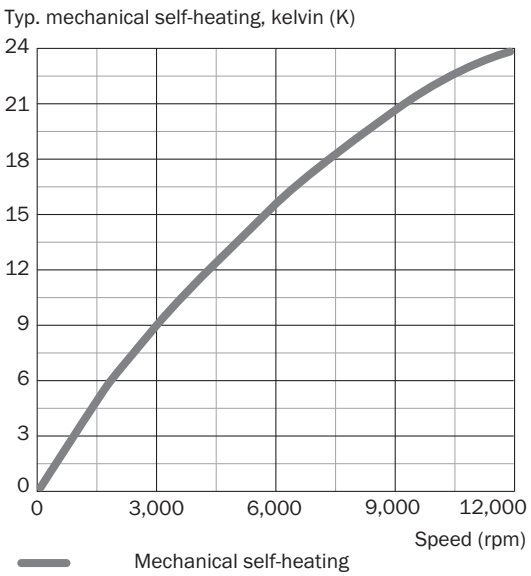
Diagrams Electrical self-heating

Diagram 3



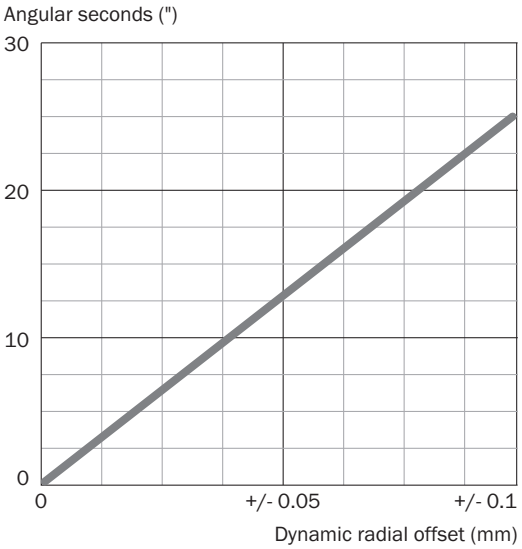
Diagrams Mechanical self-heating

Diagram 4



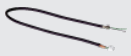
Diagrams Error limits

Diagram 1



Recommended accessories

Other models and accessories ➜ www.sick.com/EFS_EFM50

	Brief description	Type	part no.
Mounting systems			
	• **Description:** Servo clamps, small, for servo flange (clamps, eccentric fastener), 3 pcs, without mounting material • **Items supplied:** Without mounting hardware	BEF-WK-RESOL	2039082
connectors and cables			
	• **Connection type head A:** Female connector, stranded wire, 4-pin, straight • **Connection type head B:** Flying leads • **Signal type:** HIPERFACE DSL® • **Cable:** 0.2 m, 2-wire • **Description:** HIPERFACE DSL®, unshielded	DOL-0B02-G0M2XC2	2079920
	• **Connection type head A:** Female connector, stranded wire, 4-pin, straight • **Connection type head B:** Flying leads • **Signal type:** HIPERFACE DSL® • **Cable:** 0.36 m, 2-wire • **Description:** HIPERFACE DSL®, twisted, shielded	DOL-0B02-G0M3AC2	2108944

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

WORLDWIDE PRESENCE:

Contacts and other locations –www.sick.com

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