

ATM60-C1H13x13

ATM60

ABSOLUTE ENCODERS





Ordering information

| Туре | part no. |
|----------------|----------|
| ATM60-C1H13x13 | 1030025 |

Other models and accessories → www.sick.com/ATM60

Illustration may differ



Detailed technical data

Safety-related parameters

| MTTF _D (mean time to dangerous failure) | 150 years (EN ISO 13849-1) 1) |
|--|-------------------------------|
|--|-------------------------------|

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

| Number of steps per revolution (max. resolution) | 8,192 (13 bit) |
|--|---------------------------------|
| Number of revolutions | 8,192 (13 bit) |
| $\label{eq:max} \begin{tabular}{ll} \textbf{Max. resolution (number of steps per revolution x number of revolutions)} \end{tabular}$ | 13 bit x 13 bit (8,192 x 8,192) |
| Measuring step | 0.043° |
| Error limits G | ± 0.25° ¹⁾ |
| Repeatability standard deviation $\boldsymbol{\sigma}_{r}$ | 0.1° ²⁾ |

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

| Communication interface | CANopen | | |
|------------------------------------|--|--|--|
| Data protocol | Communication Profile DS 301 V4.0, Device Profile DSP 406 V 2.0 | | |
| Address setting | 0 63, DIP switches or protocol | | |
| Data transmission rate (baud rate) | 10 kBaud, 20 kBaud, 50 kBaud, 125 kBaud, 250 kBaud, 500 kBaud, 1 MBaud, DIP switches or protocol | | |
| Initialization time | 1,250 ms ¹⁾ | | |
| Position forming time | 0.25 ms | | |
| Status information | 2-colours LED for CAN controller status | | |
| Bus termination | DIP switch ²⁾ | | |

 $^{^{1)}}$ Valid positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

 $^{^{2)}\,\}mbox{Should}$ only be connected in the final device.

Set (electronic adjustment)

Via PRESET push button or protocol

Electronics

| Connection type | Bus adapter ¹⁾ |
|-----------------------------|---------------------------|
| Supply voltage | 10 32 V |
| Power consumption | ≤ 2 W (without load) |
| Reverse polarity protection | √ |

¹⁾ Order bus adapter separately.

Mechanics

| Mechanical design | Solid shaft, Servo flange |
|--------------------------------|---|
| Shaft diameter | 6 mm |
| Shaft length | 10 mm |
| Weight | 0.59 kg ¹⁾ |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Start up torque | 2.5 Ncm (+20 °C), with shaft seal 0.5 Ncm (+20 °C), without shaft seal $^{2)}$ |
| Operating torque | 1.8 Ncm (+20 °C), with shaft seal 0.3 Ncm (+20 °C), without shaft seal ²⁾ |
| Permissible shaft loading | 300 N (radial) 50 N (axial) |
| Operating speed | ≤ 6,000 min ^{-1 3)} |
| Moment of inertia of the rotor | 35 gcm ² |
| Bearing lifetime | 3.6 x 10 ⁹ revolutions |
| Angular acceleration | ≤ 500,000 rad/s² |

 $^{^{1)}}$ Based on encoder with male connector.

Ambient data

| EMC | According to EN 61000-6-2 and EN 61000-6-3 |
|-------------------------------|---|
| Enclosure rating | IP67, with shaft seal (IEC 60529) $^{1)}$ IP43, without shaft seal, on encoder flange not sealed (IEC 60529) $^{1)}$ IP66, without shaft seal, on encoder flange sealed (IEC 60529) $^{1)}$ |
| Permissible relative humidity | 98 % |
| Operating temperature range | -20 °C +85 °C |
| Storage temperature range | -40 °C +100 °C, without package |
| Resistance to shocks | 100 g, 6 ms (EN 60068-2-27) |
| Resistance to vibration | 20 g, 10 Hz 2,000 Hz (EN 60068-2-6) |

 $^{^{1)}}$ With mating connector fitted.

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ Should only be connected in the final device.

 $^{^{2)}}$ If the shaft seal has been removed by the customer.

 $^{^{3)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

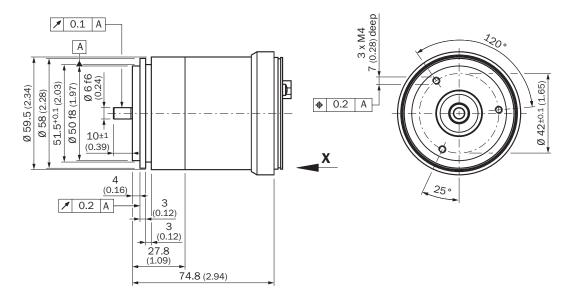
Certificates

| EU declaration of conformity | ✓ |
|------------------------------------|---|
| UK declaration of conformity | ✓ |
| ACMA declaration of conformity | ✓ |
| Moroccan declaration of conformity | ✓ |
| China RoHS | ✓ |
| cULus certificate | ✓ |

Classifications

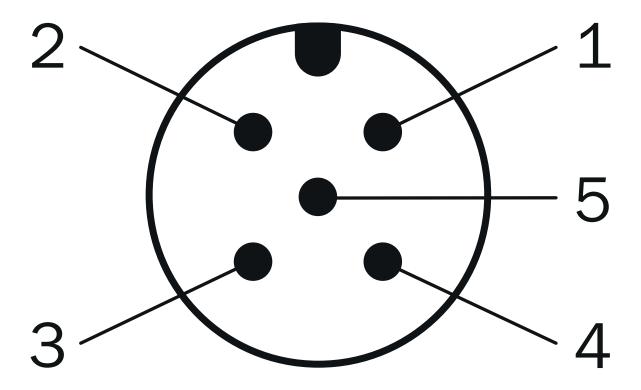
| old comod to he | |
|-----------------|----------|
| ECLASS 5.0 | 27270502 |
| ECLASS 5.1.4 | 27270502 |
| ECLASS 6.0 | 27270590 |
| ECLASS 6.2 | 27270590 |
| ECLASS 7.0 | 27270502 |
| ECLASS 8.0 | 27270502 |
| ECLASS 8.1 | 27270502 |
| ECLASS 9.0 | 27270502 |
| ECLASS 10.0 | 27270502 |
| ECLASS 11.0 | 27270502 |
| ECLASS 12.0 | 27270502 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |
| | |

Dimensional drawing



Dimensions in mm (inch)

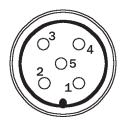
M12 male connector (bus adapter)



IN/US

| Terminal strip | Male device connector | Signal | Explanation |
|----------------|-----------------------|-----------------------|---------------------------|
| 1 | 1 | shield | Screen |
| 2 | 2 | U _S (24 V) | Operating voltage 10 32 V |
| 3 | 3 | GND (COM) | O V (GND) |
| 4 | 4 | CAN _H | CAN Bus Signal high |
| 5 | 5 | CAN_L | CAN Bus Signal low |
| 6 | - | CAN _H | CAN Bus Signal high |
| 7 | - | CAN_L | CAN Bus Signal low |
| 8 | - | GND (COM) | O V (GND) |
| 9 | - | U _S (24 V) | Operating voltage 10 32 V |

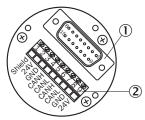
M12 female connector (bus adapter)



OUT/US (female contact)

| Terminal strip | Male device connector | Signal | Explanation |
|----------------|-----------------------|-----------------------|---------------------------|
| 1 | 1 | shield | Screen |
| 2 | 2 | U _S (24 V) | Operating voltage 10 32 V |
| 3 | 3 | GND (COM) | 0 V (GND) |
| 4 | 4 | CAN _H | CAN Bus Signal high |
| 5 | 5 | CAN _L | CAN Bus Signal low |
| 6 | - | CAN _H | CAN Bus Signal high |
| 7 | - | CAN _L | CAN Bus Signal low |
| 8 | | GND (COM) | O V (GND) |
| 9 | - | U _S (24 V) | Operating voltage 10 32 V |

PIN assignment



- ① Internal plug connector to encoder
- 2 external connection to the bus

| Terminal strip | Male device connector | Signal | Explanation |
|----------------|-----------------------|-----------------------|---------------------------|
| 1 | 1 | shield | Screen |
| 2 | 2 | U _S (24 V) | Operating voltage 10 32 V |
| 3 | 3 | GND (COM) | O V (GND) |
| 4 | 4 | CAN _H | CAN Bus Signal high |
| 5 | 5 | CAN _L | CAN Bus Signal low |
| 6 | - | CAN _H | CAN Bus Signal high |
| 7 | - | CAN_L | CAN Bus Signal low |
| 8 | - | GND (COM) | O V (GND) |
| 9 | - | U _S (24 V) | Operating voltage 10 32 V |

Recommended accessories

Other models and accessories → www.sick.com/ATM60

| | Brief description | Туре | part no. | |
|----------------------------------|---|----------------|----------|--|
| connectors and cables | | | | |
| 1 | Connection type head A: Female connector, M12, 5-pin, straight, A-coded Connection type head B: Male connector, M12, 5-pin, straight, A-coded Signal type: Fieldbus, CANopen, DeviceNet™ Cable: 6 m, 5-wire, PUR, halogen-free Description: Fieldbus, unshielded, CANopen, DeviceNet™ | DSL-1205-G06MK | 6028327 | |
| /// | Connection type head A: Flying leads Connection type head B: Flying leads Signal type: CANopen, DeviceNet™ Items supplied: By the meter Cable: 4-wire, twisted pair Description: CANopen, shielded, DeviceNet™ Note: Wire shield Al-Pt film, overall shield C-screen tin-plated | LTG-2804-MW | 6028328 | |
| | Connection type head A: Female connector, M12, 5-pin, straight, A-coded Signal type: CANopen, DeviceNet™ Description: CANopen, shieldedDeviceNet™ Connection systems: Screw-type terminals Permitted cross-section: ≤ 0.75 mm² | DOS-1205-GA | 6027534 | |
| | Connection type head A: Male connector, M12, 5-pin, straight, A-coded Signal type: CANopen, DeviceNet™ Description: CANopen, shieldedDeviceNet™ Connection systems: Screw-type terminals Permitted cross-section: ≤ 0.75 mm² | STE-1205-GA | 6027533 | |
| integration modules and adapters | | | | |
| 93 | | AD-ATM60-KR1CO | 2029230 | |
| 93 | | AD-ATM60-KR2CO | 2029231 | |
| 93 | | AD-ATM60-KR3CO | 2029232 | |
| 103 | | AD-ATM60-SR1CO | 2031686 | |
| 93 | | AD-ATM60-SR2CO | 2020935 | |

| | Brief description | Туре | part no. | |
|------------------|--|--------------|----------|--|
| shaft adaptation | | | | |
| | Product segment: Shaft adaptation Product: Shaft couplings Description: Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub | KUP-0606-B | 5312981 | |
| | Product segment: Shaft adaptation Product: Shaft couplings Description: Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub | KUP-0610-B | 5312982 | |
| | Product segment: Shaft adaptation Product: Shaft couplings Description: Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, -10° to +80°C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin | KUP-0610-F | 5312985 | |
| Mounting systems | | | | |
| | Description: Mounting bell for encoder with servo flange, 50 mm spigot Items supplied: Mounting kit included | BEF-MG-50 | 5312987 | |
| | Description: Half-shell servo clamps (2 pcs.) for servo flanges with a 50 mm centering hub | BEF-WG-SF050 | 2029165 | |
| | Description: Servo clamps, large, for servo flange (clamps, eccentric fastener), 3 pcs, without mounting material Items supplied: Without mounting hardware | BEF-WK-SF | 2029166 | |

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