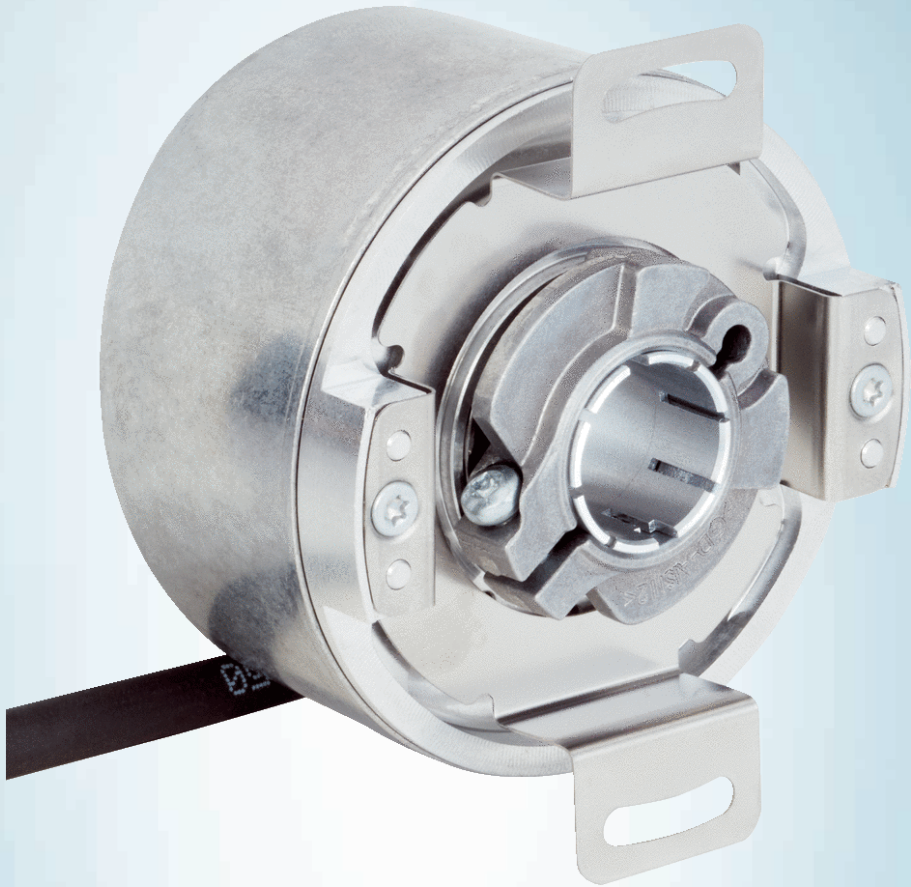
Data sheet



SFM60S-HMKB0K02

SFS/SFM60-S

SAFE MOTOR FEEDBACK SYSTEMS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

Type	part no.
SFM60S-HMKB0K02	1081516

Other models and accessories ➜ www.sick.com/SFS_SFM60-S

Detailed technical data

Features

Items supplied	M3 mounting screws for stator coupling not included with delivery.

Safety-related parameters

Safety integrity level	SIL 2 (IEC 61508), SILCL2 (EN 62061) [1]
Category	3 (EN ISO 13849)
Test rate	Not required
Maximum demand rate	Continuous (analog signals)
Performance level	PL d (EN ISO 13849) [2]
PFH (mean probability of a dangerous failure per hour)	1.7×10^{-8} [2]
T_M (mission time)	20 years (EN ISO 13849)
$MTTF_D$ (mean time to dangerous failure)	230 years (EN ISO 13849)
Safety-related accuracy	± 0.09°, For square counting
Safety-related measuring step	0.09°, For square counting

[1] For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

[2] The enclosure rating (in accordance with IEC 60529) is achieved with attached mating plug and was tested with the shaft in a horizontal position.

Performance

Sine/cosine periods per revolution	1,024
Number of the absolute ascertainable revolutions	4,096
Total number of steps	134,217,728
Measuring step	0.3 ″ For interpolation of the sine/cosine signals with e.g. 12 bit
Integral non-linearity	Typ. ± 45 ″, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling
Differential non-linearity	± 7 ″, Non-linearity within a sine/cosine period
Operating speed	≤ 6,000 min^{-1}, up to which the absolute position can be reliably produced

Available memory area	1,792 Byte
System accuracy	± 52 ″

Interfaces

Type of code for the absolute value	Binary
Code sequence	Rising, For clockwise shaft rotation, looking in direction “A” (see dimensional drawing)
Communication interface	HIPERFACE®

Electronics

Connection type	Cable, 8-wire, universal, 1.5 m
Supply voltage	7 V DC ... 12 V DC
Recommended supply voltage	8 V DC
Current consumption	< 80 mA (without load)
Output frequency for sine/cosine signals	≤ 200 kHz

Mechanics

Shaft version	Blind hollow shaft
Shaft diameter	12 mm
Shaft material	Stainless steel
Flange material	Die-cast zinc
Housing material	Aluminum die cast
Flange type / stator coupling	Stator coupling (BEF-DS07XFX)
Dimensions	See dimensional drawing
Weight	≤ 0.25 kg
Moment of inertia of the rotor	56 gcm²
Operating speed	≤ 6,000 min^{-1} [1]
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.6 Ncm (+20 °C)
Start up torque	+ 0.8 Ncm (+20 °C)
Permissible movement static	± 0.3 mm, radial ± 0.5 mm, axial
Permissible movement dynamic	± 0.05 mm, radial ± 0.1 mm, axial
Life of ball bearings	3.6 x 10^9 revolutions

[1] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

Operating temperature range	–30 °C ... +85 °C
Storage temperature range	–40 °C ... +90 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (EN 60068-2-6)
Frequency range of resistance to vibrations	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

[1] The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

EMC	According to EN 61000-6-2 and EN 61000-6-3 [1)]
Enclosure rating	IP65, with mating connector inserted (IEC 60529)
Operating height (above sea level)	2,000 m

[1)] The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

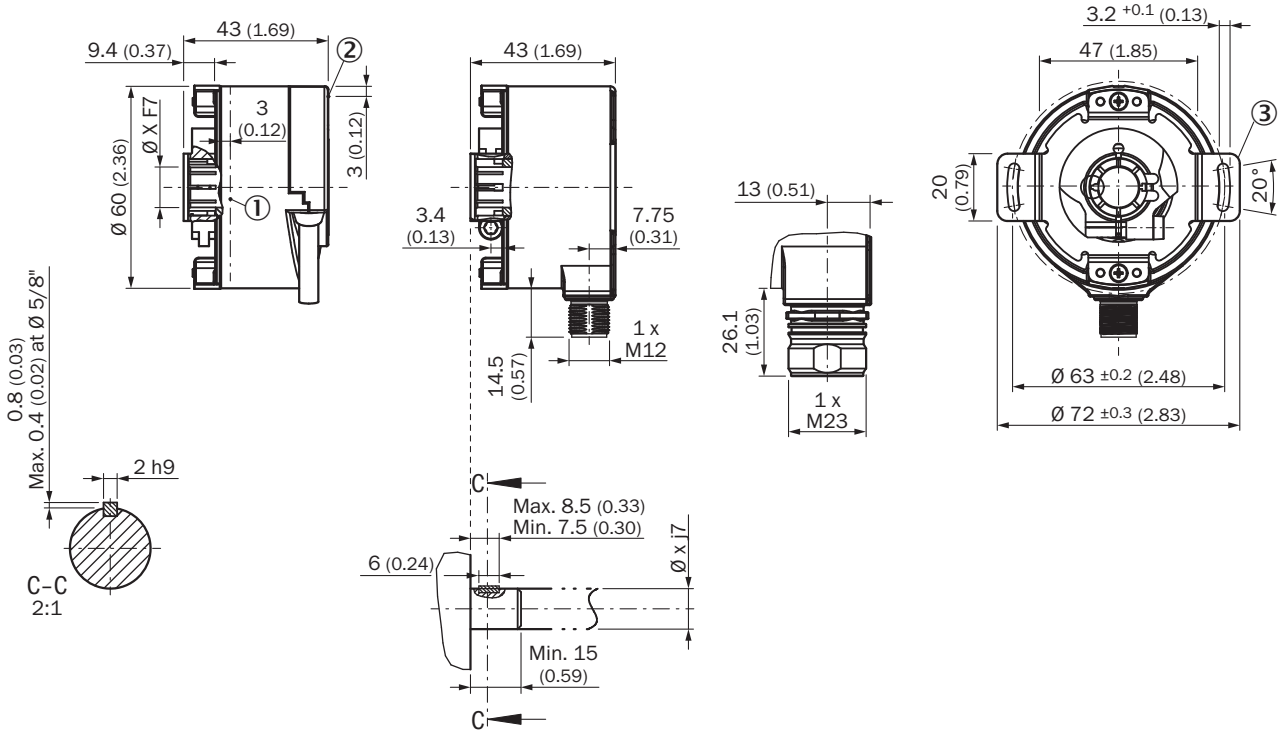
Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Certificates

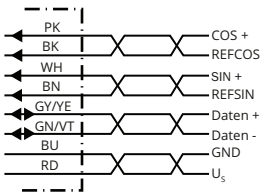
EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China RoHS	✓
UK-Type-Examination approval	✓
EC-Type-Examination approval	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Dimensional drawing Blind hollow shaft - safety system



Dimensions in mm (inch)
General tolerances according to DIN ISO 2768-mk
① Operating temperature measuring point (freely selectable, in each case circumferential at the housing surface, approx. 3 mm from the flange)
② vibration measuring point (on the housing front face in each case, approx. 3 mm away from edge of housing)
③ Dimensional drawing of the stator coupling may differ depending on the variant. Please also refer to the dimensional drawing of the stator coupling.

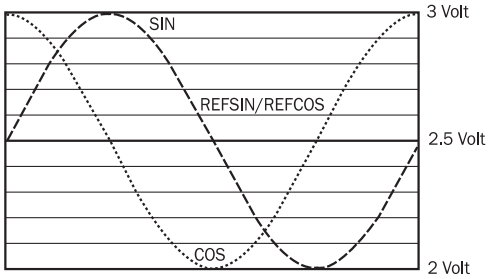
Anschlussbelegung



Wire colors (cable connection)	Signal	Explanation
Brown	REFSIN	Process data channel
White	+ SIN	Process data channel
Black	REFCOS	Process data channel
Pink	+ COS	Process data channel
Gray or yellow	Data +	Parameter channel RS 485
Green or purple	Data -	Parameter channel RS 485
Blue	GND	Ground connection
Red	U_S	Supply voltage

Wire colors (cable connection)	Signal	Explanation
Shielding	–	Shielding connected to encoder housing

Diagrams Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)
1 period = 360 ° : 1024

Operation note Overview of status messages for HIPERFACE®

	Status code	Description	SFS	SFM
Error type	00h	The encoder has not detected any faults	■	■
Initialization	01h	Incorrect alignment data	■	■
	02h	Incorrect internal angular offset	■	■
	03h	Data field partitioning table destroyed	■	■
	04h	Analog limit values not available	■	■
	05h	Internal I2C bus inoperative	■	■
	06h	Internal checksum error	■	■
Protocol	07h	Encoder reset occurred as a result of program monitoring	■	■
	09h	Parity error	■	■
	0Ah	Checksum of transmitted data is incorrect	■	■
	0Bh	Unknown command code	■	■
	0Ch	Number of transmitted data is incorrect	■	■
	0Dh	Transmitted command argument is not allowed	■	■
Data	0Eh	The selected data field may not be written to	■	■
	0Fh	Incorrect access code	■	■
	10h	Size of specified data field cannot be changed	■	■
	11h	Specified word address lies outside the data field	■	■
	12h	Access to non-existent data field	■	■
Position	01h	Analog signals outside specification	■	■
	1Fh	Speed too high, no position formation possible	■	■
	20h	Singleturn position unreliable	■	■
	21h	Multiturn position error		■
	22h	Multiturn position error		■
	23h	Multiturn position error		■
Other	1Ch	Value monitoring of the analog signals (process data)	■	■
	1Dh	Transmitter current critical (contamination, transmitter breakage)	■	■
	1Eh	Encoder temperature critical	■	■
	08h	Counter overflow	■	■
For more information on the interface see HIPERFACE® - description, part no. 8010701				

Operation note Overview of supported commands for HIPERFACE®

			SFS	SFM
Command byte	**Function**	**Code 0** [1]	**Comment**	**Comment**
42h	Read position	■		
43h	Set position			
44h	Read analog value		Channel number 48h	Channel number 48h
			Temperature [°C]	Temperature [°C]
46h	Read counter			
47h	Increase counter			
49h	Delete counter	■		
4Ah	Read data			
4Bh	Store data			
4Ch	Determine status of a data field			
4Dh	Create data field			
4Eh	Determine available memory area			
4Fh	Change access code			
50h	Read encoder status			
52h	Read out type label		Encoder type = 22h	Encoder type = 22h
53h	Encoder reset			
55h	Allocate encoder address	■		
56h	Read serial number and program version			
57h	Configure serial interface	■		

[1] The commands thus marked include the parameter 'Code 0'. Code 0 is a byte inserted into the protocol to provide additional protection of vital system parameters against accidental overwriting. When the device is supplied, 'Code 0' = 55h.

Operation note Model-specific settings

	SFS	SFM
Model ID (command 52h)	22h	27h
Free E^2PROM [bytes]	128/1.792	128/1.792
Address	40h	40h
Mode_485	E4h	E4h
Codes 0 to 3	55h	55h
Counter	0	0

Operation note Charactersitics applicable to all permissible environmental conditions

Signal	Values/unit
Signal peak, peak V_{SS} of SIN, COS	0.9 V ... 1.1 V
Signal offset REFSIN, REFCOS	2.2 V ... 2.8 V

Recommended accessories

Other models and accessories ➜ www.sick.com/SFS_SFM60-S

	Brief description	Type	part no.
programming devices			
	• **Product segment:** Programming devices • **Product family:** PGT-11-S • **Description:** SVip® LAN programming tool for all motor feedback systems • **Items supplied:** 1x programming tool PGT-11-S LAN, 1x power supply unit 100-240 V AC / 12 V DC, primary adapter (Europe, UK, USA/Japan, Australia), Ethernet cable 3 m	PGT-11-S LAN	1057324

SICK AT A GLANCE

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

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